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# Variational problem involving operator curl associated with $p$-curl system 

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#### Abstract

We shall study the problem of minimizing a functional involving curl of vector fields in a three-dimensional, bounded multiconnected domain with the prescribed tangent component of a given vector field on the boundary. It will be seen that the minimizers are weak solutions of the $p$-curl type system. We shall prove the existence and the estimate of minimizers of a more general functional that contains the $L^{p}$ norm of the curl of vector fields. We shall also give the continuity with respect to the given data.


Key words: Variational problem, p-curl system, multiconnected domain

## 1. Introduction

In this paper we shall consider the variational problem

$$
\inf \left\{\frac{1}{2} \int_{\Omega} S\left(x,|\operatorname{curl} \boldsymbol{u}|^{2}\right) d x-\int_{\Omega} \boldsymbol{f} \cdot \boldsymbol{u} d x\right\}
$$

where $S(x, t)$ satisfies some structure condition, $\boldsymbol{f}$ is a given vector field, and the minimization is taken in an appropriate space with tangent trace on the boundary being prescribed. The structure condition contains $S(x, t)=t^{p / 2}(1<p<\infty)$ as a typical example. In this case, if $\boldsymbol{f}=\mathbf{0}$, the problem

$$
\inf \int_{\Omega}|\operatorname{curl} \boldsymbol{u}|^{p} d x
$$

was proposed by Pan [12, p. 9].
This problem is related to the mathematical theory of liquid crystals, of superconductivity, and of electromagnetic fields. See, for example, Bates and Pan [5], Pan and Qi [13], and Miranda et al. [11].

When $p=2, \boldsymbol{f}=\mathbf{0}, S(x, t)=t$, and $\Omega$ is a simply connected domain without holes, the authors of [5] showed the existence of a minimizer. For the multiconnected domain, the author of [12] obtained the existence of a minimizer to minimization problem (1.4) below in this case.

More precisely, let $S(x, t)$ be a Carathéodory function on $\Omega \times[0, \infty)$ and $S\left(x, t^{2}\right)$ be a convex function with respect to $t$. Moreover, assume that for a.e. $x \in \Omega, S(x, t) \in C^{1}((0, \infty))$ and there exist $1<p<\infty$ and $\lambda, \Lambda>0$ such that for a.e. $x \in \Omega$ and all $t>0$,

$$
\begin{equation*}
\lambda t^{(p-2) / 2} \leq S_{t}(x, t):=\frac{\partial}{\partial t} S(x, t) \leq \Lambda t^{(p-2) / 2} \tag{1.1}
\end{equation*}
$$

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## ARAMAKI/Turk J Math

Without loss of generality, we may assume that $S(x, 0)=0$. We furthermore assume the following structure condition:

$$
\begin{equation*}
\left(S_{t}\left(x,|\boldsymbol{a}|^{2}\right) \boldsymbol{a}-S_{t}\left(x,|\boldsymbol{b}|^{2}\right) \boldsymbol{b}\right) \cdot(\boldsymbol{a}-\boldsymbol{b})>0 \tag{1.2}
\end{equation*}
$$

for any $\boldsymbol{a}, \boldsymbol{b} \in \mathbb{R}^{3}$ with $\boldsymbol{a} \neq \boldsymbol{b}$. Here, for any vectors $\boldsymbol{a}, \boldsymbol{b} \in \mathbb{R}^{3}, \boldsymbol{a} \cdot \boldsymbol{b}$ denotes the Euclidean inner product. Under (1.1) with $S(x, 0)=0$, we have

$$
\begin{equation*}
\frac{2}{p} \lambda t^{p / 2} \leq S(x, t) \leq \frac{2}{p} \Lambda t^{p / 2} \tag{1.3}
\end{equation*}
$$

For example, the function $S(x, t)=\nu(x) t^{p / 2}$ where $\nu(x)$ is a measurable function satisfying $0<\nu_{*} \leq$ $\nu(x) \leq \nu^{*}<\infty$ for a.e. $x \in \Omega$ satisfies (1.1)-(1.2).

Let $\Omega$ be a bounded domain in $\mathbb{R}^{3}$ with $C^{r}$ boundary $\partial \Omega(r \geq 2)$. Let $\mathcal{H}$ be a given vector field on $\partial \Omega$ and $\mathcal{H}_{T}$ be the tangential component of $\mathcal{H}$. Let $W^{1, p}\left(\Omega, \mathbb{R}^{3}\right)$ be the standard Sobolev space of vector fields. From now on, we denote the tangential component of a vector field $\boldsymbol{u}$ by $\boldsymbol{u}_{T}$; that is, $\boldsymbol{u}_{T}=\boldsymbol{u}-(\boldsymbol{u} \cdot \boldsymbol{\nu}) \boldsymbol{\nu}$ where $\boldsymbol{\nu}$ is the outer normal unit vector to the boundary $\partial \Omega$. For any given vector field

$$
\mathcal{H}_{T} \in W^{1-1 / p, p}\left(\partial \Omega, \mathbb{R}^{3}\right)
$$

define a space of vector fields

$$
W_{t}^{1, p}\left(\Omega, \mathbb{R}^{3}, \mathcal{H}_{T}\right)=\left\{\boldsymbol{u} \in W^{1, p}\left(\Omega, \mathbb{R}^{3}\right) ; \boldsymbol{u}_{T}=\mathcal{H}_{T} \text { on } \partial \Omega\right\}
$$

Then it is clear that $W_{t}^{1, p}\left(\Omega, \mathbb{R}^{3}, \mathcal{H}_{T}\right)$ is a closed convex set in $W^{1, p}\left(\Omega, \mathbb{R}^{3}\right)$. We consider the minimization problem

$$
\begin{equation*}
R_{t}^{p}\left(\mathcal{H}_{T}, \boldsymbol{f}\right)=\inf _{\boldsymbol{u} \in W_{t}^{1, p}\left(\Omega, \mathbb{R}^{3}, \mathcal{H}_{T}\right)}\left\{\frac{1}{2} \int_{\Omega} S\left(x,|\operatorname{curl} \boldsymbol{u}|^{2}\right) d x-\int_{\Omega} \boldsymbol{f} \cdot \boldsymbol{u} d x\right\} \tag{1.4}
\end{equation*}
$$

where $\boldsymbol{f} \in L^{p^{\prime}}\left(\Omega, \mathbb{R}^{3}\right)$ is given. Here $p^{\prime}$ is the conjugate exponent of $p$; that is, $(1 / p)+\left(1 / p^{\prime}\right)=1$. When $p=2, S(x, t)=t, f=\mathbf{0}$, and $\Omega$ is a simply connected domain without holes, the authors of [5] showed that (1.4) is achieved, and then in the same case and when $\Omega$ is a bounded multiconnected domain, the author of [12] succeeded to show the existence of a minimizer of (1.4) and got an estimate of the minimizer.

Since we allow $\Omega$ to be a multiconnected domain in $\mathbb{R}^{3}$, throughout this paper, we assume that the domain $\Omega$ satisfies the following (O1) and (O2) (cf. Dautray and Lions [6] and Amrouche and Seloula [2]).
(O1) $\Omega$ is a bounded domain in $\mathbb{R}^{3}$ with $C^{r}(r \geq 2)$ boundary $\partial \Omega . \Omega$ is locally situated on one side of $\partial \Omega, \partial \Omega$ has a finite number of connected components $\Gamma_{1}, \ldots, \Gamma_{m+1}(m \geq 0)$, and $\Gamma_{m+1}$ denotes the boundary of the infinite connected component of $\mathbb{R}^{3} \backslash \bar{\Omega}$.
(O2) There exist $n$ manifolds of dimension 2 and of class $C^{r}$ denoted by $\Sigma_{1}, \ldots, \Sigma_{n}(n \geq 0)$ such that $\Sigma_{i} \cap \Sigma_{j}=\emptyset(i \neq j)$ and they are nontangential to $\partial \Omega$ and such that $\Omega \backslash\left(\cup_{i=1}^{n} \Sigma_{i}\right)$ is simply connected and pseudo $C^{1,1}$.

