

## Sasakian Finsler manifolds

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**Abstract:** In this study, almost contact Finsler structures on vector bundle are defined and the condition of normality in terms of the Nijenhuis torsion  $N_\phi$  of almost contact Finsler structure is obtained. It is shown that for a  $K$ -contact structure on Finsler manifold  $\nabla_X \xi = -\frac{1}{2}\phi X$  and the flag curvature for plane sections containing  $\xi$  are equal to  $\frac{1}{4}$ . By using the Sasakian Finsler structure, the curvatures of a Finsler connection  $\nabla$  on  $V$  are obtained. We prove that a locally symmetric Finsler manifold with  $K$ -contact Finsler structure has a constant curvature  $\frac{1}{4}$ . Also, the Ricci curvature on Finsler manifold with  $K$ -contact Finsler structure is given. As a result, Sasakian structures in Riemann geometry and Finsler condition are generalized.

As a conclusion we can state that Riemannian Sasakian structures are compared to Sasakian Finsler structures and it is proven that they are adaptable.

**Key words:** Finsler connection, vector bundle, almost contact manifold, Sasakian manifold, nonlinear connection, Ricci tensor

### 1. Introduction

Let  $V(M) = \{V, \pi, M\}$  be a vector bundle of total space  $V$  with a  $(n+m)$ -dimensional  $C^\infty$  manifold and with a base space  $M$  that is an  $n$ -dimensional  $C^\infty$ -manifold. The projection map  $\pi : V \rightarrow M, u \in V \mapsto \pi(u) = x \in M$ , where  $u = (x, y)$ , and  $y \in R^m = \pi^{-1}(x)$  the fibre of  $V(M)$  over  $x$ .

A non-linear connection  $N$  on the total space  $V$  of  $V(M)$  is a differentiable distribution  $N : V \rightarrow T_u(V), u \in V \mapsto N_u \in T_u(V)$  such that

$$T_u(V) = N_u \oplus V_u^v \text{ where } V_u^v = \{X \in T_u(V) : \pi_*(X) = 0\}. \quad (1.1)$$

$N_u$  the *horizontal distribution* and  $V^v$  is the *vertical distribution*. Thus for all  $X \in T_u(V)$  can be separated by its components

$$X = X^H + X^V \text{ where } X^H \in N_u, X^V \in V_u^v. \quad (1.2)$$

Let  $x^i, i=1,2,\dots,n$  and  $y^a, a=1,2,\dots,m$  be the coordinates of  $x$  and  $y$  such that  $(x^i, y^a)$  are the coordinates of  $u \in V$ . The local base of  $N_u$  is

$$\frac{\delta}{\delta x^i} = \frac{\partial}{\partial x^i} - N_i^a(x, y) \frac{\partial}{\partial y^a} \quad (1.3)$$

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and that of  $V_u^v$  is where  $N_i^a(x, y)$  are the coefficients of  $N$ . Their dual bases are  $(dx^i, \delta y^a)$  where

$$\delta y^a = dy^a + N_i^a(x, y) dx^i. \tag{1.4}$$

Let  $X = X^i(x, y) \frac{\delta}{\delta x^i} + \tilde{X}^a(x, y) \frac{\partial}{\partial y^a}, \forall X \in T_u(V)$ . Then

$$X^H = X^i(x, y) \frac{\delta}{\delta x^i}, X^V = \tilde{X}^a(x, y) \frac{\partial}{\partial y^a}, \tilde{X}^a = X^a + N_i^a X^i. \tag{1.5}$$

Let  $\omega$  be a 1-form  $\omega = \tilde{\omega}_i(x, y) dx^i + \omega_a(x, y) \delta y^a$ . Then

$$\omega^H = \tilde{\omega}_i dx^i, \tilde{\omega}_i = \omega_i - N_i^a(x, y) \omega_a; \omega^V = \omega_a \delta y^a \tag{1.6}$$

which gives

$$\omega^H(X^V) = 0, \omega^V(X^H) = 0 \text{ where } \omega = \omega^H + \omega^V. \tag{1.7}$$

The Finsler tensor field of type  $\begin{pmatrix} p & r \\ q & s \end{pmatrix}$  on  $V$  has the following local form [4]:

$$T = T_{j_1, \dots, j_q, b_1, \dots, b_s}^{i_1, \dots, i_p, a_1, \dots, a_r}(x, y) \frac{\delta}{\delta x^{i_1}} \otimes \dots \otimes \frac{\delta}{\delta x^{i_p}} \otimes dx^{a_1} \otimes \dots \otimes dx^{a_r} \otimes \frac{\partial}{\partial y^{j_1}} \otimes \dots \otimes \frac{\partial}{\partial y^{j_q}} \otimes \delta y^{b_1} \otimes \dots \otimes \delta y^{b_s}. \tag{1.8}$$

**Definition 1.1** A Finsler connection on  $V$  is a linear connection  $\nabla = F\Gamma$  on  $V$  with the property that the horizontal linear space  $N_u, u \in V$  of the distribution  $N$  is parallel with respect to  $\nabla$  and the vertical spaces  $V_u^v, u \in V$  are also parallel relative to  $\nabla$  [3].

A linear connection  $\nabla$  on  $V$  is a Finsler connection on  $V$  if and only if

$$(\nabla_X Y^H)^V = 0, (\nabla_X Y^V)^H = 0, \forall X, Y \in T_u(V). \tag{1.9}$$

A linear connection  $\nabla$  on  $V$  is a Finsler connection on  $V$  if and only if [4]

$$\nabla_X Y = (\nabla_X Y^H)^H + (\nabla_X Y^V)^V, \forall X, Y \in T_u(V), \tag{1.10a}$$

$$\nabla_X \omega = (\nabla_X \omega^H)^H + (\nabla_X \omega^V)^V, \forall \omega \in T_u^*(V) \text{ and } X \in T_u(V). \tag{1.10b}$$

**Remark 1.1** Let  $\nabla$  on  $V$  is a Finsler connection on  $V$ . We get immediately that [6]

$$Y \in V_u^v \Rightarrow \forall X \in T_u(V); \nabla_X Y \in V_u^v, Y \in N_u \Rightarrow \forall X \in T_u(V); \nabla_X Y \in N_u. \tag{1.11}$$

For a Finsler connection  $\nabla$  on  $V$ , there is an associated pair of operators;  $h$ - and  $v$ -covariant derivation in the algebra of Finsler tensor fields. For each  $X \in T_u(V)$ , set

$$\nabla_X^H Y = \nabla_{X^H} Y, \nabla_X^H f = X^H(f), \forall Y \in T_u(V), \forall f \in F(V). \tag{1.12}$$

If  $\omega \in T_u^*(V)$ , we define

$$(\nabla_X^H \omega)(Y) = X^H(\omega(Y)) - \omega(\nabla_X^H Y), \forall Y \in T_u(V). \tag{1.13}$$

So, we may extend the action of the operator  $\nabla_X^H$  to any Finsler tensor field by asking these questions: does  $\nabla_X^H$  preserve the type of Finsler tensor fields, is it  $\mathbb{R}$ -linear, does it satisfy the Leibniz rule with respect to tensor product and does it commute with all contractions? We keep the notation  $\nabla_X^H$  for this operator on the algebra of Finsler tensor fields. We call it the *operator of h-covariant derivation*.

In a similar way, for every vector field  $X \in T_u(V)$  set

$$\nabla_X^V Y = \nabla_{X^V} Y, \nabla_X^V f = X^V(f), \forall Y \in T_u(V), \forall f \in F(V). \tag{1.14}$$

If  $\omega \in T_u^*(V)$ , we define

$$(\nabla_X^V \omega)(Y) = X^V(\omega(Y)) - \omega(\nabla_X^V Y), \forall Y \in T_u(V). \tag{1.15}$$

We extend the action of  $\nabla_X^V$  to any Finsler tensor field in a similar way, as for  $\nabla_X^H$ . We obtain an operator on the algebra of Finsler tensor fields on  $V$ ; this will be denoted also by  $\nabla_X^V$  and will be called the *operator of v-covariant derivation* [1].

**Definition 1.2** Let  $\omega \in T_u^*(V)$  be a differential  $q$ -form on  $V$ ,  $\nabla$  is a linear connection on  $V$  and  $T$  is the torsion tensor of  $\nabla$ . Then its exterior differential  $d\omega$  is also defined as [4]:

$$\begin{aligned} (d\omega)(X_1, \dots, X_{q+1}) &= \sum_{i=1}^{q+1} (-1)^{i+1} (\nabla_{X_i} \omega)(X_1, \dots, \tilde{X}_i, \dots, X_{q+1}), \forall X_i \in T_u(V) \\ &- \sum_{1 \leq i < j \leq q+1} (-1)^{i+j} \omega(T(X_i, X_j), X_1, \dots, \tilde{X}_i, \dots, \tilde{X}_j, \dots, X_{q+1}). \end{aligned} \tag{1.16}$$

**Proposition 1.1** If  $\omega \in T_u^*(V)$  is a 1-form and  $\nabla$  is a Finsler connection on  $V$ , then its exterior differential is given by [3]

$$\begin{aligned} (d\omega)(X^H, Y^H) &= (\nabla_{X^H}^H \omega)(Y^H) - (\nabla_{Y^H}^H \omega)(X^H) + \omega(T(X^H, Y^H)), \\ (d\omega)(X^V, Y^H) &= (\nabla_{X^V}^V \omega)(Y^H) - (\nabla_{Y^H}^H \omega)(X^V) + \omega(T(X^V, Y^H)), \\ (d\omega)(X^V, Y^V) &= (\nabla_{X^V}^V \omega)(Y^V) - (\nabla_{Y^V}^V \omega)(X^V) + \omega(T(X^V, Y^V)), \forall X, Y \in T_u(V). \end{aligned} \tag{1.17}$$

In the canonical coordinates  $(x^i, y^a)$ , there exists a well determined set of differentiable functions on  $V$ .  $F_{jk}^i(x, y), F_{bk}^a(x, y); C_{ja}^i(x, y); C_{bc}^a(x, y)$  such that

$$\begin{aligned} \nabla_{\frac{\delta}{\delta x^j}}^H \frac{\delta}{\delta x^i} &= F_{jk}^i(x, y) \frac{\delta}{\delta x^i}, \nabla_{\frac{\delta}{\delta x^k}}^H \frac{\partial}{\partial y^b} = F_{bk}^a(x, y) \frac{\partial}{\partial y^a}, \\ \nabla_{\frac{\partial}{\partial y^a}}^V \frac{\delta}{\delta x^j} &= C_{ja}^i(x, y) \frac{\delta}{\delta x^i}, \nabla_{\frac{\partial}{\partial y^c}}^V \frac{\partial}{\partial y^b} = C_{bc}^a(x, y) \frac{\partial}{\partial y^a} \end{aligned}$$

where  $F_{jk}^i(x, y), F_{bk}^a(x, y)$  are called coefficients of  $h$ -connections  $\nabla^H$  and  $C_{bc}^a(x, y), C_{ja}^i(x, y)$  are called coefficients of  $v$ -connections  $\nabla^V$ .

The torsion tensor field  $T$  of a Finsler-connection is characterised by five Finsler tensor fields:

$$[T(X^H, Y^H)]^H, [T(X^H, Y^H)]^V, [T(X^H, Y^V)]^H, [T(X^H, Y^V)]^V, [T(X^V, Y^V)]^V.$$

**Proposition 1.2** If the Finsler connection on  $V$  is without torsion then we have [3]

$$T(X^H, Y^H) = 0, T(X^H, Y^V) = 0, T(X^V, Y^V) = 0, \forall X, Y \in T_u(V).$$

**2. Almost contact Finsler structure on vector bundle**

Let  $\phi$  be an almost contact structure on  $V$  given by the tensor field of type  $\begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$  with the properties

1.  $\phi.\phi = -I_n + \eta^H \otimes \xi^H + \eta^V \otimes \xi^V$
2.  $\phi \xi^H = 0, \phi \xi^V = 0$
3.  $\eta^H (\xi^H) + \eta^V (\xi^V) = 1$
4.  $\eta^H (\phi X^H) = 0, \eta^V (\phi X^H) = 0, \eta^H (\phi X^V) = 0, \eta^V (\phi X^V) = 0,$

where  $\eta$  is 1-form and  $\xi$  is vector field [2].

