

A homotopy for a complex of free Lie algebras

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Abstract

Using the Guichardet construction, we compute the cohomology groups of a complex of free Lie algebras introduced by Alekseev and Torossian.

1. Introduction

In their study of the relation between the KV-conjecture and Drinfeld's associators, Alekseev and Torossian [1] studied the Eilenberg-MacLane differential $\delta_A : L_n \to L_{n+1}$, where L_n is the free Lie algebra in *n* variables, and computed the cohomology groups of δ_A in dimensions 1, 2. Following the construction of Guichardet [2] (see also [3]), we remark that the complex δ_A is acyclic, except in dimensions 1, 2, where the cohomology is of dimension 1. We also identify the cohomology groups of a similar complex $\delta_A : T_n \to T_{n+1}$, where T_n is the free associative algebra in *n* variables: the cohomology is of dimension 1 in any degree. The Guichardet construction provides an explicit homotopy.

Alekseev and Torossian used the computations in dimension 2 to deduce the existence of a solution to the KV problem from the existence of an associator. A simple by-product of their computation is the existence and the uniqueness of the Campbell-Hausdorff formula. We do not have any other application of the computations of higher cohomologies.

In this note, we start with a review of the construction of Guichardet. Then we adapt it to free associative algebras and free Lie algebras.

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2. The Guichardet construction

Let V be a finite dimensional real vector space. Let F^n be the space of polynomial functions f on $V \oplus V \oplus \cdots \oplus V$. An element f of F^n is written as $f(v_1, v_2, \ldots, v_n)$.

Define

$$(\delta_n f)(v_1, \dots, v_{n+1}) = \sum_{i=1}^n (-1)^i f(v_1, v_2, \dots, v_{i-1}, \hat{v}_i, v_{i+1}, \dots, v_n).$$

For example:

$$(\delta_1 f)(v_1, v_2) = -f(v_2) + f(v_1)$$

$$(\delta_2 f)(v_1, v_2, v_3) = -f(v_2, v_3) + f(v_1, v_3) - f(v_1, v_2).$$

We define $F^0 = \mathbb{R}$, and embed $F^0 \to F^1$ as the constant functions.

The complex $0 \to F^0 \to F^1 \to \cdots$ is acyclic except in degree 0. Indeed, $s: F^n \to F^{n-1}$ given by

$$(sf)(v_1, v_2, \dots, v_{n-1}) = f(0, v_1, v_2, \dots, v_{n-1})$$
(1)

satisfies $\operatorname{Id} := s\delta + \delta s$.

Now the additive group V operates on F^n by translations: if $\alpha \in V$, we write

$$(\tau(\alpha)f)(v_1,\ldots,v_n)=f(v_1-\alpha,\ldots,v_n-\alpha).$$

The differential δ commutes with translations, so that it induces a differential δ_A on the subspace of translation invariant functions.

It is well known that the cohomology of the complex δ_A is isomorphic with $\Lambda^{n-1}V^*$. Here, we recall Guichardet's explicit construction of the isomorphism as we will adapt it to the "universal case" considered by Alekseev-Torossian.

Let Ω^{n-1} be the space of differential forms of exterior degree n-1 on V, with polynomial coefficients, equipped with the de Rham differential.

Consider the simplex $S := S_{v_1, v_2, \dots, v_n}$ in V with vertices (v_1, v_2, \dots, v_n) . Thus the map $\Omega^{n-1} \to F^n$ defined by $\omega \to \int_S \omega$ induces a map from Ω^{n-1} to F^n . This map commutes with the differentials (as follows from Stokes formula) and with the natural action by translations.