The number $n$ is called the first Betti number and $m$ the second Betti number of $\Omega$. We say that $\Omega$ is simply connected if $n=0$, and $\Omega$ has no holes if $m=0$. If we define the spaces

$$
\mathbb{K}_{N}^{p}(\Omega)=\left\{\boldsymbol{u} \in L^{p}\left(\Omega, \mathbb{R}^{3}\right) ; \operatorname{curl} \boldsymbol{u}=\mathbf{0}, \operatorname{div} \boldsymbol{u}=0 \text { in } \Omega, \boldsymbol{\nu} \cdot \boldsymbol{u}=0 \text { on } \partial \Omega\right\}
$$

## ARAMAKI/Turk J Math

and

$$
\mathbb{K}_{T}^{p}(\Omega)=\left\{\boldsymbol{u} \in L^{p}\left(\Omega, \mathbb{R}^{3}\right) ; \operatorname{curl} \boldsymbol{u}=\mathbf{0}, \operatorname{div} \boldsymbol{u}=0 \text { in } \Omega, \boldsymbol{u}_{T}=\mathbf{0} \text { on } \partial \Omega\right\}
$$

then it is well known that $\operatorname{dim} \mathbb{K}_{N}^{p}(\Omega)=n$ and $\operatorname{dim} \mathbb{K}_{T}^{p}(\Omega)=m$. We note that $\mathbb{K}_{N}^{p}(\Omega)$ and $\mathbb{K}_{T}^{p}(\Omega)$ are contained in $W^{1, p}\left(\Omega, \mathbb{R}^{3}\right)$; moreover, $\mathbb{K}_{N}^{p}(\Omega)$ and $\mathbb{K}_{T}^{p}(\Omega)$ are closed subspaces of $W^{1, p}\left(\Omega, \mathbb{R}^{3}\right)$. It will be shown in Lemma 2.3 below that $\mathbb{K}_{N}^{p}(\Omega)$ and $\mathbb{K}_{T}^{p}(\Omega)$ are also closed subspaces of $L^{p}\left(\Omega, \mathbb{R}^{3}\right)$. Thus, since $\mathbb{K}_{T}^{p}(\Omega)$ is a finite dimensional closed subspace of $L^{p}\left(\Omega, \mathbb{R}^{3}\right), \mathbb{K}_{T}^{p}(\Omega)$ has a complement $\mathbb{L}^{p}$ in $L^{p}\left(\Omega, \mathbb{R}^{3}\right)$; that is, $\mathbb{L}^{p}$ is a closed subspace of $L^{p}\left(\Omega, \mathbb{R}^{3}\right), \mathbb{L}^{p} \cap \mathbb{K}_{T}^{p}(\Omega)=\{\mathbf{0}\}$, and $L^{p}\left(\Omega, \mathbb{R}^{3}\right)=\mathbb{L}^{p} \oplus \mathbb{K}_{T}^{p}(\Omega)$ (the direct sum). Therefore, for any $\boldsymbol{w} \in L^{p}\left(\Omega, \mathbb{R}^{3}\right)$, there exist uniquely $\boldsymbol{v} \in \mathbb{L}^{p}$ and $\boldsymbol{u} \in \mathbb{K}_{T}^{p}(\Omega)$ such that $\boldsymbol{w}=\boldsymbol{v}+\boldsymbol{u}$. We denote the projection $P: L^{p}\left(\Omega, \mathbb{R}^{3}\right) \rightarrow \mathbb{L}^{p}$ by $P \boldsymbol{w}=\boldsymbol{v}$.

Define

$$
\begin{aligned}
H^{p}(\Omega, \operatorname{curl}, \operatorname{div} 0)= & \left\{\boldsymbol{u} \in L^{p}\left(\Omega, \mathbb{R}^{3}\right) ; \operatorname{curl} \boldsymbol{u} \in L^{p}\left(\Omega, \mathbb{R}^{3}\right)\right. \\
& \operatorname{div} \boldsymbol{u}=0 \operatorname{in} \Omega\} \\
H_{t}^{p}\left(\Omega, \operatorname{curl}, \operatorname{div} 0, \mathcal{H}_{T}\right)= & \left\{\boldsymbol{u} \in H^{p}(\Omega, \operatorname{curl}, \operatorname{div} 0) ; \boldsymbol{u}_{T}=\mathcal{H}_{T} \text { on } \partial \Omega\right\} .
\end{aligned}
$$

Note that if $\boldsymbol{u} \in L^{p}\left(\Omega, \mathbb{R}^{3}\right)$ and $\operatorname{curl} \boldsymbol{u} \in L^{p}\left(\Omega, \mathbb{R}^{3}\right)$, then the tangent trace $\boldsymbol{u}_{T}$ is well defined as an element of $W^{-1 / p, p}\left(\partial \Omega, \mathbb{R}^{3}\right)(\mathrm{cf}.[2$, p. 45$])$, and

$$
H^{p}(\Omega, \operatorname{curl}, \operatorname{div} 0) \cap W^{1, p}\left(\Omega, \mathbb{R}^{3}\right)=\left\{\boldsymbol{u} \in W^{1, p}\left(\Omega, \mathbb{R}^{3}\right) ; \operatorname{div} \boldsymbol{u}=0 \text { in } \Omega\right\}
$$

Moreover, we note that if $\mathcal{H}_{T} \in W^{1-1 / p, p}\left(\partial \Omega, \mathbb{R}^{3}\right)$, then

$$
H_{t}^{p}\left(\Omega, \operatorname{curl}, \operatorname{div} 0, \mathcal{H}_{T}\right) \subset W_{t}^{1, p}\left(\Omega, \mathbb{R}^{3}, \mathcal{H}_{T}\right)
$$

(cf. Amrouche and Seloula [1, Theorem 2.3]). We will see, in Lemma 2.1 of Section 2, that

$$
\begin{equation*}
R_{t}^{p}\left(\mathcal{H}_{T}, \boldsymbol{f}\right)=\inf _{\boldsymbol{v} \in H_{t}^{p}\left(\Omega, \operatorname{curl}, \operatorname{div} 0, \mathcal{H}_{T}\right)}\left\{\frac{1}{2} \int_{\Omega} S\left(x,|\operatorname{curl} \boldsymbol{v}|^{2}\right) d x-\int_{\Omega} \boldsymbol{f} \cdot \boldsymbol{v} d x\right\} \tag{1.5}
\end{equation*}
$$

We are in a position to state the main theorem.

Theorem 1.1 Let $\Omega \subset \mathbb{R}^{3}$ be a bounded domain satisfying (O1) and (O2) with $r \geq 2$, and let $\mathcal{H}_{T} \in$ $W^{1-1 / p, p}\left(\partial \Omega, \mathbb{R}^{3}\right)$ and $\boldsymbol{f} \in L^{p^{\prime}}\left(\Omega, \mathbb{R}^{3}\right)$ satisfying $\operatorname{div} \boldsymbol{f}=0$ and $\int_{\Omega} \boldsymbol{f} \cdot \boldsymbol{z} d x=0$ for all $\boldsymbol{z} \in \mathbb{K}_{T}^{p}(\Omega)$. Then $R_{t}^{p}\left(\mathcal{H}_{T}, \boldsymbol{f}\right)$ is achieved, and the minimizers $\boldsymbol{A}$ of $R_{t}^{p}\left(\mathcal{H}_{T}, \boldsymbol{f}\right)$ in the space $H_{t}^{p}\left(\Omega, \operatorname{curl}\right.$, div $\left.0, \mathcal{H}_{T}\right)$ satisfy the following estimate. There exists a constant $C=C(\Omega)>0$ independent of $\mathcal{H}_{T}$ such that

$$
\|P \boldsymbol{A}\|_{W^{1, p}(\Omega)} \leq C\left(\left\|\mathcal{H}_{T}\right\|_{W^{1-1 / p, p}(\partial \Omega)}+\|\boldsymbol{f}\|_{L^{p^{\prime}}(\Omega)}\right)
$$

This paper is organized as follows. In Section 2, we give some preliminaries. Section 3 is devoted to the proof of Theorem 1.1. In Section 4, we consider the continuous dependence on the data of the minimizers.

## 2. Preliminaries

In this section, we shall give some lemmas as preliminaries.

Lemma 2.1 Let $\mathcal{H}_{T} \in W^{1-1 / p, p}\left(\partial \Omega, \mathbb{R}^{3}\right)$ and $\boldsymbol{f} \in L^{p^{\prime}}\left(\Omega, \mathbb{R}^{3}\right)$ satisfying $\operatorname{div} \boldsymbol{f}=0$ in $\Omega$. Then $R_{t}^{p}\left(\mathcal{H}_{T}, \boldsymbol{f}\right)$ defined by (1.4) satisfies (1.5) ; that is to say, we have

$$
R_{t}^{p}\left(\mathcal{H}_{T}, \boldsymbol{f}\right)=\inf _{\boldsymbol{v} \in H_{t}^{p}\left(\Omega, \operatorname{curl}, \operatorname{div} 0, \mathcal{H}_{T}\right)}\left\{\frac{1}{2} \int_{\Omega} S\left(x,|\operatorname{curl} \boldsymbol{v}|^{2}\right) d x-\int_{\Omega} \boldsymbol{f} \cdot \boldsymbol{v} d x\right\} .
$$

Proof Put

$$
\begin{aligned}
\alpha & =\inf _{\boldsymbol{u} \in W_{t}^{1, p}\left(\Omega, \mathbb{R}^{3}, \mathcal{H}_{T}\right)}\left\{\frac{1}{2} \int_{\Omega} S\left(x,|\operatorname{curl} \boldsymbol{u}|^{2}\right) d x-\int_{\Omega} \boldsymbol{f} \cdot \boldsymbol{u} d x\right\} \\
\beta & =\inf _{\boldsymbol{v} \in H_{t}^{p}\left(\Omega, \operatorname{curl}, \operatorname{div} 0, \mathcal{H}_{T}\right)}\left\{\frac{1}{2} \int_{\Omega} S\left(x,|\operatorname{curl} \boldsymbol{v}|^{2}\right) d x-\int_{\Omega} \boldsymbol{f} \cdot \boldsymbol{v} d x\right\} .
\end{aligned}
$$