**Proposition 2.1** *If  $\phi$  is an almost contact Finsler structure on  $V$ , there exists a unique decomposition of  $\phi$  in the Finsler tensor fields,*

$$\phi = \phi^1 + \phi^2 + \phi^3 + \phi^4 = \begin{pmatrix} \phi^1 & \phi^2 \\ \phi^3 & \phi^4 \end{pmatrix} \tag{2.2}$$

where

$$\begin{aligned} \phi^1 (\omega, X) &= \phi (\omega^H, X^H), \phi^2 (\omega, X) = \phi (\omega^H, X^V), \\ \phi^3 (\omega, X) &= \phi (\omega^V, X^H), \phi^4 (\omega, X) = \phi (\omega^V, X^V) \forall X \in T_u (V), \forall \omega \in T_u^* (V). \end{aligned} \tag{2.3}$$

We can write

$$\phi (X^H) = \phi^1 (X^H) = \phi^3 (X^H), \phi (X^V) = \phi^2 (X^V) = \phi^4 (X^V). \tag{2.4}$$

Let  $G$  be the Finsler metric structure on  $V$  which is symmetric, positive definite and non-degenerate on  $V$ . The metric-structure  $G$  on  $V$  is decomposed as:

$$G = G^H + G^V \tag{2.5}$$

where  $G^H$  is of type  $\begin{pmatrix} 0 & 0 \\ 2 & 0 \end{pmatrix}$ , symmetric, positive definite and non-degenerate on  $N_u$  and  $G^V$  is of type

$\begin{pmatrix} 0 & 0 \\ 0 & 2 \end{pmatrix}$ , symmetric, positive definite and non-degenerate on  $V_u^v$  i.e. for  $X, Y \in T_u (V)$

$$G (X, Y) = G^H (X, Y) + G^V (X, Y) \tag{2.6}$$

where  $G^H (X, Y) = G (X^H, Y^H), G^V (X, Y) = G (X^V, Y^V) ..$

Now, if the Finsler metric structure  $G$  on  $V$  satisfies

$$\begin{aligned} G (\phi X, \phi Y) &= G (X, Y) - \eta (X) \eta (Y), \\ G^H (\phi X, \phi Y) &= G^H (X, Y) - \eta^H (X^H) \eta^H (Y^H), \\ G^V (\phi X, \phi Y) &= G^V (X, Y) - \eta^V (X^V) \eta^V (Y^V), \end{aligned} \tag{2.7}$$

which is equivalent to

$$\begin{aligned} G^H (X, \xi) &= \eta^H (X), G^V (X, \xi) = \eta^V (X), \\ G^H (\phi X, \phi Y) &= -G^H (\phi^2 X, Y), G^V (\phi X, \phi Y) = -G^V (\phi^2 X, Y), \end{aligned} \tag{2.8}$$

then  $(\phi, \eta, \xi, G)$  is called almost contact metrical Finsler structure on  $V$  [5]. Now, we define

$$\Omega(X, Y) = G(X, \phi Y), \Omega(X^H, Y^H) = G^H(X, \phi Y), \Omega(X^V, Y^V) = G^V(X, \phi Y) \tag{2.9}$$

and call it the fundamental 2-form.

**Proposition 2.2** *The fundamental 2-form, defined above, satisfies [5]*

$$\begin{aligned} \Omega(\phi X^H, \phi Y^H) &= \Omega(X^H, Y^H), \Omega(\phi X^V, \phi Y^V) = \Omega(X^V, Y^V), \\ \Omega(X^H, Y^H) &= -\Omega(Y^H, X^H), \Omega(X^V, Y^V) = -\Omega(Y^V, X^V) \forall X, Y \in T_u(V). \end{aligned} \tag{2.10}$$

**Proposition 2.3** *Let  $\nabla$  be a Finsler connection on  $V$  and  $\Omega$  be the fundamental 2-form which satisfies  $\Omega(X, Y) = d\eta(X, Y)$  i.e.*

$$\begin{aligned} \Omega(X^H, Y^H) &= (\nabla_X^H \eta)(Y^H) - (\nabla_Y^H \eta)(X^H) + \eta(T(X^H, Y^H)), \\ \Omega(X^V, Y^H) &= (\nabla_X^V \eta)(Y^H) - (\nabla_Y^H \eta)(X^V) + \eta(T(X^V, Y^H)), \\ \Omega(X^V, Y^V) &= (\nabla_X^V \eta)(Y^V) - (\nabla_Y^V \eta)(X^V) + \eta(T(X^V, Y^V)). \end{aligned} \tag{2.11}$$

Then, the almost contact metrical Finsler structure is called almost Sasakian Finsler structure and the Finsler connection  $\nabla$  satisfying (2.11) is called almost Sasakian Finsler connection on  $V$  [5].

**Theorem 2.1** *Let  $\Omega$  be the fundamental 2-form and almost Sasakian Finsler connection  $\nabla$  on  $V$  is torsion free. Then [5]*

$$\begin{aligned} \Omega(X^H, Y^H) &= (\nabla_X^H \eta)(Y^H) - (\nabla_Y^H \eta)(X^H), \\ \Omega(X^V, Y^H) &= (\nabla_X^V \eta)(Y^H) - (\nabla_Y^H \eta)(X^V), \\ \Omega(X^V, Y^V) &= (\nabla_X^V \eta)(Y^V) - (\nabla_Y^V \eta)(X^V), \forall X, Y \in T_u(V). \end{aligned} \tag{2.12}$$

**Proof** From Proposition 1.2 and equations in (2.11), we have (2.12). □

**Definition 2.1** *An almost Sasakian Finsler structure on  $V$  is said to be a Sasakian Finsler structure if the 1-form  $\eta$  is a killing vector field, i.e.*

$$\begin{aligned} (\nabla_X^H \eta)(Y^H) + (\nabla_Y^H \eta)(X^H) &= 0, (\nabla_X^V \eta)(Y^H) + (\nabla_Y^H \eta)(X^V) = 0, \\ (\nabla_X^V \eta)(Y^V) + (\nabla_Y^V \eta)(X^V) &= 0 \forall X, Y \in T_u(V). \end{aligned} \tag{2.13}$$

The Finsler connection  $\nabla$  on  $V$  is torsion free, which is called Sasakian Finsler connection [5].

**Theorem 2.2** *Let  $\nabla$  be the torsion free Finsler connection together with a Sasakian Finsler structure on  $V$  and  $\Omega$  is to be the fundamental 2-form; then*

$$\begin{aligned} \Omega(X^H, Y^H) &= 2(\nabla_X^H \eta)(Y^H) = -2(\nabla_Y^H \eta)(X^H), \\ \Omega(X^H, Y^V) &= 2(\nabla_X^H \eta)(Y^V) = -2(\nabla_Y^V \eta)(X^H), \\ \Omega(X^V, Y^V) &= 2(\nabla_X^V \eta)(Y^V) = -2(\nabla_Y^V \eta)(X^V), \forall X, Y \in T_u(V). \end{aligned} \tag{2.14}$$

**Proof** From (2.12) and (2.13) we have (2.14) [5]. □

**Example 2.1** Let  $V(M) = \{V, \pi, M\}$  be a vector bundle with the total space  $V = R^{10}$  is a 10-dimensional  $C^\infty$ -manifold and the base space  $M = R^5$  is a 5-dimensional  $C^\infty$ -manifold. Let  $x^i, 1 \leq i \leq 5$  and  $y^a, 1 \leq a \leq 5$  be the coordinates of  $u = (x, y) \in V$ , that is  $u = (x^1, x^2, x^3, x^4, x^5, y^1, y^2, y^3, y^4, y^5) \in V$ . The local base of  $N_u$  is  $(\frac{\delta}{\delta x^1}, \frac{\delta}{\delta x^2}, \frac{\delta}{\delta x^3}, \frac{\delta}{\delta x^4}, \frac{\delta}{\delta x^5})$  and the local base of  $V_u^v$  is  $(\frac{\partial}{\partial y^1}, \frac{\partial}{\partial y^2}, \frac{\partial}{\partial y^3}, \frac{\partial}{\partial y^4}, \frac{\partial}{\partial y^5})$  such that  $T_u(V) = N_u \oplus V_u^v$ . Then

$$\begin{aligned} X^H &= X^1 \frac{\delta}{\delta x^1} + X^2 \frac{\delta}{\delta x^2} + X^3 \frac{\delta}{\delta x^3} + X^4 \frac{\delta}{\delta x^4} + X^5 \frac{\delta}{\delta x^5}, \\ X^V &= \tilde{X}^1 \frac{\partial}{\partial y^1} + \tilde{X}^2 \frac{\partial}{\partial y^2} + \tilde{X}^3 \frac{\partial}{\partial y^3} + \tilde{X}^4 \frac{\partial}{\partial y^4} + \tilde{X}^5 \frac{\partial}{\partial y^5} \ni X^H \in N_u, X^V \in V_u^v. \end{aligned}$$

Let  $\eta$  be a 1-form,  $\eta = \eta_i dx^i + \tilde{\eta}_a \delta y^a$  then  $\eta^H = \eta_1 dx^1 + \eta_2 dx^2 + \eta_3 dx^3 + \eta_4 dx^4 + \eta_5 dx^5$  and  $\eta^V = \tilde{\eta}_1 \delta y^1 + \tilde{\eta}_2 \delta y^2 + \tilde{\eta}_3 \delta y^3 + \tilde{\eta}_4 \delta y^4 + \tilde{\eta}_5 \delta y^5$  where  $\eta = \eta^H + \eta^V$  and  $\eta^H(X^V) = 0, \eta^V(X^H) = 0$ .

We put  $\eta^H = \frac{1}{3}(dx^5 - x^3 dx^1 - x^4 dx^2)$  and  $\eta^V = \frac{1}{3}(\delta y^5 - y^3 \delta y^1 - y^4 \delta y^2)$ .

The structure vector field  $\xi$  is given by  $\xi = 3(\frac{\delta}{\delta x^5} + \frac{\partial}{\partial y^5})$  and  $\xi$  is decomposed as  $\xi^H = 3\frac{\delta}{\delta x^5}$  and  $\xi^V = 3\frac{\partial}{\partial y^5}$ .

The tensor field  $\phi^H$  of type (1, 1) and  $\phi^V$  of type (1, 1) by a matrix form is given by

$$\phi^H = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 \\ -1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & -1 & 0 & 0 \\ -x^4 & x^3 & 0 & 0 & 0 \end{bmatrix}, \phi^V = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 \\ -1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & -1 & 0 & 0 \\ -y^4 & y^3 & 0 & 0 & 0 \end{bmatrix}.$$

We can see that  $\eta^H(\xi^H) = 1, \phi^H(\xi^H) = 0, \eta^V(\xi^V) = 1, \phi^V(\xi^V) = 0, \eta^H(\xi^V) = 0, \eta^V(\xi^H) = 0, (\phi^H)^2 X^H = -X^H + \eta^H(X^H)\xi^H, (\phi^V)^2 X^V = -X^V + \eta^V(X^V)\xi^V$  and hence  $(\phi, \xi, \eta)$  is almost contact Finsler structure on  $R^{10}$ .

