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# On Finsler metrics with vanishing S-curvature 

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#### Abstract

In this paper, we consider Finsler metrics defined by a Riemannian metric and a 1-form on a manifold. We study these metrics with vanishing S-curvature. We find some conditions under which such a Finsler metric is Berwaldian or locally Minkowskian.


Key words: $(\alpha, \beta)$-metric, Berwald metric, S-curvature.

## 1. Introduction

In Finsler geometry, there are several important non-Riemannian quantities: the Cartan torsion $\mathbf{C}$, the Berwald curvature $\mathbf{B}$, the S-curvature $\mathbf{S}$, the new non-Riemannian curvature $\mathbf{H}$, etc. They all vanish for Riemannian metrics; hence they are said to be non-Riemannian $[6,7,9]$.

Let $(M, F)$ be a Finsler manifold. The Finsler metric $F$ on $M$ induced a spray $\mathbf{G}=y^{i} \frac{\partial}{\partial x^{i}}-2 G^{i}(x, y) \frac{\partial}{\partial y^{i}}$, which determines the geodesics, where $G^{i}=G^{i}(x, y)$ are called the spray coefficients of $\mathbf{G}$. A Finsler metric $F$ is called a Berwald metric if $G^{i}=\frac{1}{2} \Gamma_{j k}^{i}(x) y^{j} y^{k}$ are quadratic in $y \in T_{x} M$ for any $x \in M$. The Berwald curvature B of Finsler metrics is an important non-Riemannian quantity constructed by L. Berwald.

The S-curvature is constructed by Shen for given comparison theorems on Finsler manifolds [10]. A natural problem is to study and characterize Finsler metrics of vanishing S-curvature. It is known that some Randers metrics are of vanishing S-curvature [8, 13]. This is one of our motivations to consider Finsler metrics with vanishing S-curvature. Shen proved that every Berwald metric satisfies $\mathbf{S}=0$ [10]. In [2], Bao and Shen find a class of non-Berwaldian Randers metrics with vanishing S-curvature. Thus the converse of Shen's theorem is not true, generally. A natural question arises: "Under which conditions does the converse of Shen's Theorem hold?"

There are 2 basic tensors on Finsler manifolds: fundamental metric tensor $\mathbf{g}_{y}$ and the Cartan torsion $\mathbf{C}_{y}$, which are second and third order derivatives of $\frac{1}{2} F_{x}^{2}$ at $y \in T_{x} M_{0}$, respectively. The rate of change of $\mathbf{C}$ along Finslerian geodesics is called Landsberg curvature $\mathbf{L}_{y}$. Taking a trace of $\mathbf{C}$ and $\mathbf{L}$ gives us mean Cartan torsion I and mean Landsberg curvature $\mathbf{J}$, respectively. $\mathbf{J} / \mathbf{I}$ is regarded as the relative rate of change of $\mathbf{I}$ along Finslerian geodesics. Then $F$ is said to be an isotropic mean Landsberg metric if $\mathbf{J}+c F \mathbf{I}=0$, where $c=c(x)$ is a scalar function on $M$.

[^0]Theorem 1 Let $F=\alpha \phi(s)$, $s=\frac{\beta}{\alpha}$ be a non-Riemannian $(\alpha, \beta)$-metric on manifold $M$ with vanishing $S$ curvature and $\phi \neq c_{1} \sqrt{1+c_{2} s^{2}}+c_{3} s$ for any constant $c_{1}>0, c_{2}, c_{3}$. Suppose that $\mathbf{J} / \mathbf{I}$ is isotropic,

$$
\mathbf{J}+c(x) F \mathbf{I}=0
$$

where $c=c(x)$ is a scalar function on $M$. Then $F$ reduces to a Berwald metric.

There is a weaker notion of Berwald metrics, namely R-quadratic metrics. For a Finsler space $(M, F)$, the Riemann curvature is a family of linear transformations $\mathbf{R}_{y}: T_{x} M \rightarrow T_{x} M$, where $y \in T_{x} M$, with homogeneity $\mathbf{R}_{\lambda y}=\lambda^{2} \mathbf{R}_{y}, \forall \lambda>0$ (the definition will be given in $\S 2$ ). If $F$ is Riemannian, i.e. $F(y)=\sqrt{g(y, y)}$ for some Riemannian metric $g$, then $\mathbf{R}_{y}:=\mathrm{R}(\cdot, y) y$, where $\mathrm{R}(u, v) z$ denotes the Riemannian curvature tensor of $g$. In this case, $\mathbf{R}_{y}$ is quadratic in $y \in T_{x} M$. A Finsler metric is said to be R-quadratic if its Riemann curvature $\mathbf{R}_{y}$ is quadratic in $y \in T_{x} M$ [11]. There are many non-Riemannian R-quadratic Finsler metrics. For example, all Berwald metrics are R-quadratic. Indeed a Finsler metric is R-quadratic if and only if the h-curvature of Berwald connection depends on position only in the sense of Bácsó-Matsumoto [1]. The notion of R-quadratic Finsler metrics was introduced by Shen, and can be considered a generalization of R-flat metrics.

Theorem 2 Let $F=\alpha \phi(s)$, $s=\frac{\beta}{\alpha}$ be a non-Riemannian $(\alpha, \beta)$-metric on a manifold $M$ with vanishing $S$-curvature and $\phi \neq c_{1} \sqrt{1+c_{2} s^{2}}+c_{3} s$ for any constant $c_{1}>0, c_{2}, c_{3}$. Suppose that $F$ is $R$-quadratic. Then $F$ reduces to a Berwald metric.