Conversely, associate to $f \in F^n$ a differential form $\omega(f)$ of degree (n-1) by setting for $v_1, v_2, \ldots, v_{n-1}$ vectors in V, identified with tangent vectors at $v \in V$:

$$\langle \omega(f)(v), v_1 \wedge v_2 \wedge \dots \wedge v_{n-1} \rangle = \sum_{\sigma \in \Sigma_{n-1}} \epsilon(\sigma) \frac{d}{d\epsilon} |_0 f(v, v + \epsilon_1 v_{\sigma(1)}, \dots, v + \epsilon_{n-1} v_{\sigma(n-1)}).$$

Here if ϕ is a polynomial function of $\epsilon_1, \ldots, \epsilon_{n-1}$, we employ the notation $\frac{d}{d\epsilon}|_0\phi(\epsilon)$ for the coefficient of $\epsilon_1 \cdots \epsilon_{n-1}$ in ϕ .

The map ω commutes with the differential, and with the action of V by translations. Thus the map $P_n: F^n \to F^n$ defined by

$$P_n(f) = \int_S \omega(f)$$

produces a map from $F^n \to F^n$, commuting with the action of V. This map is the identity on F^1 .

Let us give the formulae for P_n so that we see that the map P_n is "universal".

Given $v := (v_1, v_2, \dots, v_n) \in V$, consider the map $p_v : \mathbb{R}^{n-1} \to V$ given by

$$p_v(t_1, t_2, \dots, t_{n-1}) = v_1 + t_1(v_2 - v_1) + \dots + t_{n-1}(v_n - v_1)$$

This map sends the standard simplex Δ_{n-1} defined by

$$t_i \ge 0, \sum_{i=1}^{n-1} t_i \le 1$$

to the simplex S in V with vertices v_1, v_2, \ldots, v_n .

Let us consider the form

$$p_v^*\omega(f) = f(t, v)dt_1 \wedge \dots \wedge dt_{n-1}$$

The map P_n is given by

$$(P_n f)(v) = \int_{\Delta_{n-1}} f(t, v) dt$$

where f(t, v) is the element of F_n depending on t described as follows.

Lemma 2.1 Let

$$v(t) = v_1 + t_1(v_2 - v_1) + \dots + t_{n-1}(v_n - v_1).$$

Define

$$f(t, v_1, v_2, \dots, v_n) = \frac{d}{d\epsilon} |_0 \sum_{\sigma \in \Sigma[2, \dots, n]} \epsilon(\sigma) f(v(t), v(t) + \epsilon_1 (v_{\sigma(2)} - v_1), \dots, v(t) + \epsilon_{n-1} (v_{\sigma(n)} - v_1)).$$
(2)

Here $t = (t_1, t_2, \ldots, t_{n-1})$ and $\Sigma([2, \ldots, n])$ is the group of permutations of the set with (n-1) elements $[2, \ldots, n]$.

Then we have the formula

$$(P_n f)(v_1, v_2, \dots, v_n) = \int_{\Delta_{n-1}} f(t, v) dt_1 dt_2 \cdots dt_{n-1}$$

Let H := Id - P. Using the injectivity of the vector spaces F^n in the category of V-modules, as it is standard, and we will review the procedure below, to produce a homotopy

$$G: F^n \to F^{n-1}$$

commuting with the action of V by translations such that

$$H = G\delta + \delta G.$$

We first use the following injectivity lemma.

Lemma 2.2 Let A, B be two real vector spaces provided with a structure of V-modules. Let $u : A \to F^n$ be a V-module map from A to F^n . Let $v : A \to B$ be an injective map of V-modules. Then there exists a map $w : B \to F^n$ of V-modules extending u.

The formula for a map w (depending on a choice of retraction) is given below in the proof.

Proof. Denote by τ the action of V on B. Let s be a linear map from B to A such that sv = Id. Let $b \in B$: we define the map w (depending on our choice of linear retraction s) by

$$w(b)(v_1, v_2, \dots, v_n) = u(s\tau(-v_1)b)(0, v_2 - v_1, \dots, v_n - v_1).$$

We verify that b satisfy the wanted conditions. The crucial point is that the map w is a map of V-modules, as we now show. Indeed,

$$w(\tau(v_0)b)(v_1, v_2, \dots, v_n) = u(s(\tau(-v_1)\tau(v_0)b))(0, v_2 - v_1, \dots, v_n - v_1)$$

= $u(s(\tau(-v_1 + v_0)b))(0, v_2 - v_1, \dots, v_n - v_1),$
 $(\tau(v_0)w(b))(v_1, v_2, \dots, v_n) = w(b)(v_1 - v_0, v_2 - v_0, \dots, v_n - v_0)$
 $u(\tau(v_0 - v_1))byu(s(\tau(v_0 - v_1))).$

We now apply this lemma to define G inductively. Consider the injective map deduced from δ from $F^n/\delta(F^{n-1})$ to F^{n+1} .

