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The first page should contain the full title in sentence case (e.g., Multiplication modules with Krull dimension)

First AUTHOR^{1*}, Second AUTHOR^{1,2}

The full names (last names fully capitalised) and affiliations (in English) of all authors

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Abstract: The abstract should provide clear information about the research and the results obtained, and should not exceed 200 words. The abstract should not contain citations.

Key words: Please provide key words or phrases to enable retrieval and indexing. Acronyms should be avoided.

1. Introduction

The classical Newtonian n -body problem consists of the study of a system formed by n punctual bodies with positives masses m_1, \dots, m_n interacting by Newton's gravitational law [3].

Symbols, units, and abbreviations: In general, the journal follows the conventions of Scientific Style and Format, The CSE Manual for Authors, Editors, and Publishers, Council of Science Editors, Reston, VA, USA (7th ed.). All abbreviations and acronyms should be defined at first mention.

2. Section

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The above integrals of motion can be used in system (2.1) to reduce at most ten degrees of freedom.

The above integrals of motion can be used in system Definition 2.2, Definition 2.2 to reduce at most ten degrees of freedom (2.2).

Definition 2.1 Assume that (A1) and (A2) are satisfied. The equilibrium E_0 of system is always a stable node for all parameters.

Definition 2.2 Assume that (A1) and (A2) are satisfied. The equilibrium E_0 of system (2.2) is always a stable node for all parameters.

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equation **Formulae should be numbered consecutively in parentheses.** (2.1)

2.1. Subsection

Now, to finish the proof it is enough to take the squares of both sides of the above relations and use the chain relation [2].

Theorem 2.3 Assume that (A1) and (A2) are satisfied. The equilibrium E_0 of system (??) is always a stable node for all parameters.

Proof The first part of the theorem follows immediately from the Table. As for the stability of E_i ($i = 1, 2$), the Jacobian matrixes evaluated at E_i ($i = 1, 2$) are ... **2.4.** \square

equation (2.2)

Lemma 2.4 Let $\mathcal{K}_{1,p}$ be a star and $\mathcal{S}_{1,q}^2$ be a bicyclic graph with exactly two cycles and $q - 4$ pendent vertices.

2.1.1. Subsubsection

To see that the above proof is actually an alternative proof of Theorem 3.4 of Table 1, Figure 1.

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Charts must be prepared in 2 dimensions unless required by the data used. Charts unnecessarily prepared in 3 dimensions are not accepted.

Table 1. default.

	Fl_{15}	$T_2(Fl_{15})$	$L(Fl_{15})$	$T_1[L(Fl_{15})]$
n	31	91	60	600
m	60	660	540	1620
$F(G)$	28080	1120080	900720	7210080
(...)	28013.501	955958.802	816347.027	4616746.829
(...)	28015.492	955287.95	817804.321	4571543.636

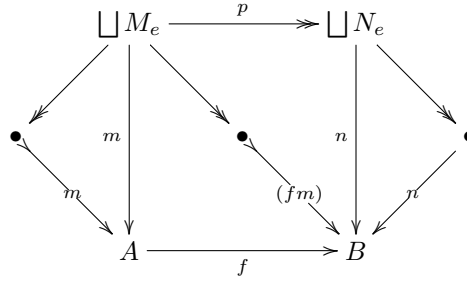


Figure 1. default.

3. Conclusion

Efficiency is quantified in terms of computation, communication, and round complexity. Then one can observe that the curves B_i in the Matsumoto relation and the curves A_{g-i} are related in the following way.

Acknowledgment

Acknowledgement and/or disclaimers, if any.

Names of funding organizations should be written in full.

References

References must be listed in alphabetical order at the end of the article and numbered in square brackets. All authors should be included in reference lists unless there are 6 or more, in which case only the first 5 should be given, followed by “et al.”. The citations should be given via “cite” command during the preparation of LaTeX file, not given in square brackets manually.. Do not use individual sets of brackets for citation numbers that appear together, e.g., [2, 6], not [2], [7].

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