Information geometry has emerged from investigating the geometrical structure of a family of probability distributions and has been applied successfully to various areas including statistical inference, control system theory, and multiterminal information theory. Dually flat Finsler metrics form a special and valuable class of Finsler metrics in Finsler information geometry, and play a very important role in studying flat Finsler information structures. A Finsler metric $F=F(x, y)$ on a manifold $M$ is said to be locally dually flat if at any point there is a standard coordinate system $\left(x^{i}, y^{i}\right)$ in $T M$ satisfying $\left[F^{2}\right]_{x^{k} y^{l}} y^{k}=2\left[F^{2}\right]_{x^{l}}$. It is easy to see that every locally Minkowskian metric satisfies in the above equation, hence is locally dually flat [14, 15]. Here, we find some conditions under which a locally dually flat non-Randers type $(\alpha, \beta)$-metric reduces to a locally Minkowskian metric. More precisely, we prove the following.

Theorem 3 Let $F=\alpha \phi(s), s=\frac{\beta}{\alpha}$ be a non-Randers type $(\alpha, \beta)$-metric on a manifold $M$ of dimension $n \geq 3$ with vanishing $S$-curvature. Suppose that one of the following holds:
(a) $\phi^{\prime}(0) \neq 0$ and $\left(k_{2}-k_{3} b^{2}\right) b^{2} \neq-1$;
(b) $\phi^{\prime}(0)=\phi^{\prime \prime}(0)=0$ or $\phi$ is a polynomial that $\phi^{\prime}(0)=0$.

If $F$ is locally dually flat then it reduces to a locally Minkowskian metric.

In this paper, we use the Berwald connection and the $h$ - and $v$ - covariant derivatives of a Finsler tensor field are denoted by " | " and ", " respectively [12].

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## 2. Preliminary

A Finsler metric on a manifold $M$ is a nonnegative function $F$ on $T M$ having the following properties:
(a) $F$ is $C^{\infty}$ on $T M_{0}:=T M \backslash\{0\}$;
(b) $F(\lambda y)=\lambda F(y), \forall \lambda>0, \quad y \in T M$;
(c) for each $y \in T_{x} M$, the following quadratic form $\mathbf{g}_{y}$ on $T_{x} M$ is positive definite,

$$
\mathbf{g}_{y}(u, v):=\left.\frac{1}{2}\left[F^{2}(y+s u+t v)\right]\right|_{s, t=0}, \quad u, v \in T_{x} M
$$

At each point $x \in M, F_{x}:=\left.F\right|_{T_{x} M}$ is an Euclidean norm if and only if $\mathbf{g}_{y}$ is independent of $y \in T_{x} M_{0}$. To measure the non-Euclidean feature of $F_{x}$, define $\mathbf{C}_{y}: T_{x} M \otimes T_{x} M \otimes T_{x} M \rightarrow \mathbb{R}$ by

$$
\mathbf{C}_{y}(u, v, w):=\left.\frac{1}{2} \frac{d}{d t}\left[\mathbf{g}_{y+t w}(u, v)\right]\right|_{t=0}, \quad u, v, w \in T_{x} M
$$

The family $\mathbf{C}:=\left\{\mathbf{C}_{y}\right\}_{y \in T M_{0}}$ is called the Cartan torsion.
Given a Finsler manifold $(M, F)$, then a global vector field $\mathbf{G}$ is induced by $F$ on $T M_{0}$, which in a standard coordinate $\left(x^{i}, y^{i}\right)$ for $T M_{0}$ is given by

$$
\mathbf{G}=y^{i} \frac{\partial}{\partial x^{i}}-2 G^{i}(x, y) \frac{\partial}{\partial y^{i}}
$$

where $G^{i}(x, y)$ are local functions on $T M_{0}$ satisfying

$$
G^{i}(x, \lambda y)=\lambda^{2} G^{i}(x, y) \quad \lambda>0
$$

$\mathbf{G}$ is called the associated spray to $(M, F)$. The projection of an integral curve of $G$ is called a geodesic in $M$. In local coordinates, a curve $c(t)$ is a geodesic if and only if its coordinates $\left(c^{i}(t)\right)$ satisfy $\ddot{c}^{i}+2 G^{i}(\dot{c})=0$. A Finsler metric $F$ is called a Berwald metric if $G^{i}$ are quadratic in $y \in T_{x} M$ for any $x \in M$ or equivalently the Berwald curvature

$$
B_{j k l}^{i}:=\frac{\partial^{3} G^{i}}{\partial y^{j} \partial y^{k} \partial y^{l}}
$$

is vanishing.
A Finsler metric $F=F(x, y)$ on a manifold $M$ is said to be locally dually flat if at any point there is a coordinate system $\left(x^{i}\right)$ in which the spray coefficients are in the following form:

$$
G^{i}=-\frac{1}{2} g^{i j} H_{y^{j}}
$$

where $H=H(x, y)$ is a $C^{\infty}$ scalar function on $T M_{0}$ satisfying $H(x, \lambda y)=\lambda^{3} H(x, y)$ for all $\lambda>0$. Such a coordinate system is called an adapted coordinate system [4]. In [8], Shen proved that the Finsler metric $F$ on an open subset $U \subset \mathbb{R}^{n}$ is dually flat if and only if it satisfies

$$
\left(F^{2}\right)_{x^{k} y^{l}} y^{k}=2\left(F^{2}\right)_{x^{l}}
$$

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In this case, $H=-\frac{1}{6}\left[F^{2}\right]_{x^{m}} y^{m}$.
Let $U(t)$ be a vector field along a curve $c(t)$. The canonical covariant derivative $\mathrm{D}_{\dot{c}} U(t)$ is defined by

$$
\mathrm{D}_{\dot{c}} U(t):=\left.\left\{\frac{d U^{i}}{d t}(t)+U^{j}(t) \frac{\partial G^{i}}{\partial y^{j}}(\dot{c}(t))\right\} \frac{\partial}{\partial x^{i}}\right|_{c(t)} .
$$