### 3. Integrability tensor field of the almost contact Finsler structure

The integrability tensor field of the almost contact Finsler structure on  $V$  is given by [4]  $\tilde{N}(X, Y) = [\phi X, \phi Y] - \phi[\phi X, Y] - \phi[X, \phi Y] + \phi^2[X, Y] + d\eta^H(X, Y)\xi^H + d\eta^V(X, Y)\xi^V, \forall X, Y \in T_u(V)$ .

We define four tensors  $N^{(1)}, N^{(2)}, N^{(3)}$  and  $N^{(4)}$ , respectively by  $\forall X^H, Y^H, \xi^H \in N_u$  and  $\forall X^V, Y^V, \xi^V \in V_u^v$

$$N^{(1)}(X^H, Y^H) = N_\phi(X^H, Y^H) + d\eta^H(X^H, Y^H)\xi^H, \tag{3.1a}$$

$$N^{(2)}(X^H, Y^H) = (L_{\phi X}^H \eta^H)(Y^H) - (L_{\phi Y}^H \eta^H)(X^H), \tag{3.1b}$$

$$N^{(3)}(X^H) = (L_\xi^H \phi)(X^H), N^{(4)}(X^H) = (L_\xi^H \eta^H)(X^H), \tag{3.2a}$$

$$N^{(1)}(X^V, Y^V) = N_\phi(X^V, Y^V) + d\eta^V(X^V, Y^V)\xi^V, \tag{3.2b}$$

$$N^{(2)}(X^V, Y^V) = (L_{\phi X}^V \eta^V)(Y^V) - (L_{\phi Y}^V \eta^V)(X^V), \tag{3.2c}$$

$$N^{(3)}(X^V) = (L_\xi^V \phi)(X^V), \quad N^{(4)}(X^V) = (L_\xi^V \eta^V)(X^V), \tag{3.3a}$$

$$N^{(1)}(X^V, Y^H) = N_\phi(X^V, Y^H) + d\eta^V(X^V, Y^H)\xi^V + d\eta^H(X^V, Y^H)\xi^H, \tag{3.3b}$$

$$N^{(2)}(X^V, Y^H) = (L_{\phi X}^V \eta^H)(Y^H) + (L_{\phi X}^V \eta^V)(Y^H) - (L_{\phi Y}^H \eta^H)(X^V) - (L_{\phi Y}^H \eta^V)(X^V), \tag{3.3c}$$

$$N^{(3)}(X^V) = (L_\xi^H \phi)(X^V), \quad N^{(4)}(X^V) = (L_\xi^H \eta^V)(X^V), \tag{3.3d}$$

$$N^{(3)}(Y^H) = (L_\xi^V \phi)(Y^H), \quad N^{(4)}(Y^H) = (L_\xi^V \eta^H)(Y^H). \tag{3.3e}$$

It is clear that the almost contact Finsler structure  $(\phi, \xi, \eta)$  is normal if and only if these four tensors vanish.

**Lemma 3.1** *If  $N^{(1)} = 0$ , then  $N^{(2)} = N^{(3)} = N^{(4)} = 0$ .*

**Proof** If  $N^{(1)} = 0$ , then for  $X^H, Y^H, \xi^H \in N_u$ , from (3.1.a) we have

$$[\xi^H, X^H] + \phi[\xi^H, \phi X^H] - \xi^H(\eta^H(X^H))\xi^H = 0. \tag{3.4}$$

Applying  $\eta^H$  to (3.4), we see that

$$N^{(4)}(X^H) = (L_\xi^H \eta^H)(X^H) = \xi^H(\eta^H(X^H)) - \eta^H([\xi^H, X^H]) = 0.$$

From this equation, we also have

$$\eta^H[\xi^H, \phi X^H] = 0. \tag{3.5}$$

On the other hand, applying  $\phi$  to (3.4), we get

$$N^{(3)}(X^H) = (L_\xi^H \phi)X^H = \phi[X^H, \xi^H] - [\phi X^H, \xi^H] = 0. \tag{3.6}$$

Finally, from  $N^{(1)} = 0$ , by using (3.6), we derive

$$\begin{aligned} 0 = & -[\phi X^H, Y^H] - [X^H, \phi Y^H] + \phi[X^H, Y^H] - \phi[\phi X^H, \phi Y^H] \\ & - \phi Y^H(\eta^H(X^H)\xi^H) + \phi(Y^H(\eta^H(X^H))\xi^H) + \phi X^H(\eta^H(Y^H))\xi^H. \end{aligned} \tag{3.7}$$

Applying  $\eta^H$  to (3.7), we get  $N^{(2)}(X^H, Y^H) = 0$ . Similarly,  $\forall X^V, Y^V, \xi^V \in V_u^v$ , if  $N^{(1)}(X^V, Y^V) = 0$ , then  $N^{(2)}(X^V, Y^V) = 0, N^{(3)}(X^V) = 0, N^{(4)}(X^V) = 0$ .

If  $N^{(1)}(X^V, Y^H) = 0$ , from (3.3.a) we obtain

$$N^{(1)}(X^V, \xi^H) = [\xi^H, X^V] - \phi[\phi X^V, \xi^H] - \xi^H(\eta^V(X^V))\xi^V = 0. \tag{3.8}$$

Applying  $\eta^V$  and  $\eta^H$  to (3.8), we get (3.9):

$$\eta^V[\xi^H, X^V] = \xi^H(\eta^V(X^V)), \eta^H[\xi^H, X^V] = 0. \tag{3.9}$$

Using (3.9) in (3.3.c), we obtain

$$N^{(4)}(X^V) = (L_{\xi}^H \eta^V)(X^V) = \xi^H(\eta^V(X^V)) - \eta^V[\xi^H, X^V] = 0.$$

Applying  $\phi$  to (3.8), we get

$$N^{(3)}(X^V) = (L_{\xi}^H \phi)X^V = [\xi^H, \phi X^V] + \phi[X^V, \xi^H] = 0.$$

On the other hand, replacing  $X$  by  $\xi$  in (3.3.a), we obtain

$$[Y^H, \xi^V] - \phi[\xi^V, \phi Y^H] + \xi^V(\eta^H(Y^H))\xi^H = 0. \tag{3.10}$$

Applying  $\eta^H$  and  $\eta^V$  to (3.10), we get

$$\eta^H[\xi^V, Y^H] = \xi^V(\eta^H(Y^H)), \eta^V[\xi^V, Y^H] = 0. \tag{3.11}$$

Using (3.11) in (3.3.d), we obtain

$$N^{(4)}(Y^H) = (L_{\xi}^V \eta^H)(Y^H) = \xi^V(\eta^H(Y^H)) - \eta^H[\xi^V, Y^H] = 0.$$

Applying  $\phi$  to (3.10) and by using (3.11), we obtain

$$N^{(3)}(Y^H) = (L_{\xi}^V \phi)(Y^H) = [\xi^V, \phi Y^H] + \phi[Y^H, \xi^V] = 0.$$

By using (3.11), from (3.3.a), we calculate

$$\begin{aligned} 0 &= N_{\phi}(\phi X^V, Y^H) + d\eta^V(\phi X^V, Y^H)\xi^V + d\eta^H(\phi X^V, Y^H)\xi^H \\ &= [Y^H, \phi X^V] + [\phi Y^H, X^V] + \phi[X^V, Y^H] - \phi[\phi X^V, \phi Y^H] - \phi Y^H(\eta^V(X^V))\xi^V + \phi X^V(\eta^H(Y^H))\xi^H. \end{aligned} \tag{3.12}$$

Applying  $\eta^V$  to (3.12), from (3.3.b), we obtain

$$\begin{aligned} 0 &= N^{(2)}(X^V, Y^H) = \phi X^V(\eta^H(Y^H)) - \phi Y^H(\eta^V(X^V)) - \eta^V[\phi X^V, Y^H] + \eta^H[\phi Y^H, X^V] \\ &\quad + \eta^V[\phi Y^H, X^V] - \eta^H[\phi X^V, Y^H]. \end{aligned}$$

□

**Proposition 3.1** *The almost contact Finsler structure on  $V$  is normal if and only if*

$$N_{\phi} + d\eta^H \otimes \xi^H + d\eta^V \otimes \xi^V = 0. \tag{3.13}$$

*Let  $(\phi, \eta, \xi, G)$  be almost metrical Finsler structure on  $V$  with contact metric. If the structure vector field  $\xi$  is a Killing vector field with respect to  $G$ , the contact structure on  $V$  is called a  $K$ -contact Finsler structure and  $V$  is called a  $K$ -contact Finsler manifold.*

**Lemma 3.2** *Let  $(\phi, \eta, \xi, G)$  be a contact metrical Finsler structure on  $V$ . Then  $N^{(2)}$  and  $N^{(4)}$  vanish. Moreover,  $N^{(3)}$  vanishes if and only if  $\xi$  is a Killing vector field with respect to  $G$ .*



**Proof** We have

$d\eta^H(\phi X^H, \phi Y^H) = \Omega(\phi X^H, \phi Y^H) = G(\phi X^H, \phi^2 Y^H) = -G(X^H, \phi^3 Y^H) = G(X^H, \phi Y^H) = d\eta^H(X^H, Y^H)$   
 from which  $d\eta^H(\phi X^H, Y^H) + d\eta^H(X^H, \phi Y^H) = 0$ . This is equivalent to  $N^{(2)}(X^H, Y^H) = 0$ .

On the other hand, we have  $0 = G(X^H, \phi \xi^H) = d\eta^H(X^H, \xi^H) = X^H \eta^H(\xi^H) - \xi^H \eta^H(X^H) - \eta^H[X^H, \xi^H]$ . Thus we obtain  $\xi^H \eta^H(X^H) - \eta^H([\xi^H, X^H]) = 0$ . Therefore, we have  $L_{\xi^H}^H \eta^H = 0$  hence  $N^{(4)}(X^H) = 0$ .

We mention that  $(L_{\xi^H}^H G)(X^H, \xi^H) = \xi^H(\eta^H(X^H)) - \eta^H[\xi^H, X^H] = (L_{\xi^H}^H \eta^H)X^H = 0$ . Simply, it is clear that  $L_{\xi^H}^H d\eta^H = 0$  and consequently,  $(L_{\xi^H}^H d\eta^H)(X^H, Y^H) = (L_{\xi^H}^H \Omega)(X^H, Y^H) = 0$  from which

$$\begin{aligned} 0 &= \xi^H G(X^H, \phi Y^H) - G([\xi^H, X^H], \phi Y^H) - G(X^H, \phi[\xi^H, Y^H]) \\ &= (L_{\xi^H}^H G)(X^H, \phi Y^H) + G(X^H, (L_{\xi^H}^H \phi)Y^H) = (L_{\xi^H}^H G)(X^H, \phi Y^H) + G(X^H, N^{(3)}(Y^H)). \end{aligned}$$

Thus  $\xi^H$  is a Killing vector field if and only if  $N^{(3)}(Y^H) = 0$ . Similarly, we consider that  $N^{(2)}(X^V, Y^V) = 0$  and  $N^{(4)}(X^V) = 0$ . Moreover,  $N^{(3)}(X^V) = 0$  if and only if  $\xi^V$  is a Killing vector field with respect to  $G^V$ . □

**Lemma 3.3** For an almost contact metric Finsler structure  $(\phi, \eta, \xi, G)$  on  $V$ , we have

$$\begin{aligned} 2G((\nabla_X \phi)Y, Z) &= d\Omega(X, \phi Y, \phi Z) - d\Omega(X, Y, Z) + G(N^{(1)}(Y, Z), \phi X) \\ &+ N^{(2)}(Y, Z)\eta(X) + d\eta(\phi Y, X)\eta(Z) - d\eta(\phi Z, X)\eta(Y). \end{aligned} \tag{3.14}$$