Since $H_{t}^{p}\left(\Omega, \operatorname{curl}, \operatorname{div} 0, \mathcal{H}_{T}\right) \subset W_{t}^{1, p}\left(\Omega, \mathbb{R}^{3}, \mathcal{H}_{T}\right)$, it is trivial that $\alpha \leq \beta$. For any $\boldsymbol{u} \in W^{1, p}\left(\Omega, \mathbb{R}^{3}, \mathcal{H}_{T}\right)$, the following Dirichlet problem

$$
\begin{cases}\Delta \varphi=\operatorname{div} \boldsymbol{u} & \text { in } \Omega \\ \varphi=0 & \text { on } \partial \Omega\end{cases}
$$

has a unique solution $\varphi \in W^{2, p}(\Omega)$ (cf. Girault and Raviart [10, Theorem 1.8]). If we define $\boldsymbol{v}=\boldsymbol{u}-\nabla \varphi \in$ $W^{1, p}\left(\Omega, \mathbb{R}^{3}\right)$, then curl $\boldsymbol{v}=\operatorname{curl} \boldsymbol{u}, \operatorname{div} \boldsymbol{v}=\operatorname{div} \boldsymbol{u}-\Delta \varphi=0$ in $\Omega$ and $\boldsymbol{v}_{T}=\boldsymbol{u}_{T}-(\nabla \varphi)_{T}=\boldsymbol{u}_{T}=\mathcal{H}_{T}$. Thus, $\boldsymbol{v} \in H_{t}^{p}\left(\Omega, \operatorname{curl}, \operatorname{div} 0, \mathcal{H}_{T}\right)$. Moreover, since $\operatorname{div} \boldsymbol{f}=0$ in $\Omega$ and $\varphi=0$ on $\partial \Omega$, we have

$$
\begin{aligned}
\int_{\Omega} \boldsymbol{f} \cdot \boldsymbol{u} d x & =\int_{\Omega} \boldsymbol{f} \cdot \boldsymbol{v} d x+\int_{\Omega} \boldsymbol{f} \cdot \nabla \varphi d x \\
& =\int_{\Omega} \boldsymbol{f} \cdot \boldsymbol{v} d x-\int_{\Omega}(\operatorname{div} \boldsymbol{f}) \varphi d x+\int_{\partial \Omega}(\boldsymbol{f} \cdot \boldsymbol{\nu}) \varphi d S \\
& =\int_{\Omega} \boldsymbol{f} \cdot \boldsymbol{v} d x
\end{aligned}
$$

Therefore, we have

$$
\frac{1}{2} \int_{\Omega} S\left(x,|\operatorname{curl} \boldsymbol{u}|^{2}\right) d x-\int_{\Omega} \boldsymbol{f} \cdot \boldsymbol{u} d x=\frac{1}{2} \int_{\Omega} S\left(x,|\operatorname{curl} \boldsymbol{v}|^{2}\right) d x-\int_{\Omega} \boldsymbol{f} \cdot \boldsymbol{v} d x \geq \beta
$$

Thus, we have $\alpha \geq \beta$.
By Lemma 2.1, the minimization problem (1.4) reduces to the following problem.
Find the minimizer $\boldsymbol{u} \in H_{t}^{p}\left(\Omega, \operatorname{curl}, \operatorname{div} 0, \mathcal{H}_{T}\right)$ such that

$$
\begin{equation*}
R_{t}^{p}\left(\mathcal{H}_{T}, \boldsymbol{f}\right)=\inf _{\boldsymbol{v} \in H_{t}^{p}\left(\Omega, \operatorname{curl}, \operatorname{div} 0, \mathcal{H}_{T}\right)}\left\{\frac{1}{2} \int_{\Omega} S\left(x,|\operatorname{curl} \boldsymbol{v}|^{2}\right) d x-\int_{\Omega} \boldsymbol{f} \cdot \boldsymbol{v} d x\right\} . \tag{2.1}
\end{equation*}
$$

In the sequel, we frequently use the following lemma.
Lemma 2.2 (i) If $\boldsymbol{u} \in L^{p}\left(\Omega, \mathbb{R}^{3}\right)$, $\operatorname{curl} \boldsymbol{u} \in L^{p}\left(\Omega, \mathbb{R}^{3}\right)$, $\operatorname{div} \boldsymbol{u} \in L^{p}(\Omega)$, and $\boldsymbol{u} \cdot \boldsymbol{\nu} \in W^{1-1 / p, p}(\partial \Omega)$, then $\boldsymbol{u} \in W^{1, p}\left(\Omega, \mathbb{R}^{3}\right)$, and there exists a constant $c_{1}(\Omega)>0$ such that

$$
\begin{equation*}
\|\boldsymbol{u}\|_{W^{1, p}(\Omega)} \leq c_{1}(\Omega)\left(\|\boldsymbol{u}\|_{L^{p}(\Omega)}+\|\operatorname{curl} \boldsymbol{u}\|_{L^{p}(\Omega)}+\|\operatorname{div} \boldsymbol{u}\|_{L^{p}(\Omega)}+\|\boldsymbol{u} \cdot \boldsymbol{\nu}\|_{W^{1-1 / p, p}(\partial \Omega)}\right) \tag{2.2}
\end{equation*}
$$

## ARAMAKI/Turk J Math

Here we note that if furthermore $\Omega$ is simply connected, we can delete the first term $\|\boldsymbol{u}\|_{L^{p}(\Omega)}$ in the right-hand side of (2.2).
(ii) If $\boldsymbol{u} \in L^{p}\left(\Omega, \mathbb{R}^{3}\right)$, $\operatorname{curl} \boldsymbol{u} \in L^{p}\left(\Omega, \mathbb{R}^{3}\right)$, $\operatorname{div} \boldsymbol{u} \in L^{p}(\Omega)$, and $\boldsymbol{u}_{T} \in W^{1-1 / p, p}\left(\partial \Omega, \mathbb{R}^{3}\right)$, then $\boldsymbol{u} \in$ $W^{1, p}\left(\Omega, \mathbb{R}^{3}\right)$, and there exists a constant $c_{2}(\Omega)>0$ such that

$$
\begin{equation*}
\|\boldsymbol{u}\|_{W^{1, p}(\Omega)} \leq c_{2}(\Omega)\left(\|\boldsymbol{u}\|_{L^{p}(\Omega)}+\|\operatorname{curl} \boldsymbol{u}\|_{L^{p}(\Omega)}+\|\operatorname{div} \boldsymbol{u}\|_{L^{p}(\Omega)}+\left\|\boldsymbol{u}_{T}\right\|_{W^{1-1 / p, p}(\partial \Omega)}\right) \tag{2.3}
\end{equation*}
$$

We note that if furthermore $\Omega$ has no holes, we can delete the first term $\|\boldsymbol{u}\|_{L^{p}(\Omega)}$ in the right-hand side of (2.3).

For the proof of (2.2) and (2.3), see [2, Theorem 3.4 and Corollary 5.2]. If $\Omega$ is simply connected or has no holes, we can see the deletion of $\|\boldsymbol{u}\|_{L^{p}(\Omega)}$ from (2.3) or (2.4) in Aramaki's work [4, Lemma 2.2].

Lemma 2.3 The space $\mathbb{K}_{T}^{p}(\Omega)$ is a closed subspace of $L^{p}\left(\Omega, \mathbb{R}^{3}\right)$.
Proof Let $\mathbb{K}_{T}^{p}(\Omega) \ni \boldsymbol{u}_{j} \rightarrow \boldsymbol{u}$ in $L^{p}\left(\Omega, \mathbb{R}^{3}\right)$. Then from (2.3) we have

$$
\left\|\boldsymbol{u}_{j}-\boldsymbol{u}_{k}\right\|_{W^{1, p}(\Omega)} \leq c_{2}(\Omega)\left\|\boldsymbol{u}_{j}-\boldsymbol{u}_{k}\right\|_{L^{p}(\Omega)}
$$

Therefore, $\left\{\boldsymbol{u}_{j}\right\}$ is a Cauchy sequence in $W^{1, p}\left(\Omega, \mathbb{R}^{3}\right)$. Hence, there exists $\boldsymbol{u}_{0} \in W^{1, p}\left(\Omega, \mathbb{R}^{3}\right)$ such that $\boldsymbol{u}_{j} \rightarrow \boldsymbol{u}_{0}$ in $W^{1, p}\left(\Omega, \mathbb{R}^{3}\right)$, so we have $\boldsymbol{u}=\boldsymbol{u}_{0}$ and $\boldsymbol{u}_{j} \rightarrow \boldsymbol{u}$ in $W^{1, p}\left(\Omega, \mathbb{R}^{3}\right)$ as $j \rightarrow \infty$. It is clear that curl $\boldsymbol{u}=\mathbf{0}, \operatorname{div} \boldsymbol{u}=0$ in $\Omega$, and $\boldsymbol{u}_{T}=\mathbf{0}$ on $\partial \Omega$. This implies that $\boldsymbol{u} \in \mathbb{K}_{T}^{p}(\Omega)$.