$U(t)$ is said to be parallel along $c$ if $\mathrm{D}_{\dot{c}(t)} U(t)=0$.
To measure the changes in the Cartan torsion $\mathbf{C}$ along geodesics, we define $\mathbf{L}_{y}: T_{x} M \otimes T_{x} M \otimes T_{x} M \rightarrow \mathbb{R}$ by

$$
\mathbf{L}_{y}(u, v, w):=\left.\frac{d}{d t}\left[\mathbf{C}_{\dot{c}(t)}(U(t), V(t), W(t))\right]\right|_{t=0}
$$

where $c(t)$ is a geodesic and $U(t), V(t), W(t)$ are parallel vector fields along $c(t)$ with $\dot{c}(0)=y, U(0)=$ $u, V(0)=v, W(0)=w$. The family $\mathbf{L}:=\left\{\mathbf{L}_{y}\right\}_{y \in T M_{0}}$ is called the Landsberg curvature. A Finsler metric is called a Landsberg metric if $\mathbf{L}=0$. An important fact is that if $F$ is Berwaldian, then it is Landsbergian. $\mathbf{L} / \mathbf{C}$ is regarded as the relative rate of change in $\mathbf{C}$ along Finslerian geodesics. Then $F$ is said to be an isotropic Landsberg metric if $\mathbf{L}=c F \mathbf{C}$, where $c=c(x)$ is a scalar function on $M$.

For a vector $y \in T_{x} M_{0}$, the Riemann curvature $R_{y}: T_{x} M \rightarrow T_{x} M$ is defined by $R_{y}(u):=R_{k}^{i}(y) u^{k} \frac{\partial}{\partial x^{i}}$, where

$$
R_{k}^{i}(y)=2 \frac{\partial G^{i}}{\partial x^{k}}-\frac{\partial^{2} G^{i}}{\partial x^{j} \partial y^{k}} y^{j}+2 G^{j} \frac{\partial^{2} G^{i}}{\partial y^{j} \partial y^{k}}-\frac{\partial G^{i}}{\partial y^{j}} \frac{\partial G^{j}}{\partial y^{k}} .
$$

The family $R:=\left\{R_{y}\right\}_{y \in T M_{0}}$ is called the Riemann curvature. There are many Finsler metrics whose Riemann curvature in every direction is quadratic. A Finsler metric $F$ is said to be R-quadratic if $R_{y}$ is quadratic in $y \in T_{x} M$ at each point $x \in M$.

Put

$$
R_{j k l}^{i}(y):=\frac{1}{3} \frac{\partial}{\partial y^{j}}\left[\frac{\partial R_{k}^{i}}{\partial y^{l}}-\frac{\partial R_{l}^{i}}{\partial y^{k}}\right] .
$$

$R_{j k l}{ }^{i}$ are the coefficients of the h-curvature of the Berwald connection, which are also denoted by $H_{j}{ }^{i} k l$ in the literature. We have

$$
R_{k}^{i}(y)=y^{j} R_{j}^{i}{ }_{k l}(y) y^{l}
$$

Thus $R_{k}^{i}(y)$ is quadratic in $y \in T_{x} M$ if and only if $R_{j}{ }^{i}{ }_{k l}(y)$ are functions of $x$ only.
For a Finsler metric $F$ on an $n$-dimensional manifold $M$, the Busemann-Hausdorff volume form $d V_{F}=$ $\sigma_{F}(x) d x^{1} \cdots d x^{n}$ is defined by

$$
\sigma_{F}(x):=\frac{\operatorname{Vol}\left(\mathbb{B}^{n}(1)\right)}{\operatorname{Vol}\left\{\left(y^{i}\right) \in \mathbb{R}^{n} \left\lvert\, F\left(\left.y^{i} \frac{\partial}{\partial x^{i}}\right|_{x}\right)<1\right.\right\}}
$$

In general, the local scalar function $\sigma_{F}(x)$ cannot be expressed in terms of elementary functions, even if $F$ is locally expressed by elementary functions.

Let $G^{i}(x, y)$ denote the geodesic coefficients of $F$ in the same local coordinate system. The S-curvature is defined by

$$
\mathbf{S}(\mathbf{y}):=\frac{\partial G^{i}}{\partial y^{i}}(x, y)-y^{i} \frac{\partial}{\partial x^{i}}\left[\ln \sigma_{F}(x)\right]
$$

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where $\mathbf{y}=\left.y^{i} \frac{\partial}{\partial x^{i}}\right|_{x} \in T_{x} M$. It is proved that $\mathbf{S}=0$ if $F$ is a Berwald metric [8]. There are many non-Berwald metrics satisfying $\mathbf{S}=0$ [2].

Given a Riemannian metric $\alpha$, a 1 -form $\beta$ on a manifold $M$, and a $C^{\infty}$ function $\phi=\phi(s)$ on $\left[-b_{o}, b_{o}\right]$, where $b_{o}:=\sup _{x \in M}\|\beta\|_{x}$, one can define a function on $T M$ by

$$
F:=\alpha \phi(s), \quad s=\frac{\beta}{\alpha}
$$

If $\phi$ and $b_{o}$ satisfy (2.1) and (2.2) below, then $F$ is a Finsler metric on $M$. Finsler metrics in this form are called $(\alpha, \beta)$-metrics. Randers metrics are special $(\alpha, \beta)$-metrics.