Recall our linear map $s: F^{n+1} \to F^n$ given by equation (1). We may take as linear inverse (that we still call s) the map $s: F^{n+1} \to F^n$ followed by the projection $F^n \to F^n/\delta(F^{n-1})$.

We define $G^1 = 0$ and inductively G^{n+1} as the map extending

$$H^n - \delta G^n : F^n \to F^n$$

to F^{n+1} constructed in Lemma 2.2. Indeed, $(H^n - \delta G^n)\delta = \delta H^{n-1} - \delta(-\delta G^{n-1} + H^{n-1}) = 0$ so that the map $H^n - \delta G^n$ produces a map from $F^n/\delta(F^{n-1}) \to F^n$ and we use the fact that $F^n/\delta(F^{n-1})$ is embedded in F^{n+1} via δ with inverse s.

More precisely, given v_1 and $f \in F^{n+1}$, we define the function ϕ of n variables given by

$$\phi(w_1, w_2, \dots, w_n) = f(v_1, v_1 + w_1, \dots, v_1 + w_n)$$

and define

$$(G^{n+1}f)(v_1, v_2, \dots, v_n) = ((H^n - \delta G^n)\phi)(0, v_2 - v_1, \dots, v_n - v_1).$$

For example, this leads to the following formulae for the first elements G^i . We have $G^1 = 0, G^2 = 0$.

$$(G^{3}f)(v_{1}, v_{2}) = f(v_{1}, v_{1}, v_{2}) - \int_{0}^{1} \frac{d}{d\epsilon} |_{0}f(v_{1}, v_{1} + t(v_{2} - v_{1}), v_{1} + t(v_{2} - v_{1}) + \epsilon(v_{2} - v_{1}))dt.$$
$$(G^{4}f)(v_{1}, v_{2}, v_{3}) = G_{0}^{4} + G_{1}^{4} + G_{2}^{4}$$

with

while

$$(G_0^4 f)(v_1, v_2, v_3) = f(v_1, v_1, v_2, v_3) - f(v_1, v_2, v_2, v_3) + f(v_1, v_1, v_1, v_3) - f(v_1, v_1, v_1, v_2)$$

$$(G_1^4 f)(v_1, v_2, v_3) = \int_{t=0}^1 \frac{d}{d\epsilon} |_0 f(v_1, v_2, v_2 + t(v_3 - v_2), v_2 + (t+\epsilon)(v_3 - v_2))|$$

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$$-\int_{t=0}^{1} \frac{d}{d\epsilon} |_{0}f(v_{1}, v_{1}, v_{1} + t(v_{3} - v_{1}), v_{1} + (t + \epsilon)(v_{3} - v_{1}))$$

$$+\int_{t=0}^{1} \frac{d}{d\epsilon} |_{0}f(v_{1}, v_{1}, v_{1} + t(v_{2} - v_{1}), v_{1} + (t + \epsilon)(v_{2} - v_{1})).$$

$$(G_{2}^{4}f)(v_{1}, v_{2}, v_{3}) = -\int_{t\in S_{2}} \frac{d}{d\epsilon} |_{0}f(v_{1}, V(t), V(t + \epsilon_{1}), V(t + \epsilon_{2}))$$

$$-\int_{t\in \Delta_{2}} \frac{d}{d\epsilon} |_{0}f(v_{1}, V(t), V(t + \epsilon_{2}), V(t + \epsilon_{1})).$$