**Proof** The Finsler connection  $\nabla$  with respect to  $G$  is given by

$$\begin{aligned} 2G^H(\nabla_X^H Y^H, Z^H) &= X^H G^H(Y^H, Z^H) + Y^H G^H(X^H, Z^H) - Z^H G(X^H, Y^H) + G^H([X^H, Y^H], Z^H) \\ &+ G^H([Z^H, X^H], Y^H) - G^H([Y^H, Z^H], X^H), \end{aligned} \tag{3.15}$$

$$\begin{aligned} 2G^V(\nabla_X^V Y^V, Z^V) &= X^V G^V(Y^V, Z^V) + Y^V G^V(X^V, Z^V) - Z^V G(X^V, Y^V) + G^V([X^V, Y^V], Z^V) \\ &+ G^V([Z^V, X^V], Y^V) - G^V([Y^V, Z^V], X^V) \end{aligned} \tag{3.16}$$

$$2G^H(\nabla_X^V Y^H, Z^H) = X^V G^H(Y^H, Z^H) + G^H([X^V, Y^H]^H, Z^H) + G^H([Z^H, X^V]^H, Y^H) \tag{3.17}$$

$$2G^V(\nabla_X^H Y^V, Z^V) = X^H G^V(Y^V, Z^V) + G^V([X^H, Y^V]^V, Z^V) + G^V([Z^V, X^H]^V, Y^V). \tag{3.18}$$

Furthermore, we have

$$\begin{aligned} d\Omega(X^H, Y^H, Z^H) &= X^H \Omega(Y^H, Z^H) + Y^H \Omega(Z^H, X^H) + Z^H \Omega(X^H, Y^H) \\ &- \Omega([X^H, Y^H], Z^H) - \Omega([Z^H, X^H], Y^H) - \Omega([Y^H, Z^H], X^H), \end{aligned} \tag{3.19}$$

$$\begin{aligned} d\Omega(X^V, Y^V, Z^V) &= X^V \Omega(Y^V, Z^V) + Y^V \Omega(Z^V, X^V) + Z^V \Omega(X^V, Y^V) \\ &- \Omega([X^V, Y^V], Z^V) - \Omega([Z^V, X^V], Y^V) - \Omega([Y^V, Z^V], X^V), \end{aligned} \tag{3.20}$$

$$d\Omega(X^V, Y^H, Z^H) = X^V \Omega(Y^H, Z^H) - \Omega([X^V, Y^H]^H, Z^H) - \Omega([Z^H, X^V]^H, Y^H), \quad (3.21)$$

$$d\Omega(X^V, Y^V, Z^H) = Z^H \Omega(X^V, Y^V) - \Omega([Z^H, X^V]^V, Y^V) - \Omega([Y^V, Z^H]^V, X^V), \quad (3.22)$$

$$d\Omega(X^H, Y^V, Z^H) = Y^V \Omega(Z^H, X^H) - \Omega([X^H, Y^V]^H, Z^H) - \Omega([Y^V, Z^H]^H, X^H), \quad (3.23)$$

$$d\Omega(X^H, Y^V, Z^V) = X^H \Omega(Y^V, Z^V) - \Omega([X^H, Y^V]^V, Z^V) - \Omega([Z^V, X^H]^V, Y^V), \quad (3.24)$$

$$d\Omega(X^V, Y^H, Z^V) = Y^H \Omega(Z^V, X^V) - \Omega([X^V, Y^H]^V, Z^V) - \Omega([Y^H, Z^V]^V, X^V), \quad (3.25)$$

$$d\Omega(X^H, Y^H, Z^V) = Z^V \Omega(X^H, Y^H) - \Omega([Z^V, X^H]^H, Y^H) - \Omega([Y^H, Z^V]^H, X^H). \quad (3.26)$$

By using (2.9), from (3.15) we get

$$\begin{aligned} 2G^H((\nabla_X^H \phi) Y^H, Z^H) &= \phi Y^H G(X^H, Z^H) - Z^H \Omega(X^H, Y^H) + G^H([X^H, \phi Y^H], Z^H) \\ &+ \Omega([Z^H, X^H], Y^H) - G^H([\phi Y^H, Z^H], X^H) + Y^H \Omega(X^H, Z^H) - \phi Z^H G(X^H, Y^H) \\ &+ \Omega([X^H, Y^H], Z^H) G([\phi Z^H, X^H], Y^H) - G^H([Y^H, \phi Z^H], X^H). \end{aligned}$$

Also from (3.19), we calculate

$$\begin{aligned} d\Omega(X^H, \phi Y^H, \phi Z^H) &= X^H \Omega(Y^H, Z^H) + \phi Y^H G(Z^H, X^H) - \phi Y^H (\eta^H(Z^H) \eta^H(X^H)) \\ &- \phi Z^H G(X^H, Y^H) + \phi Z^H (\eta^H(X^H) \eta^H(Y^H)) + G([X^H, \phi Y^H], Z^H) \\ &- \eta^H[X^H, \phi Y^H] \eta^H(Z^H) + G([\phi Z^H, X^H], Y^H) - \eta^H[\phi Z^H, X^H] \eta^H(Y^H) \\ &- \Omega([\phi Y^H, \phi Z^H], X^H). \end{aligned} \quad (3.27)$$

Also from (3.1.a) by using (2.9), we obtain

$$\begin{aligned} G(N^{(1)}(Y^H, Z^H), \phi X^H) &= -\Omega([Y^H, Z^H], X^H) + \Omega([\phi Y^H, \phi Z^H], X^H) - G([\phi Y^H, Z^H], X^H) \\ &+ \eta^H[\phi Y^H, Z^H] \eta^H(X^H) - G([Y^H, \phi Z^H], X^H) + \eta^H[Y^H, \phi Z^H] \eta^H(X^H). \end{aligned} \quad (3.28)$$

From (3.1.b), we have

$$\begin{aligned} N^{(2)}(Y^H, Z^H) \eta^H(X^H) &= \phi Y^H (\eta^H(Y^H)) \eta^H(X^H) - \phi Z^H (\eta^H(Y^H)) \eta^H(X^H) \\ &- \eta^H[\phi Y^H, Z^H] \eta^H(X^H) - \eta^H[Y^H, \phi Z^H] \eta^H(X^H). \end{aligned} \quad (3.29)$$

By using (3.27), (3.28) and (3.29), we have the equation.

Similarly by using (3.2.a), (3.2.b), (2.9), (3.16) and (3.20), we get

$$\begin{aligned} 2G((\nabla_X^V \phi) Y^V, Z^V) &= d\Omega(X^V, \phi Y^V, \phi Z^V) - d\Omega(X^V, Y^V, Z^V) + G(N^{(1)}(Y^V, Z^V), \phi X^V) \\ &+ N^{(2)}(Y^V, Z^V) \eta^V(X^V) + d\eta^V(\phi Y^V, X^V) \eta^V(Z^V) - d\eta^V(\phi Z^V, X^V) \eta^V(Y^V). \end{aligned}$$

By using (2.9), (3.1.a), (3.1.b), (3.17) and (3.21), we calculate

$$\begin{aligned} &d\Omega(X^V, \phi Y^H, \phi Z^H) - \Omega(X^V, Y^H, Z^H) + d\eta^H(\phi Y^H, X^V) \eta^H(Z^H) - d\eta^H(\phi Z^H, X^V) \eta^H(Y^H) \\ &= G^H([X^V, \phi Y^H]^H, Z^H) + G^H([\phi Z^H, X^V]^H, Y^H) + \Omega([X^V, Y^H]^H, Z^H) + \Omega([Z^H, X^V]^H, Y^H) \\ &= 2G((\nabla_X^V \phi) Y^H, Z^H). \end{aligned}$$

By using (2.9) and (3.18), (3.24), (3.2.a) and (3.2.b), we obtain

$$\begin{aligned}
 & d\Omega(X^H, \phi Y^V, \phi Z^V) - d\Omega(X^H, Y^V, Z^V) + G^V(N^{(1)}(Y^V, Z^V), \phi X^H) \\
 & + N^{(2)}(Y^V, Z^V)\eta^V(X^H) + d\eta^V(\phi Y^V, X^H)\eta^V(Z^V) - d\eta^V(\phi Z^V, X^H)\eta^V(Y^V) \\
 & + d\eta^H(\phi Y^V, X^H)\eta^H(Z^V) - d\eta^H(\phi Z^V, X^H)\eta^H(Y^V) \\
 & = G\left([X^H, \phi Y^V]^V, Z^V\right) - \eta^V(Z^V)\eta^V[X^H, \phi Y^V]^V + G\left([\phi Z^V, X^H]^V, Y^V\right) \\
 & \quad - \eta^V(Y^V)\eta^V[\phi Z^V, X^H]^V + \Omega\left([X^H, Y^V]^V, Z^V\right) + \Omega\left([Z^V, X^H]^V, Y^V\right) \\
 & \quad - \eta^V[\phi Y^V, X^H]^V\eta^V(Z^V) + \eta^V[\phi Z^V, X^H]^V\eta^V(Y^V) \\
 & = 2G^V((\nabla_X^H\phi)Y^V, Z^V).
 \end{aligned}$$

□

**Lemma 3.4** For a contact metric Finsler structure  $(\phi, \eta, \xi, G)$  of  $V$  with  $\Omega = d\eta$  and  $N^{(2)} = 0$ , we get  $2G((\nabla_X\phi)Y, Z) = G(N^{(1)}(Y, Z), \phi X) + d\eta(\phi Y, X)\eta(Z) - d\eta(\phi Z, X)\eta(Y)$ . Especially we have  $\nabla_\xi\phi = 0$ .

**Proof** The first equation is trivial by the assumption. We prove that  $\nabla_\xi\phi = 0$ .

From  $N^{(2)} = 0$  we have  $d\eta^H(X^H, \xi^H) = 0$  and  $d\eta^V(X^V, \xi^V) = 0$ . Thus the first equation implies that  $\nabla_\xi^H\phi = 0$  and  $\nabla_\xi^V\phi = 0$ . □

**Proposition 3.2** Let  $(\phi, \eta, \xi, G)$  be a contact metrical Finsler structure on  $V$ . Then  $(\phi, \eta, \xi, G)$  is a  $K$ -contact Finsler structure if and only if  $N^{(3)}$  vanishes.

**Proposition 3.3** Let  $(\phi, \eta, \xi, G)$  be contact metrical Finsler structure on  $V$ . Then  $(\phi, \eta, \xi, G)$  is a  $K$ -contact structure if and only if

$$\nabla_X\xi^H = -\frac{1}{2}\phi X^H, \nabla_X\xi^V = -\frac{1}{2}\phi X^V. \tag{3.30}$$

**Proof** If the structure vector field  $\xi$  is a Killing vector field with respect to  $G$ , then we have

$$L_\xi^H G^H = 0, L_\xi^V G^V = 0. \tag{3.31}$$

$\forall X^H, Y^H, \xi^H \in N_u$  and  $\forall X^V, Y^V, \xi^V \in V_u^v$  from (3.31), we can get

$$G(\nabla_X^H\xi^H, Y^H) = -G(X^H, \nabla_Y^H\xi^H), G(\nabla_X^V\xi^V, Y^V) = -G(X^V, \nabla_Y^V\xi^V). \tag{3.32}$$

Replacing  $Y^H$  by  $\xi^H$  and  $Z^H$  by  $Y^H$  in (3.15), we have

$$\begin{aligned}
 2G(\nabla_X^H\xi^H, Y^H) &= X^H\eta^H(Y^H) + \xi^HG(X^H, Y^H) - Y^H\eta^H(X^H) \\
 &+ G([X^H, \xi^H], Y^H) - \eta^H([X, Y]^H) - G([\xi^H, Y^H], X^H).
 \end{aligned} \tag{3.33}$$

Replacing  $Y^H$  by  $\xi^H$ ,  $X^H$  by  $Y^H$  and  $Z^H$  by  $X^H$  in (3.15), we can get

$$\begin{aligned}
 2G(\nabla_Y^H\xi^H, X^H) &= Y^H\eta^H(X^H) + \xi^HG(X^H, Y^H) - X^H\eta^H(Y^H) \\
 &+ G([Y^H, \xi^H], X^H) + \eta^H([X, Y]^H) - G([\xi^H, X^H], Y^H).
 \end{aligned} \tag{3.34}$$

Using (3.33) and (3.34), we get  $G(\nabla_X^H \xi^H, Y^H) - G(X^H, \nabla_Y^H \xi^H) = d\eta^H(X^H, Y^H)$ .