Now we consider $(\alpha, \beta)$-metrics. Let $\alpha=\sqrt{a_{i j} y^{i} y^{j}}$ be a Riemannian metric and $\beta=b_{i} y^{i}$ a 1 -form on a manifod $M$. Let

$$
\|\beta\|_{x}:=\sqrt{a^{i j}(x) b_{i}(x) b_{j}(x)}
$$

For a $C^{\infty}$ function $\phi=\phi(s)$ on $\left[-b_{o}, b_{o}\right]$, where $b_{o}=\sup _{x \in M}\|\beta\|_{x}$, define

$$
F:=\alpha \phi(s), \quad s=\frac{\beta}{\alpha}
$$

By a direct computation, we obtain

$$
g_{i j}=\rho a_{i j}+\rho_{0} b_{i} b_{j}-\rho_{1}\left(b_{i} \alpha_{j}+b_{j} \alpha_{i}\right)+s \rho_{1} \alpha_{i} \alpha_{j}
$$

where $\alpha_{i}:=a_{i j} y^{j} / \alpha$, and

$$
\begin{aligned}
\rho & :=\phi\left(\phi-s \phi^{\prime}\right) \\
\rho_{0} & :=\phi \phi^{\prime \prime}+\phi^{\prime} \phi^{\prime} \\
\rho_{1} & :=s\left(\phi \phi^{\prime \prime}+\phi^{\prime} \phi^{\prime}\right)-\phi \phi^{\prime}
\end{aligned}
$$

By further computation, one obtains

$$
\operatorname{det}\left(g_{i j}\right)=\phi^{n+1}\left(\phi-s \phi^{\prime}\right)^{n-2}\left[\left(\phi-s \phi^{\prime}\right)+\left(\|\beta\|_{x}^{2}-s^{2}\right) \phi^{\prime \prime}\right] \operatorname{det}\left(a_{i j}\right)
$$

Using the continuity, one can easily show that

Lemma 1 Let $b_{o}>0$. $F=\alpha \phi(\beta / \alpha)$ is a Finsler metric on $M$ for any pair $\{\alpha, \beta\}$ with $\sup _{x \in M}\|\beta\|_{x} \leq b_{o}$ if and only if $\phi=\phi(s)$ satisfies the following conditions:

$$
\begin{gather*}
\phi(s)>0, \quad\left(|s| \leq b_{o}\right)  \tag{2.1}\\
\phi(s)-s \phi^{\prime}(s)+\left(b^{2}-s^{2}\right) \phi^{\prime \prime}(s)>0, \quad\left(|s| \leq b \leq b_{o}\right) . \tag{2.2}
\end{gather*}
$$

Let

$$
r_{i j}:=\frac{1}{2}\left(b_{i \mid j}+b_{j \mid i}\right), \quad s_{i j}:=\frac{1}{2}\left(b_{i \mid j}-b_{j \mid i}\right)
$$

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$$
r_{j}:=b^{i} r_{i j}, \quad s_{j}:=b^{i} s_{i j}
$$

Let $r_{i 0}:=r_{i j} y^{j}, s_{i 0}:=s_{i j} y^{j}, r_{0}:=r_{j} y^{j}$ and $s_{0}:=s_{j} y^{j}$. Suppose that $G^{i}=G^{i}(x, y)$ and $\bar{G}^{i}=\bar{G}^{i}(x, y)$ denote the coefficients of $F$ and $\alpha$ respectively in the same coordinate system. By definition, we obtain the following identity:

$$
\begin{equation*}
G^{i}=\bar{G}^{i}+P y^{i}+Q^{i} \tag{2.3}
\end{equation*}
$$

where

$$
\begin{aligned}
P & =\alpha^{-1} \Theta\left[r_{00}-2 Q \alpha s_{0}\right] \\
Q^{i} & =\alpha Q s^{i}{ }_{0}+\Psi\left[r_{00}-2 Q \alpha s_{0}\right] b^{i} \\
Q & =\frac{\phi^{\prime}}{\phi-s \phi^{\prime}} \\
\Theta & =\frac{\phi \phi^{\prime}-s\left(\phi \phi^{\prime \prime}+\phi^{\prime} \phi^{\prime}\right)}{2 \phi\left(\left(\phi-s \phi^{\prime}\right)+\left(b^{2}-s^{2}\right) \phi^{\prime \prime}\right)} \\
\Psi & =\frac{1}{2} \frac{\phi^{\prime \prime}}{\left(\phi-s \phi^{\prime}\right)+\left(b^{2}-s^{2}\right) \phi^{\prime \prime}}
\end{aligned}
$$

Clearly, if $\beta$ is parallel with respect to $\alpha\left(r_{i j}=0\right.$ and $\left.s_{i j}=0\right)$, then $P=0$ and $Q^{i}=0$. In this case, $G^{i}=\bar{G}^{i}$ are quadratic in $y$, and $F$ is a Berwald metric.