Here $t = [t_1, t_2], t + \epsilon_1 = [t_1 + \epsilon_1, t_2], t + \epsilon_2 = [t_1, t_2 + \epsilon_2], V(t) = v_1 + t_1(v_2 - v_1) + t_2(v_3 - v_1), \text{ and } \Delta_2 := \{[t_1, t_2], t_1 \ge 0, t_2 \ge 0; t_1 + t_2 \le 1\}.$

Let us now consider the action of V by translations on the complex F^n . The differential δ induces a differential $\delta_A : F_A^n \to F_A^n$ on the subspaces of invariants. We identify the space F_A^n with F^{n-1} by the map

$$R: F^{n-1} \to F^n_A$$

given by

$$(Rf)(v_1, v_2, \dots, v_n) = f(v_2 - v_1, v_3 - v_2, \dots, v_n - v_{n-1})$$

Then the differential δ_A induced by δ becomes the Eilenberg-MacLane differential

$$(\delta_A f)(v_1, v_2, \dots, v_{n-1})$$

= $f(v_2, v_3, \dots, v_{n-1}) - f(v_1 + v_2, v_3, v_4, \dots, v_{n-1}) + f(v_1, v_2 + v_3, \dots, v_{n-1}) + \dots$
+ $(-1)^{n-2} f(v_1, v_2, \dots, v_{n-2} + v_{n-1}) + (-1)^{n-1} f(v_1, v_2, \dots, v_{n-1}).$

The map $P: F^n \to F^n$ also commutes with translations.

Lemma 2.3 We have PR = RAnt where Ant is the anti-symmetrization operator of F^{n-1} on the space of $\Lambda^{n-1}V^*$ of antisymmetric functions $f(v_1, v_2, \ldots, v_{n-1})$.

Proof.

To compute P, we have to compute

$$v(t) = v_1 + t_1(v_2 - v_1) + \dots + t_{n-1}(v_{n-1} - v_1)$$

and

$$f(t, v_1, v_2, \ldots, v_{n-1})$$

$$= \frac{d}{d\epsilon} \Big|_{0} \sum_{\sigma \in \Sigma[2,...,n-1]} \epsilon(\sigma) f(v(t), v(t) + \epsilon_1(v_{\sigma(2)} - v_1), \dots, v(t) + \epsilon_{n-2}(v_{\sigma(n-1)} - v_1)).$$

Now, if f is invariant by translation, we see that

$$f(t, v_1, v_2, \dots, v_{n-1}) = \frac{d}{d\epsilon} |_0 \sum_{\sigma \in \Sigma[2, \dots, n-1]} \epsilon(\sigma) f(0, \epsilon_1(v_{\sigma(2)} - v_1), \dots, \epsilon_{n-2}(v_{\sigma(n-1)} - v_1)).$$

We obtain the lemma.

The homotopy G commutes with translations and gives an operator G_A on the complex of invariants. It follows that we obtain on the complex δ_A the relation

$$G_A \delta_A + \delta_A G_A = \mathrm{Id} - \mathrm{Ant}$$

We thus obtain that the cohomology of the operator δ_A is isomorphic in degree n to $\Lambda^{n-1}V^*$.

3. Free variables

Let T_n be the free associative algebra in n variables. We consider $L_n \subset T_n$ as the free Lie algebra in n variables. An element f of T_n is written as $f(x_1, x_2, \ldots, x_n)$.

Define

$$(\delta_n f)(x_1, \dots, x_{n+1}) = \sum_{i=1}^n (-1)^i f(x_1, x_2, \dots, x_{i-1}, \hat{x}_i, x_{i+1}, \dots, x_n).$$

Consider $T_n(y)$ the free associative algebra generated by $(x_1, x_2, \ldots, x_n, y)$. An operator h on T_n is extended by an operator still denoted by h on $T_n(y)$ where we do not operate on y.