Since  $\xi^H$  is a Killing vector field with respect to  $G^H$ , using (3.32), we obtain

$$d\eta^H(X^H, Y^H) = 2G(\nabla_X^H \xi^H, Y^H) = G(X^H, \phi Y^H) = -G(\phi X^H, Y^H) \text{ and } \nabla_X^H \xi^H = -\frac{1}{2}\phi X^H.$$

Similarly for  $X^V, Y^V, \xi^V \in V_u^v$ , from (3.16) and (3.32), we get  $\nabla_X^V \xi^V = -\frac{1}{2}\phi X^V$ . □

**Example 3.1** Let  $V(M) = \{V, \pi, M\}$  be a vector bundle with the total space  $V = R^6$  is a 6-dimensional  $C^\infty$ -manifold and the base space  $M = R^3$  is a 3-dimensional  $C^\infty$ -manifold. Let  $x^i, 1 \leq i \leq 3$  and  $y^a, 1 \leq a \leq 3$  be the coordinates of  $u = (x, y) \in V$  that is  $u = (x^1, x^2, x^3, y^1, y^2, y^3) \in V$ .

The local base of  $N_u$  is  $(\frac{\delta}{\delta x^1}, \frac{\delta}{\delta x^2}, \frac{\delta}{\delta x^3})$  and that of  $V_u^v$  is  $(\frac{\partial}{\partial y^1}, \frac{\partial}{\partial y^2}, \frac{\partial}{\partial y^3})$ .

Let  $X = X^i \frac{\delta}{\delta x^i} + \tilde{X}^a \frac{\partial}{\partial y^a} \forall X \in T_u(V)$ . Then  $X^H = X^1 \frac{\delta}{\delta x^1} + X^2 \frac{\delta}{\delta x^2} + X^3 \frac{\delta}{\delta x^3}$ ,  $X^V = \tilde{X}^1 \frac{\partial}{\partial y^1} + \tilde{X}^2 \frac{\partial}{\partial y^2} + \tilde{X}^3 \frac{\partial}{\partial y^3}$  where  $X^H \in N_u$  and  $X^V \in V_u^v$ . Similarly  $Y$  can be written as

$$Y^H = Y^1 \frac{\delta}{\delta x^1} + Y^2 \frac{\delta}{\delta x^2} + Y^3 \frac{\delta}{\delta x^3}, Y^V = \tilde{Y}^1 \frac{\partial}{\partial y^1} + \tilde{Y}^2 \frac{\partial}{\partial y^2} + \tilde{Y}^3 \frac{\partial}{\partial y^3}.$$

Let  $\eta$  be a 1-form,  $\eta = \eta_i dx^i + \tilde{\eta}_a \delta y^a$  then  $\eta^H = \eta_1 dx^1 + \eta_2 dx^2 + \eta_3 dx^3$  and  $\eta^V = \tilde{\eta}_1 \delta y^1 + \tilde{\eta}_2 \delta y^2 + \tilde{\eta}_3 \delta y^3$  where  $\eta = \eta^H + \eta^V$  and  $\eta^H(X^V) = 0$  and  $\eta^V(X^H) = 0$ . We put  $\eta^H = \frac{1}{2}(dx^3 - x^2 dx^1)$  and  $\eta^V = \frac{1}{2}(\delta y^3 - y^2 \delta y^1)$ . Then the structure vector field  $\xi$  is given by  $\xi = 2(\frac{\delta}{\delta x^3} + \frac{\partial}{\partial y^3})$  and  $\xi$  is decomposed as  $\xi^H = 2\frac{\delta}{\delta x^3}$  and  $\xi^V = 2\frac{\partial}{\partial y^3}$ . The tensor field  $\phi^H$  of type (1, 1) and  $\phi^V$  of type (1, 1) by a matrix form is given by

$$\phi^H = \begin{bmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & x^2 & 0 \end{bmatrix}, \phi^V = \begin{bmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & y^2 & 0 \end{bmatrix}.$$

The Riemann metric tensor field  $G = G^H + G^V$  is given by

$$G^H = \frac{1}{4}(dx^1 \otimes dx^1 + dx^2 \otimes dx^2 + \eta^H \otimes \eta^H) = \frac{1}{4}((1 + (x^2)^2)(dx^1)^2 + (dx^2)^2 + (dx^3)^2 - 2x^2(dx^1)(dx^3))$$

$$G^V = \frac{1}{4}(\delta y^1 \otimes \delta y^1 + \delta y^2 \otimes \delta y^2 + \eta^V \otimes \eta^V) = \frac{1}{4}((1 + (y^2)^2)(\delta y^1)^2 + (\delta y^2)^2 + (\delta y^3)^2 - 2y^2(\delta y^1)(\delta y^3)).$$

Thus we give a metric tensor field  $G$  by a matrix form

$$G^H = \frac{1}{4} \begin{bmatrix} 1 + (x^2)^2 & 0 & -x^2 \\ 0 & 1 & 0 \\ -x^2 & 0 & 1 \end{bmatrix}, G^V = \frac{1}{4} \begin{bmatrix} 1 + (y^2)^2 & 0 & -y^2 \\ 0 & 1 & 0 \\ -y^2 & 0 & 1 \end{bmatrix}.$$

We analyze that  $\eta^H(\xi^H) = 1$ ,  $\eta^V(\xi^V) = 1$ ,  $\phi^H(\xi^H) = 0$ ,  $\eta^H(\xi^V) = 0$ ,  $\phi^V(\xi^V) = 0$ ,  $\eta^V(\xi^H) = 0$ ,  $(\phi^H)^2 X^H = -X^H + \eta^H(X^H)\xi^H$  and  $(\phi^V)^2 X^V = -X^V + \eta^V(X^V)\xi^V$ , hence  $(\phi, \xi, \eta)$  is an almost contact Finsler structure on  $R^6$ .

On the other hand, we formulize that

$$\eta^H(X^H) = G^H(X^H, \xi^H), \eta^V(X^V) = G^V(X^V, \xi^V)$$

$$G^H(\phi X^H, \phi Y^H) = G^H(X^H, Y^H) - \eta^H(X^H)\eta^H(Y^H), G^V(\phi X^V, \phi Y^V) = G^V(X^V, Y^V) - \eta^V(X^V)\eta^V(Y^V)$$

$$\eta^H(X^H) = \frac{1}{2}(dx^3 - x^2 dx^1) \left( X^1 \frac{\delta}{\delta x^1} + X^2 \frac{\delta}{\delta x^2} + X^3 \frac{\delta}{\delta x^3} \right) = \frac{1}{2}(X^3 - X^1 x^2) \tag{3.35}$$

$$G^H(X^H, \xi^H) = \frac{1}{4} \begin{bmatrix} X^1 & X^2 & X^3 \end{bmatrix} \begin{bmatrix} 1 + (x^2)^2 & 0 & -x^2 \\ 0 & 1 & 0 \\ -x^2 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ 2 \end{bmatrix} = \frac{1}{4} \begin{bmatrix} X^1 & X^2 & X^3 \end{bmatrix} \begin{bmatrix} -2x^2 \\ 0 \\ 2 \end{bmatrix} \\ = \frac{1}{4}(-2X^1 x^2 + 2X^3) = \frac{1}{2}(X^3 - X^1 x^2). \tag{3.36}$$

From (3.35) and (3.36) we get  $\eta^H(X^H) = G^H(X^H, \xi^H)$ . Similarly, we have

$$\eta^V(X^V) = \frac{1}{2}(\delta y^3 - y^2 \delta y^1) \left( \tilde{X}^1 \frac{\partial}{\partial y^1} + \tilde{X}^2 \frac{\partial}{\partial y^2} + \tilde{X}^3 \frac{\partial}{\partial y^3} \right) = \frac{1}{2}(\tilde{X}^3 - \tilde{X}^1 y^2) \eta^V = G^V(X^V, \xi^V),$$

$$\phi^H(X^H) = (X^2, -X^1, X^2 x^2), \phi^H(Y^H) = (Y^2, -Y^1, Y^2 x^2),$$

$$\phi^V(X^V) = (\tilde{X}^2, -\tilde{X}^1, \tilde{X}^2 y^2), \phi^V(Y^V) = (\tilde{Y}^2, -\tilde{Y}^1, \tilde{Y}^2 y^2),$$

$$G^H(\phi^H X^H, \phi^H Y^H) = \frac{1}{4}(X^1 Y^1 + X^2 Y^2), G^V(\phi^V X^V, \phi^V Y^V) = \frac{1}{4}(\tilde{X}^1 \tilde{Y}^1 + \tilde{X}^2 \tilde{Y}^2),$$

$$G^H(X^H, Y^H) = \frac{1}{4} \left\{ (Y^1(1 + (x^2)^2) - Y^3 x^2) X^1 + X^2 Y^2 + X^3 (Y^3 - Y^1 x^2) \right\},$$

$$G^V(X^V, Y^V) = \frac{1}{4} \left\{ (\tilde{Y}^1(1 + (y^2)^2) - \tilde{Y}^3 y^2) \tilde{X}^1 + \tilde{X}^2 \tilde{Y}^2 + \tilde{X}^3 (\tilde{Y}^3 - \tilde{Y}^1 y^2) \right\},$$

$$\eta^H(X^H)\eta^H(Y^H) = \frac{1}{4} [X^3 Y^3 + X^1 Y^1 (x^2)^2 - X^1 Y^3 x^2 - X^3 Y^1 x^2],$$

$$\eta^V(X^V)\eta^V(Y^V) = \frac{1}{4} [\tilde{X}^3 \tilde{Y}^3 + \tilde{X}^1 \tilde{Y}^1 (y^2)^2 - \tilde{X}^1 \tilde{Y}^3 y^2 - \tilde{X}^3 \tilde{Y}^1 y^2].$$

Thus, we get  $G^H(\phi X^H, \phi Y^H) = G^H(X^H, Y^H) - \eta^H(X^H)\eta^H(Y^H)$ ,  $G^V(\phi X^V, \phi Y^V) = G^V(X^V, Y^V) - \eta^V(X^V)\eta^V(Y^V)$  and hence  $(\phi, \xi, \eta, G)$  is an almost contact Finsler metric structure.

$$G^H(X^H, \phi Y^H) = \frac{1}{4} \begin{bmatrix} X^1 & X^2 & X^3 \end{bmatrix} \begin{bmatrix} 1 + (x^2)^2 & 0 & -x^2 \\ 0 & 1 & 0 \\ -x^2 & 0 & 1 \end{bmatrix} \begin{bmatrix} Y^2 \\ -Y^1 \\ Y^2 x^2 \end{bmatrix} = \frac{1}{4}(X^1 Y^2 - X^2 Y^1).$$

Also, we know that  $d\eta^H = \frac{1}{2}(dx^1 \wedge dx^2)$ . By using this equality, we obtain

$d\eta^H(X^H, Y^H) = G^H(X^H, \phi Y^H)$ . Similarly we get

$$G^V(X^V, \phi Y^V) = \frac{1}{4} \begin{bmatrix} \tilde{X}^1 & \tilde{X}^2 & \tilde{X}^3 \end{bmatrix} \begin{bmatrix} 1 + (y^2)^2 & 0 & -y^2 \\ 0 & 1 & 0 \\ -y^2 & 0 & 1 \end{bmatrix} \begin{bmatrix} \tilde{Y}^2 \\ -\tilde{Y}^1 \\ \tilde{Y}^2 y^2 \end{bmatrix} = \frac{1}{4}(\tilde{X}^1 \tilde{Y}^2 - \tilde{X}^2 \tilde{Y}^1).$$

By using  $d\eta^V = \frac{1}{2}(\delta y^1 \wedge \delta y^2)$ , we derived  $d\eta^V(X^V, Y^V) = G^V(X^V, \phi Y^V)$ . As a result we come up with the following equation:

$$d\eta^H(X^H, Y^H) = G^H(X^H, \phi Y^H) = \Omega(X^H, Y^H), d\eta^V(X^V, Y^V) = G^V(X^V, \phi Y^V) = \Omega(X^V, Y^V). \quad (3.37)$$

Then the almost contact metrical Finsler structure  $(\phi, \xi, \eta, G)$  is called almost Sasakian Finsler structure.