Now, let $\phi=\phi(s)$ be a positive $C^{\infty}$ function on $\left(-b_{0}, b_{0}\right)$. For a number $b \in\left[0, b_{0}\right)$, let

$$
\begin{equation*}
\Phi:=-\left(Q-s Q^{\prime}\right)\{n \Delta+1+s Q\}-\left(b^{2}-s^{2}\right)(1+s Q) Q^{\prime \prime} \tag{2.4}
\end{equation*}
$$

where

$$
\begin{equation*}
\Delta:=1+s Q+\left(b^{2}-s^{2}\right) Q^{\prime} \tag{2.5}
\end{equation*}
$$

Lemma 2 ([3]) Let $F=\alpha \phi(s), s=\frac{\beta}{\alpha}$ be a non-Riemannian $(\alpha, \beta)$-metric on a manifold and $b:=\left\|\beta_{x}\right\|_{\alpha}$. Suppose that $\phi \neq c_{1} \sqrt{1+c_{2} s^{2}}+c_{3} s$ for any constant $c_{1}>0, c_{2}$ and $c_{3}$. Then $F$ is of isotropic S-curvature, $\mathbf{S}=(n+1) c F$, if and only if one of the following holds:
(a) $\beta$ satisfies

$$
\begin{equation*}
r_{i j}=\varepsilon\left(b^{2} a_{i j}-b_{i} b_{j}\right), \quad s_{j}=0 \tag{2.6}
\end{equation*}
$$

where $\varepsilon=\varepsilon(x)$ is a scalar function, and $\phi=\phi(s)$ satisfies

$$
\begin{equation*}
\Phi=-2(n+1) k \frac{\phi \Delta^{2}}{b^{2}-s^{2}} \tag{2.7}
\end{equation*}
$$

where $k$ is a constant. In this case, $\mathbf{S}=(n+1) c F$ with $c=k \varepsilon$.
(b) $\beta$ satisfies

$$
\begin{equation*}
r_{i j}=0, \quad s_{j}=0 \tag{2.8}
\end{equation*}
$$

In this case, $\mathbf{S}=0$, regardless of choices of a particular $\phi$.

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## 3. Proof of Theorem 1

We have the following formula for the spray coefficient $G^{i}$ of $F$

$$
\begin{equation*}
G^{i}=G_{\alpha}^{i}+\alpha Q s_{0}^{i}+\left(-2 Q \alpha s_{0}+r_{00}\right)\left(\Theta \alpha^{-1} y^{i}+\Psi b^{i}\right) \tag{3.9}
\end{equation*}
$$

where $s_{j}^{i}:=a^{i h} s_{h j}, s_{0}^{i}:=s_{i} y^{i}, r_{00}=r_{i j} y^{i} y^{j}$ and

$$
\Theta=\frac{Q-s Q^{\prime}}{2 \Delta}, \quad \Psi=\frac{Q^{\prime}}{2 \Delta}
$$

By a direct computation, we can obtain a formula for the mean Cartan torsion of $(\alpha, \beta)$ - metrics as follows:

$$
\begin{equation*}
I_{i}=-\frac{\Phi\left(\phi-s \phi^{\prime}\right)}{2 \Delta \phi \alpha^{2}}\left(\alpha b_{i}-s y_{i}\right) \tag{3.10}
\end{equation*}
$$

According to Deickeğs theorem, a Finsler metric is Riemannian if and only if $\mathbf{I}=0$. Clearly, an $(\alpha, \beta)$-metric $F=\alpha \phi(s)$ is Riemannian if and only if $\Phi=0$.

In [5], Li and Shen obtained the mean Landsberg curvature of an $(\alpha, \beta)$-metric $F=\alpha \phi(s), s=\frac{\beta}{\alpha}$ as follows

$$
\begin{align*}
J_{i}= & -\frac{1}{\alpha^{2} \Delta\left(b^{2}-s^{2}\right)}\left[\frac{\Phi}{\Delta}+(n+1)\left(Q-s Q^{\prime}\right)\right]\left(r_{0}+s_{0}\right) h_{i} \\
& -\frac{h_{i}}{2 \alpha^{3} \Delta\left(b^{2}-s^{2}\right)}\left(\Psi_{1}+s \frac{\Phi}{\Delta}\right)\left(r_{00}-2 \alpha Q s_{0}\right) \\
& -\frac{\Phi}{2 \alpha^{3} \Delta^{2}}\left[-\alpha Q^{\prime} s_{0} h_{i}+\alpha Q\left(\alpha^{2} s_{i}-y_{i} s_{0}\right)+\alpha^{2} \Delta s_{i 0}\right. \\
& \left.+\alpha^{2}\left(r_{i 0}-2 \alpha Q s_{0}\right)-\left(r_{00}-2 \alpha Q s_{0}\right) y_{i}\right] \tag{3.11}
\end{align*}
$$

where $h_{i}:=\alpha b_{i}-s y_{i}$ and

$$
\Psi_{1}:=\sqrt{b^{2}-s^{2}} \Delta^{\frac{1}{2}}\left[\frac{\sqrt{b^{2}-s^{2}}}{\Delta^{\frac{3}{2}}}\right]^{\prime}
$$

They also obtained

$$
\begin{equation*}
\bar{J}:=J_{i} b^{i}=-\frac{\Delta}{2 \alpha^{2}}\left[\Psi_{1}\left(r_{00}-2 \alpha Q s_{0}\right)+\alpha \Psi_{2}\left(r_{0}+s_{0}\right)\right] \tag{3.12}
\end{equation*}
$$

where

$$
\Psi_{2}:=2(n+1)\left(Q-s Q^{\prime}\right)+3 \frac{\Phi}{\Delta}
$$

Lemma 3 Let $F=\alpha \phi(s), s=\frac{\beta}{\alpha}$ be $n$ non-Riemannian $(\alpha, \beta)$-metric on manifold $M$. Suppose that $\phi \neq c_{1} \sqrt{1+c_{2} s^{2}}+c_{3} s$ for any constant $c_{1}>0, c_{2}$.If $F$ has vanishing $S$-curvature and a weakly Landsberg metric then $F$ is a Berwald metric.