## 3. Proof of the main Theorem 1.1

In this section, we give a proof of Theorem 1.1. The proof consists of some lemmas and propositions.
Lemma 3.1 Let $\boldsymbol{A} \in H_{t}^{p}\left(\Omega\right.$, curl, $\left.\operatorname{div} 0, \mathcal{H}_{T}\right)$. Then the minimizing problem

$$
\begin{equation*}
\gamma=\inf _{\boldsymbol{u} \in \mathbb{K}_{T}^{p}(\Omega)}\|\boldsymbol{A}-\boldsymbol{u}\|_{L^{p}(\Omega)} \tag{3.1}
\end{equation*}
$$

has a unique minimizer.
Proof From Lemma 2.3, we know that $\mathbb{K}_{T}^{p}(\Omega)$ is a closed subspace of $L^{p}\left(\Omega, \mathbb{R}^{3}\right)$. Thus, it is well known that (3.1) has a minimizer. For the uniqueness of the minimizer, it suffices to show that the unit sphere $B=\left\{\boldsymbol{u} \in L^{p}\left(\Omega, \mathbb{R}^{3}\right) ;\|\boldsymbol{u}\|_{L^{p}(\Omega)}=1\right\}$ does not contain any line segment $[\boldsymbol{u}, \boldsymbol{v}]=\{\lambda \boldsymbol{u}+(1-\lambda) \boldsymbol{v} ; 0 \leq \lambda \leq 1\}$ for $\boldsymbol{u}, \boldsymbol{v} \in B$ and $\boldsymbol{u} \neq \boldsymbol{v}$ (cf. Fujita et al. [9, p. 306 and the remark]). However, this is clear because the functional

$$
f(\boldsymbol{u})=\int_{\Omega}|\boldsymbol{u}|^{p} d x
$$

is strictly convex.
For $\boldsymbol{A} \in H_{t}^{p}\left(\Omega, \operatorname{curl}, \operatorname{div} 0, \mathcal{H}_{T}\right)$, let $\boldsymbol{u} \in \mathbb{K}_{T}^{p}(\Omega)$ be a unique minimizer of (3.1), and define $\boldsymbol{B}=\boldsymbol{A}-\boldsymbol{u}$. Then, since for any $\boldsymbol{z} \in \mathbb{K}_{T}^{p}(\Omega)$ and $\theta \in \mathbb{R},\|\boldsymbol{B}\|_{L^{p}(\Omega)}^{p} \leq\|\boldsymbol{B}+\theta \boldsymbol{z}\|_{L^{p}(\Omega)}^{p}$, we have

$$
0=\left.\frac{d}{d \theta}\right|_{\theta=0} \int_{\Omega}|\boldsymbol{B}+\theta \boldsymbol{z}|^{p} d x=p \int_{\Omega}|\boldsymbol{B}|^{p-2} \boldsymbol{B} \cdot \boldsymbol{z} d x
$$

## ARAMAKI/Turk J Math

If we define a space

$$
\begin{aligned}
B\left(\Omega, \mathcal{H}_{T}\right) & =\left\{\boldsymbol{B} \in L^{p}\left(\Omega, \mathbb{R}^{3}\right) ; \operatorname{curl} \boldsymbol{B} \in L^{p}\left(\Omega, \mathbb{R}^{3}\right), \operatorname{div} \boldsymbol{B}=0 \text { in } \Omega\right. \\
\boldsymbol{B}_{T} & \left.=\mathcal{H}_{T} \text { on } \partial \Omega \text { and } \int_{\Omega}|\boldsymbol{B}|^{p-2} \boldsymbol{B} \cdot \boldsymbol{z} d x=0 \text { for all } \boldsymbol{z} \in \mathbb{K}_{T}^{p}(\Omega)\right\}
\end{aligned}
$$

then we see that $\boldsymbol{B} \in B\left(\Omega, \mathcal{H}_{T}\right)$. Then we have the following.

Lemma 3.2 We can see that for any $\boldsymbol{A} \in H_{t}^{p}\left(\Omega, \operatorname{curl}\right.$, $\left.\operatorname{div} 0, \mathcal{H}_{T}\right)$, there exist uniquely $\boldsymbol{B} \in B\left(\Omega, \mathcal{H}_{T}\right)$ and $\boldsymbol{u} \in \mathbb{K}_{T}^{p}(\Omega)$ such that

$$
\boldsymbol{A}=\boldsymbol{B}+\boldsymbol{u}
$$

Proof For any $\boldsymbol{A} \in H_{t}^{p}\left(\Omega\right.$, curl, $\left.\operatorname{div} 0, \mathcal{H}_{T}\right)$, as in the above we can write

$$
\boldsymbol{A}=\boldsymbol{B}+\boldsymbol{u} \text { where } \boldsymbol{B} \in B\left(\Omega, \mathcal{H}_{T}\right) \text { and } \boldsymbol{u} \in \mathbb{K}_{T}^{p}(\Omega)
$$

We show the uniqueness of the above decomposition. If we can write

$$
\boldsymbol{A}=\boldsymbol{B}_{1}+\boldsymbol{u}_{1}=\boldsymbol{B}_{2}+\boldsymbol{u}_{2}
$$

where $\boldsymbol{B}_{1}, \boldsymbol{B}_{2} \in B\left(\Omega, \mathcal{H}_{T}\right), \boldsymbol{u}_{1}, \boldsymbol{u}_{2} \in \mathbb{K}_{T}^{p}(\Omega)$, then $\boldsymbol{B}_{1}-\boldsymbol{B}_{2}=\boldsymbol{u}_{2}-\boldsymbol{u}_{1} \in \mathbb{K}_{T}^{p}(\Omega)$. Therefore, we have

$$
\int_{\Omega}\left|\boldsymbol{B}_{1}\right|^{p-2} \boldsymbol{B}_{1} \cdot\left(\boldsymbol{B}_{1}-\boldsymbol{B}_{2}\right) d x=0, \int_{\Omega}\left|\boldsymbol{B}_{2}\right|^{p-2} \boldsymbol{B}_{2} \cdot\left(\boldsymbol{B}_{1}-\boldsymbol{B}_{2}\right) d x=0
$$

Hence,

$$
\begin{equation*}
\int_{\Omega}\left(\left|\boldsymbol{B}_{1}\right|^{p-2} \boldsymbol{B}_{1}-\left|\boldsymbol{B}_{2}\right|^{p-2} \boldsymbol{B}_{2}\right) \cdot\left(\boldsymbol{B}_{1}-\boldsymbol{B}_{2}\right) d x=0 \tag{3.2}
\end{equation*}
$$

Here we use the following inequality. There exists a constant $c>0$ such that

$$
\left(|\boldsymbol{a}|^{p-2} \boldsymbol{a}-|\boldsymbol{b}|^{p-2} \boldsymbol{b}\right) \cdot(\boldsymbol{a}-\boldsymbol{b}) \geq \begin{cases}c|\boldsymbol{a}-\boldsymbol{b}|^{p} & \text { if } p \geq 2  \tag{3.3}\\ c(|\boldsymbol{a}|+|\boldsymbol{b}|)^{p-2}|\boldsymbol{a}-\boldsymbol{b}|^{2} & \text { if } 1<p<2\end{cases}
$$

for all $\boldsymbol{a}, \boldsymbol{b} \in \mathbb{R}^{3}$. For the proof of this inequality, see DiBenedetto [7, Lemma 4.4] for $p \geq 2$, and see [11, (7C')] for $1<p<2$. Applying (3.3) with $\boldsymbol{a}=\boldsymbol{B}_{1}, \boldsymbol{b}=\boldsymbol{B}_{2}$ to (3.2), we have

$$
\int_{\Omega}\left|\boldsymbol{B}_{1}-\boldsymbol{B}_{2}\right|^{p} d x=0 \text { for } p \geq 2
$$

and

$$
\int_{\Omega}\left(\left|\boldsymbol{B}_{1}\right|+\left|\boldsymbol{B}_{2}\right|\right)^{p-2}\left|\boldsymbol{B}_{1}-\boldsymbol{B}_{2}\right|^{2} d x=0 \text { for } 1<p<2
$$

From these equalities, we have $\boldsymbol{B}_{1}=\boldsymbol{B}_{2}$, so $\boldsymbol{u}_{1}=\boldsymbol{u}_{2}$.
Now we state a refinement of Fatou's lemma (cf. Evans [8, pp. 11-12]).

## ARAMAKI/Turk J Math

Lemma 3.3 Assume $1<p<\infty$. Let $\boldsymbol{B}_{j} \rightarrow \boldsymbol{B}$ weakly in $L^{p}\left(\Omega, \mathbb{R}^{3}\right)$ and a.e. in $\Omega$. Then we have

$$
\begin{equation*}
\lim _{j \rightarrow \infty} \int_{\Omega}\left(\left|\boldsymbol{B}_{j}\right|^{p}-\left|\left|\boldsymbol{B}_{j}\right|^{p-2} \boldsymbol{B}_{j}-|\boldsymbol{B}|^{p-2} \boldsymbol{B}\right|^{p^{\prime}}\right) d x=\int_{\Omega}|\boldsymbol{B}|^{p} d x \tag{3.4}
\end{equation*}
$$

If furthermore

$$
\lim _{j \rightarrow \infty} \int_{\Omega}\left|\boldsymbol{B}_{j}\right|^{p} d x=\int_{\Omega}|\boldsymbol{B}|^{p} d x
$$

then

$$
\begin{equation*}
\left|\boldsymbol{B}_{j}\right|^{p-2} \boldsymbol{B}_{j} \rightarrow|\boldsymbol{B}|^{p-2} \boldsymbol{B} \text { strongly in } L^{p^{\prime}}\left(\Omega, \mathbb{R}^{3}\right) \tag{3.5}
\end{equation*}
$$

where $p^{\prime}$ denotes the conjugate exponent of $p$, i.e. $(1 / p)+\left(1 / p^{\prime}\right)=1$. In particular, if $\boldsymbol{B}_{j} \rightarrow \boldsymbol{B}$ strongly in $L^{p}\left(\Omega, \mathbb{R}^{3}\right)$ and a.e. in $\Omega$, then (3.5) holds.