Because of  $\eta \wedge (d\eta) \neq 0$ ,  $(\phi, \xi, \eta, G)$  is a contact metrical Finsler structure. The vector fields  $X_1 = 2\left(\frac{\delta}{\delta x^2} + \frac{\partial}{\partial y^2}\right)$ ,  $X_2 = 2\left(\frac{\delta}{\delta x^1} + x^2 \frac{\delta}{\delta x^3} + \frac{\partial}{\partial y^1} + y^2 \frac{\partial}{\partial y^3}\right)$  and  $\xi = 2\left(\frac{\delta}{\delta x^3} + \frac{\partial}{\partial y^3}\right)$  form a  $\phi$ -basis for the contact metrical Finsler structure, where these are decomposed as

$$X_1^H = 2\left(\frac{\delta}{\delta x^2}\right), X_1^V = 2\left(\frac{\partial}{\partial y^2}\right), X_2^H = 2\left(\frac{\delta}{\delta x^1} + x^2 \frac{\delta}{\delta x^3}\right), X_2^V = 2\left(\frac{\partial}{\partial y^1} + y^2 \frac{\partial}{\partial y^3}\right), \\ \xi^H = 2\left(\frac{\delta}{\delta x^3}\right), \xi^V = 2\left(\frac{\partial}{\partial y^3}\right).$$

On the other hand, we can see that  $N_\phi + d\eta \otimes \xi = 0$ , that is  $N_\phi^H + d\eta^H \otimes \xi^H = 0$  and  $N_\phi^V + d\eta^V \otimes \xi^V = 0$ . Hence the contact metrical Finsler structure is normal.

#### 4. The curvature of a Finsler connection

The curvature of a Finsler connection  $\nabla$  is given by:

$$R(X, Y)Z = \nabla_X \nabla_Y Z - \nabla_Y \nabla_X Z - \nabla_{[X, Y]}Z, \forall X, Y, Z \in T_u(V). \quad (4.1)$$

As  $\nabla$  preserves by parallelism the horizontal and the vertical distributions, from (4.1) we have that the operator  $R(X, Y)$  carries horizontal vector fields into horizontal vector fields and vertical vector fields into verticals. Consequently,

$$R(X, Y)Z = R^H(X, Y)Z^H + R^V(X, Y)Z^V, \forall X, Y, Z \in T_u(V). \quad (4.2)$$

Noting that the operator  $R(X, Y)$  is skew-symmetric with respect to  $X$  and  $Y$ , a theorem follows [1]:

**Theorem 4.1** *The curvature of a Finsler connection  $\nabla$  on the tangent space  $T_u(V)$  is completely determined by the following six Finsler tensor fields:*

$$R(X^H, Y^H)Z^H = \nabla_X^H \nabla_Y^H Z^H - \nabla_Y^H \nabla_X^H Z^H - \nabla_{[X^H, Y^H]}Z^H, \\ R(X^H, Y^H)Z^V = \nabla_X^H \nabla_Y^H Z^V - \nabla_Y^H \nabla_X^H Z^V - \nabla_{[X^H, Y^H]}Z^V, \\ R(X^V, Y^H)Z^H = \nabla_X^V \nabla_Y^H Z^H - \nabla_Y^H \nabla_X^V Z^H - \nabla_{[X^V, Y^H]}Z^H, \\ R(X^V, Y^H)Z^V = \nabla_X^V \nabla_Y^H Z^V - \nabla_Y^H \nabla_X^V Z^V - \nabla_{[X^V, Y^H]}Z^V, \\ R(X^V, Y^V)Z^H = \nabla_X^V \nabla_Y^V Z^H - \nabla_Y^V \nabla_X^V Z^H - \nabla_{[X^V, Y^V]}Z^H, \\ R(X^V, Y^V)Z^V = \nabla_X^V \nabla_Y^V Z^V - \nabla_Y^V \nabla_X^V Z^V - \nabla_{[X^V, Y^V]}Z^V. \quad (4.3)$$

Then the curvature tensor of a Finsler connection  $\nabla$  has only three different components with respect to the Berwald basis. These are given by:

$$R\left(\frac{\delta}{\delta x^k}, \frac{\delta}{\delta x^j}\right) \frac{\delta}{\delta x^h} = R_{hjk}^i \frac{\delta}{\delta x^i}, R\left(\frac{\partial}{\partial y^k}, \frac{\delta}{\delta x^j}\right) \frac{\delta}{\delta x^h} = P_{hjk}^i \frac{\delta}{\delta x^i}, R\left(\frac{\partial}{\partial y^k}, \frac{\partial}{\partial x^j}\right) \frac{\delta}{\delta x^h} = S_{hjk}^i \frac{\delta}{\delta x^i}. \quad (4.4)$$

These three components are the first, third and fifth Finsler tensors from (4.3). The other three Finsler tensors from (4.3) have the same local components  $R_{h\ jk}^i$ ,  $P_{h\ jk}^i$ , and  $S_{h\ jk}^i$ .

$$\left(\frac{\delta}{\delta x^k}, \frac{\delta}{\delta x^j}\right) \frac{\partial}{\partial y^h} = R_{h\ jk}^i \frac{\partial}{\partial y^i}, R\left(\frac{\partial}{\partial y^k}, \frac{\delta}{\delta x^j}\right) \frac{\partial}{\partial y^h} = P_{h\ jk}^i \frac{\partial}{\partial y^i}, R\left(\frac{\partial}{\partial y^k}, \frac{\partial}{\partial x^j}\right) \frac{\partial}{\partial y^h} = S_{h\ jk}^i \frac{\partial}{\partial y^i}. \tag{4.5}$$

(4.5)

So, a Finsler connection  $\nabla\Gamma = (N_j^i, F_{jk}^i, C_{jk}^i)$  has only three local components  $R_{h\ jk}^i$ ,  $P_{h\ jk}^i$ ,  $S_{h\ jk}^i$  [1]. For a Finsler connection  $\nabla$ , consider the torsion  $T$ , defined as usual

$$T(X, Y) = \nabla_X Y - \nabla_Y X - [X, Y], \forall X, Y \in T_u(V). \tag{4.6}$$

Breaking  $T$  down into horizontal and vertical parts gives the torsion of a Finsler connection,  $\nabla$  on  $T_u(V)$  is completely determined by the following Finsler tensor fields [1]:

$$\begin{aligned} T^H(X^H, Y^H) &= \nabla_X^H Y^H - \nabla_Y^H X^H - [X^H, Y^H]^H, T^V(X^H, Y^H) = -[X^H, Y^H]^V, \\ T^H(X^H, Y^V) &= -\nabla_Y^V X^H - [X^H, Y^V]^H, T^V(X^H, Y^V) = \nabla_X^H Y^V - [X^H, Y^V]^V, \\ T^V(X^V, Y^V) &= \nabla_X^V Y^V - \nabla_Y^V X^V - [X^V, Y^V]^V. \end{aligned} \tag{4.7}$$

Let  $\nabla$  be the torsion free Finsler connection, then we get

$$\begin{aligned} [X^H, Y^H]^H &= \nabla_X^H Y^H - \nabla_Y^H X^H, [X^H, Y^H]^V = 0, [X^H, Y^V]^H = -\nabla_Y^V X^H, \\ [X^H, Y^V]^V &= \nabla_X^H Y^V, [X^V, Y^V]^V = \nabla_X^V Y^V - \nabla_Y^V X^V. \end{aligned} \tag{4.8}$$

**Theorem 4.2** In order for a  $(n+m)$ -dimensional Finsler manifold  $V$  to be  $K$ -contact, it is necessary and sufficient that the following two conditions are satisfied:

1.  $V$  admits a unit Killing vector field  $\xi$ ;
2. The flag curvature for plane sections containing  $\xi$  are equal to  $\frac{1}{4}$  at every point of  $V$ .

**Proof** Let  $V$  be a  $K$ -contact manifold. From (4.3) and (3.30), we have

$$\begin{aligned} G^H(R(X^H, \xi^H)\xi^H, X^H) &= G^H\left(\nabla_X^H \nabla_\xi^H \xi^H - \nabla_\xi^H \nabla_X^H \xi^H - \nabla_{[X^H, \xi^H]}^H \xi^H, X^H\right) \\ &= \frac{1}{4}G^H(X^H, X^H) = \frac{1}{4}, G^V(R(X^V, \xi^V)\xi^V, X^V) \\ &= G^V\left(\nabla_X^V \nabla_\xi^V \xi^V - \nabla_\xi^V \nabla_X^V \xi^V - \nabla_{[X^V, \xi^V]}^V \xi^V, X^V\right) = \frac{1}{4}G^V(X^V, X^V) = \frac{1}{4}, \end{aligned}$$

where  $X^H$  is a unit vector field orthogonal to  $\xi^H$  and  $X^V$  is a unit vector field orthogonal to  $\xi^V$ . Hence

$$\begin{aligned} G(R(X, \xi)\xi, X) &= G^H(R^H(X, \xi)\xi^H, X^H) + G^V(R^V(X, \xi)\xi^V, X^V) \\ &= \frac{1}{4}(G^H(X^H, X^H) + G^V(X^V, X^V)) = \frac{1}{4}G(X, X) = \frac{1}{4}. \end{aligned}$$

Thus we obtain  $K(X, \xi) = \frac{G(R(X, \xi)\xi, X)}{G(X, X)} = \frac{1}{4}$ .

Conversely, we suppose that  $M$  satisfies the conditions (1.1) and (1.2). Since  $\xi$  is a Killing vector field, we have

$$d\eta(X^H, Y^H) = (G^H(\nabla_X^H \xi^H, Y^H) - G^H(\nabla_Y^H \xi^H, X^H)) = -2G(\nabla_Y^H \xi^H, X^H) = G(X^H, \phi Y^H),$$

$$d\eta(X^V, Y^V) = G(X^V, \phi Y^V).$$

Consequently,  $(\phi, \eta, \xi, G)$  is a  $K$ -contact Finsler structure on  $V$ .

Let  $(\phi, \eta, \xi, G)$  be a contact metrical Finsler structure on  $V$ . If the metric structure of  $V$  is normal, then  $V$  is mentioned to have a Sasakian Finsler structure and  $V$  is called a *Sasakian Finsler manifold*.  $\square$

**Theorem 4.3** *An almost contact metrical Finsler structure  $(\phi, \eta, \xi, G)$  on  $V$  is a Sasakian Finsler structure if and only if*

$$(\nabla_X^H \phi) Y^H = \frac{1}{2} [G^H(X^H, Y^H) \xi^H - \eta^H(Y^H) X^H], \tag{4.9}$$

$$(\nabla_X^V \phi) Y^V = \frac{1}{2} [G^V(X^V, Y^V) \xi^V - \eta^V(Y^V) X^V]. \tag{4.10}$$

**Proof** If the structure is normal, we have  $\Omega = d\eta$  and  $N^{(1)} = N^{(2)} = 0$ . Thus, by using (3.14), (3.18) and (3.19), we get  $2G^H((\nabla_X^H \phi) Y^H, \xi^H) = -d\Omega(X^H, Y^H, \xi^H) + d\eta(\phi Y^H, X^H) = G^H(Y^H, X^H) - \eta^H(X^H) \eta^H(Y^H)$ . Thus we have  $(\nabla_X^H \phi) Y^H = \frac{1}{2} [G^H(X^H, Y^H) \xi^H - \eta^H(Y^H) X^H]$ .