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Proof By (2.8) and (3.11) we have

$$
\begin{equation*}
J_{i}=-\frac{\Phi s_{i 0}}{2 \alpha \Delta} . \tag{3.13}
\end{equation*}
$$

From (3.13) we conclude if $F$ is weakly Landsberg then $s_{0}^{i}=0$ and because of $r_{00}=0, F$ is a Berwald metric.
Proof of Theorem 1 Let $F$ be a relatively isotropic mean Landsberg curvature metric with vanishing S-curvature. The following holds:

$$
\begin{equation*}
J_{k}+c F I_{k}=0 . \tag{3.14}
\end{equation*}
$$

By (2.8) and (3.12) we have $b_{i} J^{i}=0$. Multiplying (3.14) by $b^{k}$ yields

$$
\begin{equation*}
c F\left(b^{k} I_{k}\right)=0 . \tag{3.15}
\end{equation*}
$$

If $c \neq 0$ from (3.15) we have $b^{k} I_{k}=0$ and so by (3.10) we conclude

$$
\begin{equation*}
\frac{\Phi\left(\phi-s \phi^{\prime}\right)}{2 \Delta \phi \alpha^{3}}\left(b^{2} \alpha^{2}-\beta^{2}\right)=0 \tag{3.16}
\end{equation*}
$$

From (3.16) we conclude $\Phi=0$ or $\phi-s \phi^{\prime}=0$. Then by (3.10) we have $I=0$ and $F$ is a Riemannian metric. By assumption $F$ is a non-Riemannian metric and so $c=0$. From (3.14), we conclude $F$ is a weakly Landsberg metric. Then, by Lemma 3, $F$ is a Berwald metric. The proof of Theorem 1 is complete.

## 4. Proof of Theorem 2

Lemma 4 ([9]) For the Berwald connection, the following Bianchi identities hold:

$$
\begin{align*}
& R^{i}{ }_{j k l \mid m}+R^{i}{ }_{j l m \mid k}+R^{i}{ }_{j m k l l}=B^{i}{ }_{j k u} R^{u}{ }_{l m}+B^{i}{ }_{j l u} R^{u}{ }_{k m}+B^{i}{ }_{k l u} R^{u}{ }_{j m}  \tag{4.17}\\
& B^{i}{ }_{j m l \mid k}-B^{i}{ }_{j k m \mid l}=R^{i}{ }_{j k l, m}  \tag{4.18}\\
& B^{i}{ }_{j k l, m}=B^{i}{ }_{j k m, l} . \tag{4.19}
\end{align*}
$$

Lemma 5 Let $F=\alpha \phi(s)$, $s=\frac{\beta}{\alpha}$ be a non-Riemannian $(\alpha, \beta)$-metric on manifold $M$. Suppose that $\phi \neq c_{1} \sqrt{1+c_{2} s^{2}}+c_{3} s$ for any constant $c_{1}>0, c_{2}$ If $F$ has vanishing $S$-curvature then we have

$$
\begin{equation*}
b_{m} B_{j k l}^{m}=0 \tag{4.20}
\end{equation*}
$$

Proof By (2.8), we have $s_{0}=0$. By assumption $F$ has vanishing S curvature. By (2.8) and (3.9) we have

$$
\begin{equation*}
G^{i}=G_{\alpha}^{i}+\alpha Q s_{0}^{i} . \tag{4.21}
\end{equation*}
$$

Multiplying (4.21) by $b_{i}$ yields $b_{i} G^{i}=b_{i} G_{\alpha}^{i}$. Thus $b_{m} B_{j k l}^{m}=0$.
Proof of Theorem 2 According to Lemma 5, we have

$$
\begin{equation*}
b_{m \mid s} B_{j k l}^{m}+b_{m} B_{j k l \mid s}^{m}=0 . \tag{4.22}
\end{equation*}
$$

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By assumption $F$ is an R-quadratic metric. Thus (4.18) implies that

$$
\begin{equation*}
B_{j k l \mid m}^{i}-B_{j k m \mid l}^{i}=0 \tag{4.23}
\end{equation*}
$$

Multiplying (4.23) by $b_{i}$ yields

$$
\begin{equation*}
b_{i} B_{j k l \mid m}^{i}=b_{i} B_{j k m \mid l}^{i} \tag{4.24}
\end{equation*}
$$

From (4.22) and (4.24) we conclude

$$
\begin{equation*}
b_{i \mid m} B_{j k l}^{i}=b_{i \mid l} B_{j k m}^{i} \tag{4.25}
\end{equation*}
$$

Since $r_{i j}=0$, then by multiplying (4.25) by $y^{l}$ we obtain

$$
\begin{equation*}
s_{i 0} B_{j k m}^{i}=0 \tag{4.26}
\end{equation*}
$$

By (4.21) we get $B_{j k l}^{i}=\left[\alpha Q s_{0}^{i}\right]_{y^{j} y^{k} y^{l}}$. From (4.26) we have

$$
\begin{equation*}
[\alpha Q]_{y^{j} y^{k} y^{l}} s_{i 0} s_{0}^{i}+[\alpha Q]_{y^{j} y^{k}} s_{i 0} s_{l}^{i}+[\alpha Q]_{y^{j} y^{l}} s_{i 0} s_{k}^{i}+[\alpha Q]_{y^{k} y^{l}} s_{i 0} s_{j}^{i}=0 \tag{4.27}
\end{equation*}
$$

By (2.8), we have $s^{i}=s_{i}=0$. Then multiplying (4.27) by $b^{j} b^{k} b^{l}$ yields

$$
\begin{equation*}
\left[b^{j} b^{k} b^{l}[\alpha Q]_{y^{j} y^{k} y^{l}}\right] s_{i 0} s_{0}^{i}=0 \tag{4.28}
\end{equation*}
$$

Then by (4.28), we conclude that $\beta$ is a closed 1-form and then $F$ reduces to a Berwald metric. The proof of Theorem 2 is complete.