Proof We use an elementary estimate. Let $1 \leq q<\infty$. Then for any fixed $\varepsilon>0$, there exists a constant $C=C(\varepsilon, q)>0$ such that

$$
\begin{equation*}
\left||\boldsymbol{a}+\boldsymbol{b}|^{q}-|\boldsymbol{a}|^{q}\right| \leq \varepsilon|\boldsymbol{a}|^{q}+C|\boldsymbol{b}|^{q} \tag{3.6}
\end{equation*}
$$

for any $\boldsymbol{a}, \boldsymbol{b} \in \mathbb{R}^{3}(\mathrm{cf} .[8,(1.13)])$. Define

$$
g_{j}^{\varepsilon}=\left[\left|\left|\left|\boldsymbol{B}_{j}\right|^{p-2} \boldsymbol{B}_{j}\right|^{p^{\prime}}-\left|\left|\boldsymbol{B}_{j}\right|^{p-2} \boldsymbol{B}_{j}-|\boldsymbol{B}|^{p-2} \boldsymbol{B}\right|^{p^{\prime}}-\left||\boldsymbol{B}|^{p-2} \boldsymbol{B}\right|^{p^{\prime}}\right|-\left.\varepsilon| | \boldsymbol{B}_{j}\right|^{p-2} \boldsymbol{B}_{j}-\left.|\boldsymbol{B}|^{p-2} \boldsymbol{B}\right|^{p^{\prime}}\right]^{+}
$$

where $[a]^{+}=\max \{a, 0\}$ for $a \in \mathbb{R}$. Then we have

If we apply (3.6) with $\boldsymbol{a}=\left|\boldsymbol{B}_{j}\right|^{p-2} \boldsymbol{B}_{j}-|\boldsymbol{B}|^{p-2} \boldsymbol{B}, \boldsymbol{b}=|\boldsymbol{B}|^{p-2} \boldsymbol{B}$ and $q=p^{\prime}$, we have

$$
g_{j}^{\varepsilon} \leq\left.\left.(C+1)| | \boldsymbol{B}\right|^{p-2} \boldsymbol{B}\right|^{p^{\prime}}=(C+1)|\boldsymbol{B}|^{p}
$$

We note that the right-hand side is integrable. By the hypothesis, we can see $g_{j}^{\varepsilon} \rightarrow 0$ a.e. in $\Omega$. Therefore, by the Lebesgue dominated theorem, we have

$$
\lim _{j \rightarrow \infty} \int_{\Omega} g_{j}^{\varepsilon} d x=0
$$

Therefore, we have

$$
\begin{aligned}
& \left.\limsup _{j \rightarrow \infty} \int_{\Omega}| |\left|\boldsymbol{B}_{j}\right|^{p-2} \boldsymbol{B}_{j}\right|^{p^{\prime}}-\left|\left|\boldsymbol{B}_{j}\right|^{p-2} \boldsymbol{B}_{j}-|\boldsymbol{B}|^{p-2} \boldsymbol{B}\right|^{p^{\prime}}-\left||\boldsymbol{B}|^{p-2} \boldsymbol{B}\right|^{p^{\prime}} \mid d x \\
& \quad \leq\left.\varepsilon \limsup _{j \rightarrow \infty} \int_{\Omega}| | \boldsymbol{B}_{j}\right|^{p-2} \boldsymbol{B}_{j}-\left.|\boldsymbol{B}|^{p-2} \boldsymbol{B}\right|^{p^{\prime}} d x \\
& \quad \leq \varepsilon 2^{p^{\prime}} \limsup _{j \rightarrow \infty} \int_{\Omega}\left(\left.\left.| | \boldsymbol{B}_{j}\right|^{p-2} \boldsymbol{B}_{j}\right|^{p^{\prime}}+\left||\boldsymbol{B}|^{p-2} \boldsymbol{B}\right|^{p^{\prime}}\right) d x \\
& \quad=\varepsilon 2^{p^{\prime}} \limsup _{j \rightarrow \infty} \int_{\Omega}\left(\left|\boldsymbol{B}_{j}\right|^{p}+|\boldsymbol{B}|^{p}\right) d x
\end{aligned}
$$

Since $\boldsymbol{B}_{j} \rightarrow \boldsymbol{B}$ weakly in $L^{p}\left(\Omega, \mathbb{R}^{3}\right),\left\|\boldsymbol{B}_{j}\right\|_{L^{p}(\Omega)}$ is bounded. Since $\varepsilon$ is arbitrary, we have

$$
\lim _{j \rightarrow \infty} \int_{\Omega}\left(\left|\boldsymbol{B}_{j}\right|^{p}-\left|\left|\boldsymbol{B}_{j}\right|^{p-2} \boldsymbol{B}_{j}-|\boldsymbol{B}|^{p-2} \boldsymbol{B}\right|^{p^{\prime}}\right) d x=\int_{\Omega}|\boldsymbol{B}|^{p} d x
$$

If furthermore

$$
\lim _{j \rightarrow \infty} \int_{\Omega}\left|\boldsymbol{B}_{j}\right|^{p} d x=\int_{\Omega}|\boldsymbol{B}|^{p} d x
$$

then we have

$$
\left.\lim _{j \rightarrow \infty} \int_{\Omega}| | \boldsymbol{B}_{j}\right|^{p-2} \boldsymbol{B}_{j}-\left.|\boldsymbol{B}|^{p-2} \boldsymbol{B}\right|^{p^{\prime}} d x=0
$$

This completes the proof.

Lemma $3.4 B\left(\Omega, \mathcal{H}_{T}\right)$ is a weakly closed set in $W^{1, p}\left(\Omega, \mathbb{R}^{3}\right)$.
Proof Let $\boldsymbol{B}_{j} \in B\left(\Omega, \mathcal{H}_{T}\right), \boldsymbol{B}_{j} \rightarrow \boldsymbol{B}$ weakly in $W^{1, p}\left(\Omega, \mathbb{R}^{3}\right)$. Then we have curl $\boldsymbol{B} \in L^{p}\left(\Omega, \mathbb{R}^{3}\right)$, $\operatorname{div} \boldsymbol{B}=0$ in $\Omega, \boldsymbol{B}_{T}=\mathcal{H}_{T}$ on $\partial \Omega$, and

$$
\int_{\Omega}\left|\boldsymbol{B}_{j}\right|^{p-2} \boldsymbol{B}_{j} \cdot \boldsymbol{z} d x=0 \text { for all } \boldsymbol{z} \in \mathbb{K}_{T}^{p}(\Omega)
$$

Passing to a subsequence, we may assume that $\boldsymbol{B}_{j} \rightarrow \boldsymbol{B}$ strongly in $L^{p}\left(\Omega, \mathbb{R}^{3}\right)$ and a.e. in $\Omega$. Thus, from Lemma 3.3, we have $\left|\boldsymbol{B}_{j}\right|^{p-2} \boldsymbol{B}_{j} \rightarrow|\boldsymbol{B}|^{p-2} \boldsymbol{B}$ in $L^{p^{\prime}}\left(\Omega, \mathbb{R}^{3}\right)$. Therefore, we have

$$
\int_{\Omega}|\boldsymbol{B}|^{p-2} \boldsymbol{B} \cdot \boldsymbol{z} d x=0 \text { for all } \boldsymbol{z} \in \mathbb{K}_{T}^{p}(\Omega)
$$

This implies that $\boldsymbol{B} \in B\left(\Omega, \mathcal{H}_{T}\right)$.

Lemma 3.5 There exists a constant $c(\Omega)>0$ such that for all $\boldsymbol{B} \in W^{1, p}\left(\Omega, \mathbb{R}^{3}\right)$ satisfying $\operatorname{div} \boldsymbol{B}=0$ in $\Omega$ and

$$
\int_{\Omega}|\boldsymbol{B}|^{p-2} \boldsymbol{B} \cdot \boldsymbol{z} d x=0 \text { for all } \boldsymbol{z} \in \mathbb{K}_{T}^{p}(\Omega)
$$

we have

$$
\begin{equation*}
\|\boldsymbol{B}\|_{W^{1, p}(\Omega)} \leq c(\Omega)\left(\|\operatorname{curl} \boldsymbol{B}\|_{L^{p}(\Omega)}+\left\|\boldsymbol{B}_{T}\right\|_{W^{1-1 / p, p}(\partial \Omega)}\right) \tag{3.7}
\end{equation*}
$$