Similarly, from Lemma 3.3, we have

$$2G^V((\nabla_X^V \phi) Y^V, \xi^V) = G^V(Y^V, X^V) - \eta^V(X^V) \eta^V(Y^V).$$

Thus we get  $(\nabla_X^V \phi) Y^V = \frac{1}{2} [G^V(X^V, Y^V) \xi^V - \eta^V(Y^V) X^V]$ .

Conversely, we suppose that the structure satisfies (4.9) and (4.10). Putting  $Y^H = \xi^H$  in (4.9) we have  $-\phi \nabla_X^H \xi^H = \frac{1}{2} (\eta^H(X^H) \xi^H - X^H)$ , and putting  $Y^V = \xi^V$  in (4.10), we can get  $-\phi \nabla_X^V \xi^V = \frac{1}{2} (\eta^V(X^V) \xi^V - X^V)$ , and hence, applying  $\phi$  to this, we obtain  $\nabla_X^H \xi^H = -\frac{1}{2} \phi X^H$  and  $\nabla_X^V \xi^V = -\frac{1}{2} \phi X^V$ . Since  $\xi$  is skew-symmetric, we prove that  $\xi^H$  and  $\xi^V$  is a Killing vector field. Moreover, we obtain

$$d\eta(X^H, Y^H) = \frac{1}{2} ((\nabla_X^H \eta) Y^H - (\nabla_Y^H \eta) X^H) = G(X^H, \phi Y^H) = \Omega(X^H, Y^H),$$

$$d\eta(X^V, Y^V) = \frac{1}{2} ((\nabla_X^V \eta) Y^V - (\nabla_Y^V \eta) X^V) = G(X^V, \phi Y^V) = \Omega(X^V, Y^V).$$

Thus the structure is a contact metric Sasakian structure.

If  $(\phi, \eta, \xi, G)$  is a Sasakian Finsler structure on  $V$ , from (4.9) and (4.10) we obtain

$$R(X^H, Y^H) \xi^H = \frac{1}{4} (\eta^H(Y^H) X^H - \eta^H(X^H) Y^H), \tag{4.11}$$

$$R(X^V, Y^V) \xi^V = \frac{1}{4} (\eta^V(Y^V) X^V - \eta^V(X^V) Y^V). \tag{4.12}$$

That is, we have

$$\begin{aligned} R(X, Y) \xi &= R^H(X, Y) \xi^H + R^V(X, Y) \xi^V = R(X^H, Y^H) \xi^H + R(X^V, Y^V) \xi^V \\ &= \frac{1}{4} [\eta^H(Y^H) X^H + \eta^V(Y^V) X^V - \eta^H(X^H) Y^H - \eta^V(X^V) Y^V]. \end{aligned} \tag{4.13}$$

$\square$



**Theorem 4.4** *Let  $V$  be a  $(n+m)$ -dimensional Finsler manifold admitting a unit Killing vector field  $\xi$ . Then  $V$  is a Sasakian Finsler manifold if and only if*

$$R(X, \xi)Y = \frac{1}{4} [-G^H(X, Y)\xi^H - G^V(X, Y)\xi^V + \eta^H(Y^H)X^H + \eta^V(Y^V)X^V]. \quad (4.14)$$

**Proof**

$$\begin{aligned} R^H(X, \xi)Y^H &= \nabla_X^H \nabla_\xi^H Y^H - \nabla_\xi^H \nabla_X^H Y^H - \nabla_{[X, \xi]}^H Y^H = -\frac{1}{2} (\nabla_X^H \phi) Y^H \\ &= \frac{1}{4} [-G(X^H, Y^H)\xi^H + \eta^H(Y^H)X^H], \end{aligned}$$

$$R^V(X, \xi)Y^V = -\frac{1}{2} (\nabla_X^V \phi) Y^V = -\frac{1}{4} [G(X^V, Y^V)\xi^V - \eta^V(Y^V)X^V].$$

From these equations mentioned above, we have the equation.

Let  $(\phi, \eta, \xi, G)$  be a Sasakian Finsler structure on  $V$ . From (4.9) and (4.10), we realize that

$$\begin{aligned} R(X^H, Y^H)\phi Z^H &= \phi R(X^H, Y^H)Z^H + \frac{1}{4} \{G(\phi X^H, Z^H)Y^H - G(Y^H, Z^H)\phi X^H \\ &+ G(X^H, Z^H)\phi Y^H - G(\phi Y^H, Z^H)X^H\}, \end{aligned} \quad (4.15)$$

$$\begin{aligned} R(X^V, Y^V)\phi Z^V &= \phi R(X^V, Y^V)Z^V + \frac{1}{4} \{G(\phi X^V, Z^V)Y^V - G(Y^V, Z^V)\phi X^V \\ &+ G(X^V, Z^V)\phi Y^V - G(\phi Y^V, Z^V)X^V\}, \end{aligned} \quad (4.16)$$

$$R(X^H, Y^H)\phi Z^V = \phi R(X^H, Y^H)Z^V, \quad (4.17)$$

$$R(X^H, Y^V)\phi Z^V = \phi R(X^H, Y^V)Z^V - \frac{1}{4} \{G(Y^V, Z^V)\phi X^H - G(\phi Y^V, Z^V)X^H\}, \quad (4.18)$$

$$R(X^V, Y^H)\phi Z^V = \phi R(X^V, Y^H)Z^V + \frac{1}{4} \{G(\phi X^V, Z^V)Y^H + G(X^V, Z^V)\phi Y^H\}, \quad (4.19)$$

$$R(X^V, Y^V)\phi Z^H = \phi R(X^V, Y^V)Z^H, \quad (4.20)$$

$$R(X^V, Y^H)\phi Z^H = \phi R(X^V, Y^H)Z^H - \frac{1}{4} \{G(Y^H, Z^H)\phi X^V - G(\phi Y^H, Z^H)X^V\}, \quad (4.21)$$

$$R(X^H, Y^V)\phi Z^H = \phi R(X^H, Y^V)Z^H + \frac{1}{4} \{G(\phi X^H, Z^H)Y^V + G(X^H, Z^H)\phi Y^V\}, \quad (4.22)$$

$$R(X, Y)\phi Z = R(X, Y)\phi Z^H + R(X, Y)\phi Z^V. \quad (4.23)$$

From (4.15), (4.16), (4.17), (4.18), (4.19), we also have the following equations:

$$\begin{aligned} R(X^H, Y^H)Z^H &= -\phi R(X^H, Y^H)\phi Z^H + \frac{1}{4} \{G(Y^H, Z^H)X^H - G(X^H, Z^H)Y^H \\ &- G(\phi Y^H, Z^H)\phi X^H + G(\phi X^H, Z^H)\phi Y^H\}, \end{aligned} \quad (4.24)$$

$$\begin{aligned} R(X^V, Y^V)Z^V &= -\phi R(X^V, Y^V)\phi Z^V + \frac{1}{4} \{G(Y^V, Z^V)X^V - G(X^V, Z^V)Y^V \\ &- G(\phi Y^V, Z^V)\phi X^V + G(\phi X^V, Z^V)\phi Y^V\}, \end{aligned} \quad (4.25)$$

$$R(X^H, Y^H)Z^V = -\phi R(X^H, Y^H)\phi Z^V, \quad (4.26)$$

$$R(X^H, Y^V)Z^V = -\phi R(X^H, Y^V)\phi Z^V + \frac{1}{4} \{G(Y^V, Z^V)X^H - G(\phi Y^V, Z^V)\phi X^H\}, \quad (4.27)$$

$$R(X^V, Y^H) Z^V = -\phi R(X^V, Y^H) \phi Z^V - \frac{1}{4} \{G(X^V, Z^V) Y^H + G(\phi X^V, Z^V) \phi Y^H\}, \tag{4.28}$$

$$R(X^V, Y^V) Z^H = -\phi R(X^V, Y^V) \phi Z^H, \tag{4.29}$$

$$R(X^V, Y^H) Z^H = -\phi R(X^V, Y^H) \phi Z^H + \frac{1}{4} \{G(Y^H, Z^H) X^H - G(\phi Y^H, Z^H) \phi X^H\}, \tag{4.30}$$

$$R(X^H, Y^V) Z^H = -\phi R(X^H, Y^V) \phi Z^H - \frac{1}{4} \{G(X^H, Z^H) Y^V + G(\phi X^H, Z^H) \phi Y^V\}, \tag{4.31}$$

$$\begin{aligned} G(R(\phi X^H, \phi Y^H) \phi Z^H, \phi W^H) &= G(R(X^H, Y^H) Z^H, W^H) \\ &+ \frac{1}{4} \{-\eta^H(Y^H) \eta^H(Z^H) G(X^H, W^H) - \eta^H(X^H) \eta^H(W^H) G(Y^H, Z^H) \\ &+ \eta^H(Y^H) \eta^H(W^H) G(X^H, Z^H) + \eta^H(X^H) \eta^H(Z^H) G(Y^H, W^H)\}, \end{aligned} \tag{4.32}$$

$$\begin{aligned} G(R(\phi X^V, \phi Y^V) \phi Z^V, \phi W^V) &= G(R(X^V, Y^V) Z^V, W^V) \\ &+ \frac{1}{4} \{-\eta^V(Y^V) \eta^V(Z^V) G(X^V, W^V) - \eta^V(X^V) \eta^V(W^V) G(Y^V, Z^V) \\ &+ \eta^V(Y^V) \eta^V(W^V) G(X^V, Z^V) + \eta^V(X^V) \eta^V(Z^V) G(Y^V, W^V)\}. \end{aligned} \tag{4.33}$$

A plane section in  $N_u$  is called a *horizontal  $\phi$ -section* if there exists a unit vector  $X^H$  in  $N_u$  orthogonal to  $\xi^H$  such that  $\{X^H, \phi X^H\}$  and a plane section in  $V_u^v$  is called a *vertical  $\phi$ -section* if there exists a unit vector  $X^V$  in  $V_u^v$  orthogonal to  $\xi^V$  such that  $\{X^V, \phi X^V\}$ . Then the horizontal flag curvature

$$K(X^H, \phi X^H) = G^H(R(X^H, \phi X^H) \phi X^H, X^H) \tag{4.34}$$

is called a *horizontal  $\phi$ -sectional curvature*, which will be denoted by  $K^H(X^H)$ . Vertical flag curvature

$$K(X^V, \phi X^V) = G^V(R(X^V, \phi X^V) \phi X^V, X^V) \tag{4.35}$$

is called a *vertical  $\phi$ -sectional curvature*, which will be denoted by  $K^V(X^V)$ . On a Sasakian Finsler manifold the  $\phi$ -sectional curvature is  $K(X) = K^H(X^H) + K^V(X^V)$ . □

**Proposition 4.1** *Let  $(\phi, \eta, \xi, G)$  be a  $K$ -contact Finsler structure on  $V$ . If  $V$  is locally symmetric, then  $V$  is a Sasakian Finsler manifold with constant curvature  $\frac{1}{4}$ .*

**Proof** For  $X^H, Y^H, Z^H, \xi^H \in N_u$  from (4.9), (4.10), (4.11) and (4.12), we get

$$(\nabla_Z^H R)(X^H, Y^H, \xi^H) = \frac{1}{4} \{G(Z^H, X^H) Y^H - G(Z^H, Y^H) X^H\} - R(X^H, Y^H) Z^H. \tag{4.36}$$

Since  $V$  is locally symmetric, that is,  $\nabla_Z^H R = 0$ , from (4.36) we obtain

$$R(X^H, Y^H) Z^H = \frac{1}{4} \{G(Z^H, Y^H) X^H - G(Z^H, X^H) Y^H\}.$$

Thus for any orthonormal pair  $\{X^H, Y^H\}$ , we get

$$K(X^H, Y^H) = G(R(X^H, Y^H) Y^H, X^H) = \frac{1}{4}.$$

Similarly for  $X^V, Y^V, Z^V, \xi^V \in V_u^v$ , we get

$$R(X^V, Y^V) Z^V = \frac{1}{4} \{G(Z^V, Y^V) X^V - G(Z^V, X^V) Y^V\},$$

and for any orthonormal pair  $\{X^V, Y^V\}$ , we obtain  $K(X^V, Y^V) = G(R(X^V, Y^V) Y^V, X^V) = \frac{1}{4}$ .