## 5. Proof of Theorem 3

In this section, we are going to prove Theorem 3. First, we remark the following.
Lemma 6 ([16]) Let $F=\alpha \phi(s), s=\frac{\beta}{\alpha}$, be a non-Riemannian $(\alpha, \beta)$-metric on a manifold $M$ of dimension $n \geq 3$, where $\phi^{\prime}(0) \neq 0$ and $\beta \neq 0$. Then $F$ is locally dually flat if and only if $\alpha, \beta$, and $\phi$ satisfy

$$
\begin{aligned}
& s_{l 0}=\frac{1}{3}\left(\beta \theta_{l}-\theta b_{l}\right) \\
& r_{00}=\frac{2}{3} \theta \beta+\left[\tau+\frac{2}{3}\left(b^{2} \tau-\theta_{l} b^{l}\right)\right] \alpha^{2}+\frac{1}{3}\left(3 k_{2}-2-3 k_{3} b^{2}\right) \tau \beta^{2} \\
& G_{\alpha}^{l}=\frac{1}{3}\left[2 \theta+\left(3 k_{1}-2\right) \tau \beta\right] y^{l}+\frac{1}{3}\left(\theta^{l}-\tau b^{l}\right) \alpha^{2}+\frac{1}{2} k_{3} \tau \beta^{2} b^{l} \\
& \tau\left[s\left(k_{2}-k_{3} s^{2}\right)\left(\phi \phi^{\prime}-s \phi^{\prime 2}-s \phi \phi^{\prime \prime}\right)-\left(\phi^{2}+\phi \phi^{\prime \prime}\right)+k_{1} \phi\left(\phi-s \phi^{\prime}\right)\right]=0
\end{aligned}
$$

where $\tau:=\tau(x)$ is a scalar function, $\theta:=\theta_{i}(x) y^{i}$ is a 1-form on $M, \theta^{l}=a^{l m} \theta_{m}$, and

$$
\begin{aligned}
& k_{1}:=\Pi(0), \quad k_{2}:=\frac{\Pi^{\prime}(0)}{Q(0)} \\
& k_{3}:=\frac{1}{6 Q(0)^{2}}\left[3 Q^{\prime \prime}(0) \Pi^{\prime}(0)-6 \Pi^{\prime}(0)^{2}-Q(0) \Pi^{\prime \prime \prime}(0)\right] \\
& \Pi:=\frac{\phi^{2}+\phi \phi^{\prime \prime}}{\phi\left(\phi-s \phi^{\prime}\right)}
\end{aligned}
$$

By Lemma 6, we can get the following.

Corollary 1 ([16]) Let $F=\alpha \phi(s), s=\frac{\beta}{\alpha}$ be an $(\alpha, \beta)$-metric on a manifold $M$ of dimension $n \geq 3$ with the same assumption as Lemma 6. Let $\phi$ satisfy

$$
s\left(k_{2}-k_{3} s^{2}\right)\left(\phi \phi^{\prime}-s \phi^{\prime}-s \phi \phi^{\prime \prime}\right)-\left(\phi^{2}+\phi \phi^{\prime \prime}\right)+k_{1} \phi\left(\phi-s \phi^{\prime}\right) \neq 0
$$

Then $F$ is locally dually flat on $M$ if and only if

$$
\begin{align*}
s_{l 0} & =\frac{1}{3}\left(\beta \theta_{l}-\theta b_{l}\right)  \tag{5.29}\\
r_{00} & =\frac{2}{3}\left[\theta \beta-\left(\theta_{l} b^{l}\right) \alpha^{2}\right]  \tag{5.30}\\
G_{\alpha}^{l} & =\frac{1}{3}\left[2 \theta y^{l}+\theta^{l} \alpha^{2}\right] \tag{5.31}
\end{align*}
$$

where $k_{i} \quad(1 \leq i \leq 3)$ are the same as those of Theorem 6 .
In [16], Xia proved the following.

Lemma 7 ([16]) Let $F:=\alpha \phi(s), s=\frac{\beta}{\alpha}$ be a non-Riemannian $(\alpha, \beta)-$ metric on a manifold $M$ of dimension $n \geq 3$. Suppose that $\phi(s)$ is an analytic function with $\phi^{\prime}(0)=\phi^{\prime \prime}(0)=0$ or $\phi(s)$ is a polynomial of s with $\phi^{\prime}(0)=0$ and $\beta=b_{i}(x) y^{i} \neq 0$. Then $F$ is locally dually flat if and only if $\alpha$ and $\beta$ satisfy (5.29), (5.30) and (5.31), where $\theta=\theta_{i}(x) y^{i}$ is a 1 -form on $M$ and $\theta^{l}:=a^{l m} \theta_{m}$.