We may consider the application $\tau: T_n \to T_n(y)$ defined by

$$(\tau_n f)(x_1, \dots, x_n) = f(x_1 + y, x_2 + y, \dots, x_i + y, \dots, x_n + y).$$

The application τ commutes with δ . Thus the kernel of τ is a subcomplex of T_n . We may identify it with T_{n-1} by $(Rf)(x_1, x_2, \ldots, x_n) = f(x_2 - x_1, x_3 - x_2, \ldots, x_n - x_{n-1})$ and we obtain on T_n the complex δ_A considered by Alekseev-Torossian. Here,

$$(\delta_A f)(x_1, x_2, \dots, x_{n-1})$$

= $f(x_2, x_3, \dots, x_{n-1}) - f(x_1 + x_2, x_3, x_4, \dots, x_{n-1}) + f(x_1, x_2 + x_3, \dots, x_{n-1}) + \dots$
+ $(-1)^{n-2} f(x_1, x_2, \dots, x_{n-2} + x_{n-1}) + (-1)^{n-1} f(x_1, x_2, \dots, x_{n-1}).$

It is clear that the complex $\delta: 0 \to T_0 \to T_1 \to T_2 \cdots$ is acyclic. Indeed we can define

$$(sf)(x_1, x_2, \dots, x_n) = f(0, x_1, x_2, \dots, x_n)$$

and it is immediate to verify that

 $s\delta + \delta s = \text{Id.}$

If $f \in T_n$, we define a function $f(t, x) \in \mathbb{R}[t] \otimes T_k$ by the same formula as Formula (2):

Definition 3.1 Let

$$x(t) = x_1 + t_1(x_2 - x_1) + \dots + t_{n-1}(x_n - x_1).$$

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Define

$$f(t, x_1, x_2, \dots, x_n) = \frac{d}{d\epsilon} |_0 \sum_{\sigma \in \Sigma([2, \dots, n])} \epsilon(\sigma) f(x(t), x(t) + \epsilon_1(x_{\sigma(2)} - x_1), \dots, x(t) + \epsilon_{n-1}(x_{\sigma(n)} - x_1)).$$

Define

$$(P_n f)(x_1, x_2, \dots, x_n) = \int_{\Delta_{n-1}} f(t, x_1, x_2, \dots, x_n) dt_1 dt_2 \cdots dt_{n-1}$$

The following lemma is immediate.

Lemma 3.2 We have $\delta P_n = P_n \delta$.

We define $G^1 = 0$ and inductively G^{n+1} by the same formula as before. More precisely, given $f \in T^{n+1}$, we define the function ϕ of $T^n(x_1)$ given by

$$\phi(w_1, w_2, \dots, w_n) = f(x_1, x_1 + w_1, \dots, x_1 + w_n)$$

and define

$$(G^{n+1}f)(x_1, x_2, \dots, x_n) = ((H^n - \delta G^n)\phi)(0, x_2 - x_1, \dots, x_n - x_1).$$

Then we conclude as before that $G\delta + \delta G = \mathrm{Id} - P$. Restricting to the invariants, we obtain a map G_A such that $\mathrm{Id} - \mathrm{Ant} = G_A \delta_A + G_A \delta_A$. Here Ant is the anti-symmetrization operator $\sum_{\sigma} \epsilon(\sigma) x_{\sigma(1)} \cdots x_{\sigma(n)}$.

The subspace L_n of T_n is stable under the differential. The operator Ant is equal to 0 on L_n , except in degree 1, 2, as there are no totally antisymmetric elements in L_n for $n \ge 3$. Thus we obtain

Theorem 3.3 • The cohomology groups $H^n(T_n, \delta_A)$ of the complex $\delta_A : T_n \to T_n$ are of dimension 1 and are generated by $\sum_{\sigma} \epsilon(\sigma) x_{\sigma(1)} \cdots x_{\sigma(n)}$.

• The cohomology groups $H^n(L_n, \delta_A)$ of the complex $\delta_A : L_n \to L_n$ are of dimension 0 if n > 2. For n = 1, 2,

$$H^{1}(L_{1}, \delta_{A}) = \mathbb{R}x_{1}, \qquad \qquad H^{2}(L_{2}, \delta_{A}) = \mathbb{R}[x_{1}, x_{2}].$$

Remark: The Guichardet construction also provides an explicit homotopy.

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