For any orthonormal pair  $\{X, Y\}$ , we get  $K(X, Y) = \frac{G^H(R(X^H, Y^H) Y^H, X^H) + G^V(R(X^V, Y^V) Y^V, X^V)}{G^H(X^H, X^H)G^H(Y^H, Y^H) + G^V(X^V, X^V)G^V(Y^V, Y^V)} = \frac{1}{4}$  which shows us that the sectional curvature of  $V$  is  $\frac{1}{4}$ . The *horizontal Ricci tensor*  $S^H$  of a  $(4n+2)$ -dimensional Sasakian Finsler manifold  $V$  is given by

$$\begin{aligned} S^H(X^H, Y^H) &= \sum_{i=1}^{2n} G(R(X^H, E_i^H) E_i^H, Y^H) + G(R(X^H, \xi^H) \xi^H, Y^H) \\ &= \sum_{i=1}^{2n} G(R(E_i^H, X^H) Y^H, E_i^H) + G(R(\xi^H, X^H) Y^H, \xi^H), \end{aligned}$$

where  $\{E_1^H, E_2^H, \dots, E_{2n}^H, \xi^H\}$  is a local orthonormal frame of  $N_u$ .

The *vertical Ricci tensor* of a  $(4n+2)$ -dimensional Sasakian Finsler manifold  $V$  is given by

$$\begin{aligned} S^V(X^V, Y^V) &= \sum_{i=1}^{2n} G(R(X^V, E_i^V) E_i^V, Y^V) + G(R(X^V, \xi^V) \xi^V, Y^V) \\ &= \sum_{i=1}^{2n} G(R(E_i^V, X^V) Y^V, E_i^V) + G(R(\xi^V, X^V) Y^V, \xi^V) \end{aligned}$$

where  $\{E_1^V, E_2^V, \dots, E_{2n}^V, \xi^V\}$  is a local orthonormal frame of  $V_u^v$ . Thus the Ricci tensor  $S$  of a  $(4n+2)$ -dimensional Sasakian Finsler manifold  $V$  is given by

$$\begin{aligned} S(X, Y) &= S^H(X, Y) + S^V(X, Y) = S(X^H, Y^H) + S(X^V, Y^V) \\ &= \sum_{i=1}^{2n} G(R(X^H, E_i^H) E_i^H, Y^H) + G(R(X^H, \xi^H) \xi^H, Y^H) \\ &\quad + \sum_{i=1}^{2n} G(R(X^V, E_i^V) E_i^V, Y^V) + G(R(X^V, \xi^V) \xi^V, Y^V). \end{aligned} \tag{4.37}$$

□

**Proposition 4.2** *A contact metric structure  $(\phi, \eta, \xi, G)$  on a Finsler manifold of dimension  $(4n+2)$  is  $K$ -contact if and only if  $S(\xi^H, \xi^H) = \frac{n}{2}, S(\xi^V, \xi^V) = \frac{n}{2}$ .*

**Proof** From (4.37) and (4.14), we have

$$S(\xi^H, \xi^H) = \sum_{i=1}^{2n} G(R(E_i^H, \xi^H) \xi^H, E_i^H) = \frac{1}{4} \sum_{i=1}^{2n} G(E_i^H, E_i^H) - \frac{1}{4} \sum_{i=1}^{2n} \eta^H(E_i^H) \eta^H(E_i^H).$$

Since  $E_i^H$  and  $\xi^H$  orthogonal, we can take  $\eta^H(E_i^H) = 0$ , thus we have  $S(\xi^H, \xi^H) = \frac{n}{2}$ .

$$S(\xi^V, \xi^V) = \sum_{i=1}^{2n} G(R(E_i^V, \xi^V) \xi^V, E_i^V) = \frac{1}{4} \sum_{i=1}^{2n} G(E_i^V, E_i^V) - \frac{1}{4} \sum_{i=1}^{2n} \eta^V(E_i^V) \eta^V(E_i^V).$$

Since  $E_i^V$  and  $\xi^V$  orthogonal, we can take  $\eta^V(E_i^V) = 0$ , thus we have  $S(\xi^V, \xi^V) = \frac{n}{2}$ . □

**Lemma 4.1** *The Ricci tensor  $S$  of a  $(4n+2)$ -dimensional Sasakian Finsler manifold satisfies the following equations:*

$$S(X, \xi) = S(X^H, \xi^H) + S(X^V, \xi^V) = \frac{n}{2}\eta^H(X^H) + \frac{n}{2}\eta^V(X^V) = \frac{n}{2}(\eta^H(X^H) + \eta^V(X^V)) = \frac{n}{2}\eta(X),$$

$$S(\phi X, \phi Y) = S(\phi X^H, \phi Y^H) + S(\phi X^V, \phi Y^V) - \frac{n}{2}\eta^H(X^H)\eta^H(Y^H) - \frac{n}{2}\eta^V(X^V)\eta^V(Y^V).$$

**5. Conclusion**

For the Sasakian Finsler structure  $(\phi, \eta, \xi, G)$  on  $V$ , the following relations hold:

$$\phi.\phi = -I_n + \eta^H \otimes \xi^H + \eta^V \otimes \xi^V, \phi\xi^H = 0, \phi\xi^V = 0, \eta^H(\xi^H) + \eta^V(\xi^V) = 1,$$

$$\eta^H(\phi X^H) = 0, \eta^V(\phi X^H) = 0, \eta^H(\phi X^V) = 0, \eta^V(\phi X^V) = 0,$$

$$G^H(\phi X, \phi Y) = G^H(X, Y) - \eta^H(X^H)\eta^H(Y^H), G^V(\phi X, \phi Y) = G^V(X, Y) - \eta^V(X^V)\eta^V(Y^V),$$

$$G^H(X, \xi) = \eta^H(X^H), G^V(X, \xi) = \eta^V(X^V), N_\phi + d\eta^H \otimes \xi^H + d\eta^V \otimes \xi^V = 0,$$

$$\Omega(X^H, Y^H) = G^H(X, \phi Y) = d\eta(X^H, Y^H), \Omega(X^V, Y^V) = G^V(X, \phi Y) = d\eta(X^V, Y^V),$$

$$\nabla_\xi^H \phi = 0, \nabla_\xi^V \phi = 0, \nabla_X^H \xi^H = -\frac{1}{2}\phi X^H, \nabla_X^V \xi^V = -\frac{1}{2}\phi X^V,$$

$$\begin{aligned} (\nabla_X^H \phi) Y^H &= \frac{1}{2} [G^H(X^H, Y^H)\xi^H - \eta^H(Y^H)X^H], (\nabla_X^V \phi) Y^V \\ &= \frac{1}{2} [G^V(X^V, Y^V)\xi^V - \eta^V(Y^V)X^V], R(X^H, Y^H)Z^H \\ &= \frac{1}{4} \{G(Z^H, Y^H)X^H - G(Z^H, X^H)Y^H\} \text{ (} V \text{ is locally symmetric)}, R^H(X^H, Y^H)\xi^H \\ &= \frac{1}{4} (\eta^H(Y^H)X^H - \eta^H(X^H)Y^H), R^V(X^V, Y^V)\xi^V \\ &= \frac{1}{4} (\eta^V(Y^V)X^V - \eta^V(X^V)Y^V), R^H(X^H, \xi^H)Y^H \\ &= \frac{1}{4} [-G(X^H, Y^H)\xi^H + \eta^H(Y^H)X^H], S(\xi^H, \xi^H) = \frac{n}{2}, \end{aligned}$$

$$R^V(X^V, \xi^V)Y^V = \frac{1}{4} [-G(X^V, Y^V)\xi^V + \eta^V(Y^V)X^V], S(\xi^V, \xi^V) = \frac{n}{2},$$

$$K(X^V, Y^V) = G(R(X^V, Y^V)Y^V, X^V) = \frac{1}{4}, K(X^H, Y^H) = G(R(X^H, Y^H)Y^H, X^H) = \frac{1}{4},$$

$$S(X, \xi) = S(X^H, \xi^H) + S(X^V, \xi^V) = \frac{n}{2}(\eta^H(X^H) + \eta^V(X^V)) = \frac{n}{2}\eta(X).$$

$\forall X^V, Y^V, \xi^V \in V_u^v$  and  $\forall X^H, Y^H, \xi^H \in N_u$ , where a linear connection  $\nabla$  on  $V$  denotes Finsler connection,  $\phi$  is the tensor field of type  $\begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$  on  $V$ ,  $\eta$  is a 1-form,  $S$  is the Ricci tensor,  $R$  is the Riemann curvature tensor,  $G$  is the Finsler metric structure on  $V$ ,  $K$  is the flag curvature on  $V$ . Next, let us set the equation below

$2d\tilde{\eta}(X, Y) = X(\tilde{\eta}(Y)) - Y(\tilde{\eta}(X)) - \tilde{\eta}[X, Y], \forall X = X^H \in N_u, Y = Y^H \in N_u, \forall \tilde{\eta} = \eta^H \in N_u^*$ . If we get  $\tilde{\phi} = \phi^H, \tilde{\eta} = \eta^H, \tilde{\xi} = \xi^H, \tilde{g} = G^H$ , the standard Sasakian structure of the base space  $M^{2n+1}$  is  $(\tilde{\phi}, \tilde{\xi}, \tilde{\eta}, \tilde{g})$ . Then we have the following equations:

$$N_{\tilde{\phi}} + 2d\tilde{\eta} \otimes \tilde{\xi} = 0, \nabla_X \tilde{\xi} = -\phi X, L_{\tilde{\xi}} \tilde{g} = 0, \nabla_{\tilde{\xi}} \tilde{\phi} = 0,$$

$$(\nabla_X \tilde{\phi}) Y = \tilde{g}(X, Y) \tilde{\xi} - \tilde{\eta}(Y) X, R(X, \tilde{\xi}) Y = \tilde{\eta}(Y) X - \tilde{g}(X, Y) \tilde{\xi},$$

$$\tilde{g}(R(X, \tilde{\xi}) \tilde{\xi}, X) = 1, S(\tilde{\xi}, \tilde{\xi}) = 2n, R(X, Y) \tilde{\xi} = \tilde{\eta}(Y) X - \tilde{\eta}(X) Y,$$

$K(X, Y) = \tilde{g}(R(X, Y) Y, X) = 1$  (sectional curvature for orthonormal pair  $\{X, Y\}$ ).

The structure  $(\phi^H, \eta^H, \xi^H, G^H)$  on  $N_u$  is Sasakian Finsler if and only if the base manifold  $M^{2n+1}$  with the structure  $(\tilde{\phi}, \tilde{\xi}, \tilde{\eta}, \tilde{g})$  has positive constant curvature 1 in which case  $M^{2n+1}$  is Sasakian manifold and  $N_u$  is Sasakian Finsler manifold.

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