Proof of Theorem 3 To prove Theorem 3, we consider some cases.
Case (1): $\phi^{\prime}(0)=\phi^{\prime \prime}(0)=0$ or $\phi(s)$ is a polynomial of $s$ with $\phi^{\prime}(0)=0$. In this case, by Lemma 7 we have

$$
\begin{align*}
s_{l 0} & =\frac{1}{3}\left(\beta \theta_{l}-\theta b_{l}\right)  \tag{5.32}\\
r_{00} & =\frac{2}{3}\left[\theta \beta-\left(\theta_{l} b^{l}\right) \alpha^{2}\right]  \tag{5.33}\\
G_{\alpha}^{l} & =\frac{1}{3}\left[2 \theta y^{l}+\theta^{l} \alpha^{2}\right] \tag{5.34}
\end{align*}
$$

Since $s_{0}=0$ then (5.32) reduces to the following:

$$
\begin{equation*}
\theta=\frac{b^{l} \theta_{l}}{b^{2}} \beta \tag{5.35}
\end{equation*}
$$

Plugging (5.35) into (5.33) implies that

$$
\begin{equation*}
r_{00}=\frac{\left(b^{l} \theta_{l}\right)}{b^{2}}\left[\beta^{2}-b^{2} \alpha^{2}\right] \tag{5.36}
\end{equation*}
$$

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By (2.8), we have $r_{00}=0$. By (5.36), we get $b^{l} \theta_{l}=0$ and by (5.35) we have $\theta=0$. Then $G_{\alpha}^{l}=0$ and $s_{0}^{l}=0$. So $G^{l}=0$ and $F$ is a locally Minkowski metric.

Case(2): $\phi^{\prime}(0) \neq 0$ such that

$$
s\left(k_{2}-k_{3} s^{2}\right)\left(\phi \phi^{\prime}-s \phi^{\prime}-s \phi \phi^{\prime \prime}\right)-\left(\phi^{2}+\phi \phi^{\prime \prime}\right)+k_{1} \phi\left(\phi-s \phi^{\prime}\right) \neq 0
$$

According to Corollary 1, the proof of this case is similar to the proof of case (1).
Case(3): $\phi^{\prime}(0) \neq 0$ such that

$$
s\left(k_{2}-k_{3} s^{2}\right)\left(\phi \phi^{\prime}-s \phi^{\prime}-s \phi \phi^{\prime \prime}\right)-\left(\phi^{2}+\phi \phi^{\prime \prime}\right)+k_{1} \phi\left(\phi-s \phi^{\prime}\right)=0
$$

According to Lemma 6, we have

$$
\begin{align*}
s_{l 0} & =\frac{1}{3}\left(\beta \theta_{l}-\theta b_{l}\right)  \tag{5.37}\\
r_{00} & =\frac{2}{3} \theta \beta+\left[\tau+\frac{2}{3}\left(b^{2} \tau-\theta_{l} b^{l}\right)\right] \alpha^{2}+\frac{1}{3}\left(3 k_{2}-2-3 k_{3} b^{2}\right) \tau \beta^{2}  \tag{5.38}\\
G_{\alpha}^{l} & =\frac{1}{3}\left[2 \theta+\left(3 k_{1}-2\right) \tau \beta\right] y^{l}+\frac{1}{3}\left(\theta^{l}-\tau b^{l}\right) \alpha^{2}+\frac{1}{2} k_{3} \tau \beta^{2} b^{l} \tag{5.39}
\end{align*}
$$

By (2.8) we have $s_{0}=0$. Thus (5.37) implies that

$$
\begin{equation*}
\theta=\frac{\left(b^{l} \theta_{l}\right)}{b^{2}} \beta \tag{5.40}
\end{equation*}
$$

Plugging (5.40) into (5.38) we obtain

$$
\begin{equation*}
r_{00}=\frac{2}{3} \frac{\left(b^{l} \theta_{l}\right)}{b^{2}} \beta^{2}+\left[\tau+\frac{2}{3}\left(b^{2} \tau-\theta_{l} b^{l}\right)\right] \alpha^{2}+\frac{1}{3}\left(3 k_{2}-2-3 k_{3} b^{2}\right) \tau \beta^{2} \tag{5.41}
\end{equation*}
$$

By (2.8), since $r_{00}=0$ then (5.41) reduces to the following:

$$
\begin{equation*}
\frac{2}{3} \frac{\left(b^{l} \theta_{l}\right)}{b^{2}} \beta^{2}+\left[\tau+\frac{2}{3}\left(b^{2} \tau-\theta_{l} b^{l}\right)\right] \alpha^{2}+\frac{1}{3}\left(3 k_{2}-2-3 k_{3} b^{2}\right) \tau \beta^{2}=0 \tag{5.42}
\end{equation*}
$$

Differentiating (5.42) with respect to $y^{m}$ yields

$$
\begin{equation*}
\frac{4}{3} \frac{\left(b^{l} \theta_{l}\right)}{b^{2}} \beta b_{m}+2\left[\tau+\frac{2}{3}\left(b^{2} \tau-\theta_{l} b^{l}\right)\right] y_{m}+\frac{2}{3}\left(3 k_{2}-2-3 k_{3} b^{2}\right) \tau \beta b_{m}=0 \tag{5.43}
\end{equation*}
$$

By multiplying (5.43) by $b^{m}$ we get

$$
\begin{equation*}
2\left[\left(k_{2}-k_{3} b^{2}\right) b^{2}+1\right] \tau \beta=0 \tag{5.44}
\end{equation*}
$$

By assumption, we have $\left(k_{2}-k_{3} b^{2}\right) b^{2}+1 \neq 0$. Then $\tau=0$. Plugging $\tau=0$ into (5.37), (5.38), and (5.39) yields (5.29), (5.30), and (5.31). Thus the proof of Theorem in this case is similar to the first case. This completes the proof.

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