## ARAMAKI/Turk J Math

Proof If the conclusion (3.7) is false, there exists a sequence $\left\{\boldsymbol{B}_{j}\right\} \subset W^{1, p}\left(\Omega, \mathbb{R}^{3}\right)$ satisfying div $\boldsymbol{B}_{j}=0$ in $\Omega$ and

$$
\int_{\Omega}\left|\boldsymbol{B}_{j}\right|^{p-2} \boldsymbol{B}_{j} \cdot \boldsymbol{z} d x=0 \text { for all } \boldsymbol{z} \in \mathbb{K}_{T}^{p}(\Omega)
$$

such that $\left\|\boldsymbol{B}_{j}\right\|_{W^{1, p}(\Omega)}=1,\left\|\operatorname{curl} \boldsymbol{B}_{j}\right\|_{L^{p}(\Omega)} \rightarrow 0,\left\|\boldsymbol{B}_{j, T}\right\|_{W^{1-1 / p, p}(\partial \Omega)} \rightarrow 0$ as $j \rightarrow \infty$. After passing to a subsequence, we may assume that $\boldsymbol{B}_{j} \rightarrow \boldsymbol{B}_{0}$ weakly in $W^{1, p}\left(\Omega, \mathbb{R}^{3}\right)$, strongly in $L^{p}\left(\Omega, \mathbb{R}^{3}\right)$, and a.e. in $\Omega$. Therefore, we have div $\boldsymbol{B}_{0}=0, \operatorname{curl} \boldsymbol{B}_{0}=\mathbf{0}$ in $\Omega$, and $\boldsymbol{B}_{0, T}=\mathbf{0}$ on $\partial \Omega$, so $\boldsymbol{B}_{0} \in \mathbb{K}_{T}^{p}(\Omega)$. From Lemma 3.3,

$$
\int_{\Omega}\left|\boldsymbol{B}_{0}\right|^{p} d x=\int_{\Omega}\left|\boldsymbol{B}_{0}\right|^{p-2} \boldsymbol{B}_{0} \cdot \boldsymbol{B}_{0} d x=\lim _{j \rightarrow \infty} \int_{\Omega}\left|\boldsymbol{B}_{j}\right|^{p-2} \boldsymbol{B}_{j} \cdot \boldsymbol{B}_{0} d x=0
$$

Thus, we have $\boldsymbol{B}_{0}=\mathbf{0}$. Hence, $\boldsymbol{B}_{j} \rightarrow \mathbf{0}$ strongly in $L^{p}\left(\Omega, \mathbb{R}^{3}\right)$. From (2.3), we see that

$$
\left\|\boldsymbol{B}_{j}\right\|_{W^{1, p}(\Omega)} \leq c_{2}(\Omega)\left(\left\|\boldsymbol{B}_{j}\right\|_{L^{p}(\Omega)}+\left\|\operatorname{curl} \boldsymbol{B}_{j}\right\|_{L^{p}(\Omega)}+\left\|\boldsymbol{B}_{j, T}\right\|_{W^{1-1 / p, p}(\partial \Omega)}\right) \rightarrow 0
$$

as $j \rightarrow \infty$. This contradicts $\left\|\boldsymbol{B}_{j}\right\|_{W^{1, p}(\Omega)}=1$.

Proposition 3.6 Let $\mathcal{H}_{T} \in W^{1-1 / p, p}\left(\partial \Omega, \mathbb{R}^{3}\right)$ and $\boldsymbol{f} \in L^{p^{\prime}}\left(\Omega, \mathbb{R}^{3}\right)$ satisfying

$$
\begin{equation*}
\operatorname{div} \boldsymbol{f}=0 \text { in } \Omega \text { and } \int_{\Omega} \boldsymbol{f} \cdot \boldsymbol{z} d x=0 \text { for all } \boldsymbol{z} \in \mathbb{K}_{T}^{p}(\Omega) \tag{3.8}
\end{equation*}
$$

Then the minimizing problem

$$
\inf _{\boldsymbol{B} \in B\left(\Omega, \mathcal{H}_{T}\right)}\left\{\frac{1}{2} \int_{\Omega} S\left(x,|\operatorname{curl} \boldsymbol{B}|^{2}\right) d x-\int_{\Omega} \boldsymbol{f} \cdot \boldsymbol{B} d x\right\}
$$

is achieved and

$$
\begin{equation*}
R_{t}^{p}\left(\mathcal{H}_{T}, \boldsymbol{f}\right)=\inf _{\boldsymbol{B} \in B\left(\Omega, \mathcal{H}_{T}\right)}\left\{\frac{1}{2} \int_{\Omega} S\left(x,|\operatorname{curl} \boldsymbol{B}|^{2}\right) d x-\int_{\Omega} \boldsymbol{f} \cdot \boldsymbol{B} d x\right\} \tag{3.9}
\end{equation*}
$$

Proof By Lemma 2.1, we can see that

$$
R_{t}^{p}\left(\mathcal{H}_{T}, \boldsymbol{f}\right)=\inf _{\boldsymbol{A} \in H_{t}^{p}\left(\Omega, \operatorname{curl}, \mathrm{div} 0, \mathcal{H}_{T}\right)}\left\{\frac{1}{2} \int_{\Omega} S\left(x,|\operatorname{curl} \boldsymbol{A}|^{2}\right) d x-\int_{\Omega} \boldsymbol{f} \cdot \boldsymbol{A} d x\right\}
$$

Since $B\left(\Omega, \mathcal{H}_{T}\right) \subset H_{t}^{p}\left(\Omega\right.$, curl $\left., \operatorname{div} 0, \mathcal{H}_{T}\right)$, it is clear that

$$
R_{t}^{p}\left(\mathcal{H}_{T}, \boldsymbol{f}\right) \leq \inf _{\boldsymbol{B} \in B\left(\Omega, \mathcal{H}_{T}\right)}\left\{\frac{1}{2} \int_{\Omega} S\left(x,|\operatorname{curl} \boldsymbol{B}|^{2}\right) d x-\int_{\Omega} \boldsymbol{f} \cdot \boldsymbol{B} d x\right\}
$$

On the other hand, for any $\boldsymbol{A} \in H_{t}^{p}\left(\Omega\right.$, curl, $\left.\operatorname{div} 0, \mathcal{H}_{T}\right)$, we can write $\boldsymbol{A}=\boldsymbol{B}+\boldsymbol{u}$ where $\boldsymbol{B} \in B\left(\Omega, \mathcal{H}_{T}\right), \boldsymbol{u} \in$ $\mathbb{K}_{T}^{p}(\Omega)$. Since $\operatorname{curl} \boldsymbol{A}=\operatorname{curl} \boldsymbol{B}$ and

$$
\int_{\Omega} \boldsymbol{f} \cdot \boldsymbol{A} d x=\int_{\Omega} \boldsymbol{f} \cdot \boldsymbol{B} d x+\int_{\Omega} \boldsymbol{f} \cdot \boldsymbol{u} d x=\int_{\Omega} \boldsymbol{f} \cdot \boldsymbol{B} d x
$$

we have

$$
\begin{aligned}
\frac{1}{2} \int_{\Omega} S\left(x,|\operatorname{curl} \boldsymbol{A}|^{2}\right) d x-\int_{\Omega} \boldsymbol{f} \cdot \boldsymbol{A} d x & =\frac{1}{2} \int_{\Omega} S\left(x,|\operatorname{curl} \boldsymbol{B}|^{2}\right) d x-\int_{\Omega} \boldsymbol{f} \cdot \boldsymbol{B} d x \\
& \geq \inf _{\boldsymbol{B} \in B\left(\Omega, \mathcal{H}_{T}\right)}\left\{\frac{1}{2} \int_{\Omega} S\left(x,|\operatorname{curl} \boldsymbol{B}|^{2}\right) d x-\int_{\Omega} \boldsymbol{f} \cdot \boldsymbol{B} d x\right\}
\end{aligned}
$$

Thus, (3.9) holds. We show that the right-hand side of (3.9) has a minimizer. Let $\left\{\boldsymbol{B}_{j}\right\} \subset B\left(\Omega, \mathcal{H}_{T}\right)$ be a minimizing sequence. Then

$$
\frac{1}{2} \int_{\Omega} S\left(x,\left|\operatorname{curl} \boldsymbol{B}_{j}\right|^{2}\right) d x-\int_{\Omega} \boldsymbol{f} \cdot \boldsymbol{B}_{j} d x=R_{t}^{p}\left(\mathcal{H}_{T}, \boldsymbol{f}\right)+o(1) \text { as } j \rightarrow \infty
$$

By (1.3), we have

$$
\frac{2}{p} \lambda \int_{\Omega}\left|\operatorname{curl} \boldsymbol{B}_{j}\right|^{p} d x-\|\boldsymbol{f}\|_{L^{p^{\prime}}(\Omega)}\left\|\boldsymbol{B}_{j}\right\|_{L^{p}(\Omega)} \leq R_{t}^{p}\left(\mathcal{H}_{T}, \boldsymbol{f}\right)+o(1)
$$

Using Lemma 3.5, for any $\varepsilon>0$, there exists $C(\varepsilon)>0$ such that

$$
\begin{aligned}
\|\boldsymbol{f}\|_{L^{p^{\prime}}(\Omega)}\left\|\boldsymbol{B}_{j}\right\|_{L^{p}(\Omega)} & \leq \varepsilon\left\|\boldsymbol{B}_{j}\right\|_{L^{p}(\Omega)}^{p}+C(\varepsilon)\|\boldsymbol{f}\|_{L^{p^{\prime}}(\Omega)}^{p^{\prime}} \\
& \leq C(\Omega) \varepsilon\left(\left\|\operatorname{curl} \boldsymbol{B}_{j}\right\|_{L^{p}(\Omega)}^{p}+\left\|\mathcal{H}_{T}\right\|_{W^{1-1 / p, p}(\partial \Omega)}^{p}\right)+C(\varepsilon)\|\boldsymbol{f}\|_{L^{p^{\prime}}(\Omega)}^{p^{\prime}}
\end{aligned}
$$

If we choose $\varepsilon>0$ so that $C(\Omega) \varepsilon<2 \lambda / p$, we can see that

$$
\int_{\Omega}\left|\operatorname{curl} \boldsymbol{B}_{j}\right|^{p} d x \leq R_{t}^{p}\left(\mathcal{H}_{T}, \boldsymbol{f}\right)+C\left(\left\|\mathcal{H}_{T}\right\|_{W^{1-1 / p, p}(\partial \Omega)}^{p}+\|\boldsymbol{f}\|_{L^{p^{\prime}}(\Omega)}^{p^{\prime}}\right)+o(1)
$$

Then it follows from Lemma 3.5 that $\left\{\boldsymbol{B}_{j}\right\}$ is bounded in $W^{1, p}\left(\Omega, \mathbb{R}^{3}\right)$. Passing to a subsequence, we may assume that $\boldsymbol{B}_{j} \rightarrow \boldsymbol{B}_{0}$ weakly in $W^{1, p}\left(\Omega, \mathbb{R}^{3}\right)$, strongly in $L^{p}\left(\Omega, \mathbb{R}^{3}\right)$, and a.e. in $\Omega$. Therefore, we have $\operatorname{div} \boldsymbol{B}_{0}=0$ in $\Omega$ and $\boldsymbol{B}_{0, T}=\mathcal{H}_{T}$ on $\partial \Omega$. Since

$$
\int_{\Omega}\left|\boldsymbol{B}_{j}\right|^{p-2} \boldsymbol{B}_{j} \cdot \boldsymbol{z} d x=0 \text { for all } \boldsymbol{z} \in \mathbb{K}_{T}^{p}(\Omega)
$$

it follows from Lemma 3.3 that

$$
\int_{\Omega}\left|\boldsymbol{B}_{0}\right|^{p-2} \boldsymbol{B}_{0} \cdot \boldsymbol{z} d x=0 \text { for all } \boldsymbol{z} \in \mathbb{K}_{T}^{p}(\Omega)
$$

Therefore, $\boldsymbol{B}_{0} \in B\left(\Omega, \mathcal{H}_{T}\right)$. It suffices to prove that

$$
\int_{\Omega} S\left(x,\left|\operatorname{curl} \boldsymbol{B}_{0}\right|^{2}\right) d x \leq \liminf _{j \rightarrow \infty} \int_{\Omega} S\left(x,\left|\operatorname{curl} \boldsymbol{B}_{j}\right|^{2}\right) d x
$$

In fact, we can choose a subsequence $\left\{\operatorname{curl} \boldsymbol{B}_{j_{k}}\right\}$ of $\left\{\operatorname{curl} \boldsymbol{B}_{j}\right\}$ so that

$$
\lim _{k \rightarrow \infty} \int_{\Omega} S\left(x,\left|\operatorname{curl} \boldsymbol{B}_{j_{k}}\right|^{2}\right) d x=\liminf _{j \rightarrow \infty} \int_{\Omega} S\left(x,\left|\operatorname{curl} \boldsymbol{B}_{j}\right|^{2}\right) d x
$$

## ARAMAKI/Turk J Math

Since curl $\boldsymbol{B}_{j_{k}} \rightarrow \operatorname{curl} \boldsymbol{B}_{0}$ weakly in $L^{p}\left(\Omega, \mathbb{R}^{3}\right)$, it follows from the Mazur theorem that there exist $\boldsymbol{g}_{l} \in$ $L^{p}\left(\Omega, \mathbb{R}^{3}\right)$ such that $\boldsymbol{g}_{l} \in$ convex hull of $\left\{\operatorname{curl} \boldsymbol{B}_{j_{k}} ; k \geq l\right\}$ and $\boldsymbol{g}_{l} \rightarrow \operatorname{curl} \boldsymbol{B}_{0}$ strongly in $L^{p}\left(\Omega, \mathbb{R}^{3}\right)$. Hence, we can choose a subsequence $\left\{\boldsymbol{g}_{l_{m}}\right\}$ of $\left\{\boldsymbol{g}_{l}\right\}$ so that $\boldsymbol{g}_{l_{m}} \rightarrow \operatorname{curl} \boldsymbol{B}_{0}$ strongly in $L^{p}\left(\Omega, \mathbb{R}^{3}\right)$ and a.e. in $\Omega$. By the Fatou lemma, we have

$$
\int_{\Omega} S\left(x,\left|\operatorname{curl} \boldsymbol{B}_{0}\right|^{2}\right) d x \leq \liminf _{m \rightarrow \infty} \int_{\Omega} S\left(x,\left|\boldsymbol{g}_{l_{m}}\right|^{2}\right) d x
$$

Since $S\left(x, t^{2}\right)$ is a convex function with respect to $t$, we have

$$
\int_{\Omega} S\left(x,\left|\boldsymbol{g}_{l_{m}}\right|^{2}\right) d x \leq \sup \left\{\int_{\Omega} S\left(x,\left|\operatorname{curl} \boldsymbol{B}_{j_{k}}\right|^{2}\right) d x ; k \geq l_{m}\right\} .
$$

Therefore, we have

$$
\begin{aligned}
\int_{\Omega} S\left(x,\left|\operatorname{curl} \boldsymbol{B}_{0}\right|^{2}\right) d x & \leq \liminf _{m \rightarrow \infty} \int_{\Omega} S\left(x,\left|\boldsymbol{g}_{l_{m}}\right|^{2}\right) d x \\
& \leq \lim _{m \rightarrow \infty} \sup \left\{\int_{\Omega} S\left(x,\left.\operatorname{curl} \boldsymbol{B}_{j_{k}}\right|^{2}\right) d x ; k \geq l_{m}\right\} \\
& =\lim _{k \rightarrow \infty} \int_{\Omega} S\left(x,\left.\operatorname{curl} \boldsymbol{B}_{j_{k}}\right|^{2}\right) d x \\
& =\liminf _{j \rightarrow \infty} \int_{\Omega} S\left(x,\left|\operatorname{curl} \boldsymbol{B}_{j}\right|^{2}\right) d x
\end{aligned}
$$

This completes the proof.

Lemma 3.7 Let $\boldsymbol{A} \in H_{t}^{p}\left(\Omega\right.$, curl, $\left.\operatorname{div} 0, \mathcal{H}_{T}\right)$ be a minimizer of $R_{t}^{p}\left(\mathcal{H}_{T}, \boldsymbol{f}\right)$. Then $\boldsymbol{A}$ is a weak solution of the following system:

$$
\begin{cases}\operatorname{curl}\left[S_{t}\left(x,|\operatorname{curl} \boldsymbol{A}|^{2}\right) \operatorname{curl} \boldsymbol{A}\right]=\boldsymbol{f}, \operatorname{div} \boldsymbol{A}=0 & \text { in } \Omega  \tag{3.10}\\ \boldsymbol{A}_{T}=\mathcal{H}_{T} & \text { on } \partial \Omega\end{cases}
$$

Proof If $\boldsymbol{A} \in H_{t}^{p}\left(\Omega, \operatorname{curl}, \operatorname{div} 0, \mathcal{H}_{T}\right)$ is a minimizer of $R_{t}^{p}\left(\mathcal{H}_{T}, \boldsymbol{f}\right)$, then we can see that for any $\boldsymbol{w} \in$ $H_{t}^{p}(\Omega, \operatorname{curl}, \operatorname{div} 0, \mathbf{0})$, we have

$$
\left.\frac{d}{d \theta}\right|_{\theta=0}\left\{\frac{1}{2} \int_{\Omega} S\left(x,|\operatorname{curl} \boldsymbol{A}+\theta \operatorname{curl} \boldsymbol{w}|^{2}\right) d x-\int_{\Omega} \boldsymbol{f} \cdot(\boldsymbol{A}+\theta \boldsymbol{w}) d x\right\}=0 .
$$

Thus, we have

$$
\begin{equation*}
\int_{\Omega} S_{t}\left(x,|\operatorname{curl} \boldsymbol{A}|^{2}\right) \operatorname{curl} \boldsymbol{A} \cdot \operatorname{curl} \boldsymbol{w} d x-\int_{\Omega} \boldsymbol{f} \cdot \boldsymbol{w} d x=0 \tag{3.11}
\end{equation*}
$$

for all $\boldsymbol{w} \in H_{t}^{p}(\Omega, \operatorname{curl}, \operatorname{div} 0, \mathbf{0})$. For any $\boldsymbol{u} \in W_{t}^{1, p}\left(\Omega, \mathbb{R}^{3}, \mathbf{0}\right)$, we choose a unique solution $\phi \in W^{2, p}(\Omega)$ of the Dirichlet problem

$$
\begin{cases}\Delta \phi=\operatorname{div} \boldsymbol{u} & \text { in } \Omega \\ \phi=0 & \text { on } \partial \Omega\end{cases}
$$

## ARAMAKI/Turk J Math

and put $\boldsymbol{w}=\boldsymbol{u}-\nabla \phi$. Then $\operatorname{curl} \boldsymbol{w}=\operatorname{curl} \boldsymbol{u} \in L^{p}\left(\Omega, \mathbb{R}^{3}\right), \operatorname{div} \boldsymbol{w}=\operatorname{div} \boldsymbol{u}-\Delta \phi=0$ in $\Omega$, and $\boldsymbol{w}_{T}=$ $\boldsymbol{u}_{T}-(\nabla \phi)_{T}=\boldsymbol{u}_{T}=\mathbf{0}$. Thus, we have $\boldsymbol{w} \in H_{t}^{p}(\Omega$, curl, div 0,0$)$. Since

$$
\begin{aligned}
\int_{\Omega} \boldsymbol{f} \cdot \boldsymbol{u} d x & =\int_{\Omega} \boldsymbol{f} \cdot \boldsymbol{w} d x+\int_{\Omega} \boldsymbol{f} \cdot \nabla \phi d x \\
& =\int_{\Omega} \boldsymbol{f} \cdot \boldsymbol{w} d x-\int_{\Omega}(\operatorname{div} \boldsymbol{f}) \phi d x+\int_{\partial \Omega}(\boldsymbol{f} \cdot \boldsymbol{\nu}) \phi d S \\
& =\int_{\Omega} \boldsymbol{f} \cdot \boldsymbol{w} d x
\end{aligned}
$$

it follows from (3.11) that

$$
\int_{\Omega} S_{t}\left(x,|\operatorname{curl} \boldsymbol{A}|^{2}\right) \operatorname{curl} \boldsymbol{A} \cdot \operatorname{curl} \boldsymbol{u} d x-\int_{\Omega} \boldsymbol{f} \cdot \boldsymbol{u} d x=0
$$

for all $\boldsymbol{u} \in W_{t}^{1, p}\left(\Omega, \mathbb{R}^{3}, \mathbf{0}\right)$. Since $\mathcal{D}\left(\Omega, \mathbb{R}^{3}\right) \subset W_{t}^{1, p}\left(\Omega, \mathbb{R}^{3}, \mathbf{0}\right)$, we can see that (3.10) holds.

Remark 3.8 The system (3.10) with $S(x, t)=t^{p / 2}$ is the so-called p-curl system. When $\Omega$ is a bounded, simply connected domain in $\mathbb{R}^{3}$ without holes, and with $C^{2+\alpha}$ boundary for some $\alpha \in(0,1)$. If $\mathcal{H}_{T}=\mathbf{0}$ and $\boldsymbol{f} \in C^{\alpha}\left(\bar{\Omega}, \mathbb{R}^{3}\right)$ satisfying $\operatorname{div} \boldsymbol{f}=0$ in $\Omega$, then Aramaki [4] showed that the weak solution $\boldsymbol{A}$ of the system (3.10) satisfies that $\boldsymbol{A} \in C^{1+\beta}\left(\bar{\Omega}, \mathbb{R}^{3}\right)$ for some $\beta \in(0,1)$ and there exists a constant $C$ depending only on $p, \Omega$ such that $\|\boldsymbol{A}\|_{C^{1+\beta}(\bar{\Omega})} \leq C$.

Lemma 3.9 Let $\mathcal{H}_{T} \in W^{1-1 / p, p}\left(\partial \Omega, \mathbb{R}^{3}\right)$ and $\boldsymbol{f} \in L^{p^{\prime}}\left(\Omega, \mathbb{R}^{3}\right)$ satisfying (3.8). If $\boldsymbol{B}_{0} \in B\left(\Omega, \mathcal{H}_{T}\right)$ is a minimizer of (3.9), then any minimizer $\boldsymbol{A} \in H_{T}^{p}\left(\Omega, \operatorname{curl}\right.$, $\left.\operatorname{div} 0, \mathcal{H}_{T}\right)$ of (2.1) must have the form $\boldsymbol{A}=\boldsymbol{B}_{0}+\boldsymbol{u}$ where $\boldsymbol{u} \in \mathbb{K}_{T}^{p}(\Omega)$. In particular, the minimizer of (3.9) is unique.

Proof Since for any $\boldsymbol{u} \in \mathbb{K}_{T}^{p}(\Omega)$, we see that

$$
\boldsymbol{B}_{0}+\boldsymbol{u} \in H_{t}^{p}\left(\Omega, \operatorname{curl}, \operatorname{div} 0, \mathcal{H}_{T}\right)
$$

and

$$
\int_{\Omega}\left|\operatorname{curl}\left(\boldsymbol{B}_{0}+\boldsymbol{u}\right)\right|^{p} d x=\int_{\Omega}\left|\operatorname{curl} \boldsymbol{B}_{0}\right|^{p} d x
$$

and

$$
\int_{\Omega} \boldsymbol{f} \cdot\left(\boldsymbol{B}_{0}+\boldsymbol{u}\right) d x=\int_{\Omega} \boldsymbol{f} \cdot \boldsymbol{B}_{0} d x
$$

thus, $\boldsymbol{B}_{0}+\boldsymbol{u}$ is a minimizer of (2.1). On the other hand, for any minimizer $\boldsymbol{A} \in H_{t}^{p}\left(\Omega, \operatorname{curl}, \operatorname{div} 0, \mathcal{H}_{T}\right)$ of (2.1), define $\boldsymbol{w}=\boldsymbol{A}-\boldsymbol{B}_{0}$. Then $\boldsymbol{w} \in H_{t}^{p}(\Omega, \operatorname{curl}, \operatorname{div} 0, \mathbf{0})$. Since $\boldsymbol{A}$ and $\boldsymbol{B}_{0}$ are minimizers of $R_{t}^{p}\left(\mathcal{H}_{T}, \boldsymbol{f}\right)$, it follows from Lemma 3.7 that

$$
\begin{aligned}
\int_{\Omega} S_{t}\left(x,|\operatorname{curl} \boldsymbol{A}|^{2}\right) \operatorname{curl} \boldsymbol{A} \cdot \operatorname{curl} \boldsymbol{w} d x & =\int_{\Omega} \boldsymbol{f} \cdot \boldsymbol{w} d x \\
\int_{\Omega} S_{t}\left(x,\left|\operatorname{curl} \boldsymbol{B}_{0}\right|^{2}\right) \operatorname{curl} \boldsymbol{B}_{0} \cdot \operatorname{curl} \boldsymbol{w} d x & =\int_{\Omega} \boldsymbol{f} \cdot \boldsymbol{w} d x
\end{aligned}
$$

## ARAMAKI/Turk J Math

Therefore,

$$
\int_{\Omega}\left(S_{t}\left(x,|\operatorname{curl} \boldsymbol{A}|^{2}\right) \operatorname{curl} \boldsymbol{A}-S_{t}\left(x,\left|\operatorname{curl} \boldsymbol{B}_{0}\right|^{2}\right) \operatorname{curl} \boldsymbol{B}_{0}\right) \cdot\left(\operatorname{curl} \boldsymbol{A}-\operatorname{curl} \boldsymbol{B}_{0}\right) d x=0
$$

By the structure condition (1.2), we have $\operatorname{curl}\left(\boldsymbol{A}-\boldsymbol{B}_{0}\right)=\mathbf{0}$ in $\Omega$, so $\boldsymbol{A}-\boldsymbol{B}_{0} \in \mathbb{K}_{T}^{p}(\Omega)$.
If $\boldsymbol{B} \in B\left(\Omega, \mathcal{H}_{T}\right) \subset H_{t}^{p}\left(\Omega, \operatorname{curl}, \operatorname{div} 0, \mathcal{H}_{T}\right)$ is a minimizer of $(3.9)$, we can write $\boldsymbol{B}=\boldsymbol{B}_{0}+\boldsymbol{u}$ where $\boldsymbol{u} \in \mathbb{K}_{T}^{p}(\Omega)$. If follows from Lemma 3.2 that we see that $\boldsymbol{u}=\mathbf{0}$. Thus, the minimizer of (3.9) in $B\left(\Omega, \mathcal{H}_{T}\right)$ is unique.

For $\mathcal{H}_{T} \in W^{1-1 / p, p}\left(\partial \Omega, \mathbb{R}^{3}\right)$ and $\boldsymbol{f} \in L^{p^{\prime}}\left(\Omega, \mathbb{R}^{3}\right)$ satisfying $(3.8)$, let $\boldsymbol{A}=\boldsymbol{A}\left(\mathcal{H}_{T}, \boldsymbol{f}\right) \in H_{t}^{p}\left(\Omega, \operatorname{curl}, \operatorname{div} 0, \mathcal{H}_{T}\right)$ be a minimizer of (2.1). Then there exist uniquely $\boldsymbol{B}_{0}=\boldsymbol{B}_{0}\left(\mathcal{H}_{T}, \boldsymbol{f}\right) \in B\left(\Omega, \mathcal{H}_{T}\right)$, which is a minimizer of (3.9), and $\boldsymbol{u}=\boldsymbol{u}\left(\mathcal{H}_{T}, \boldsymbol{f}\right) \in \mathbb{K}_{T}^{p}(\Omega)$, such that

$$
\begin{equation*}
\boldsymbol{A}\left(\mathcal{H}_{T}, \boldsymbol{f}\right)=\boldsymbol{B}_{0}\left(\mathcal{H}_{T}, \boldsymbol{f}\right)+\boldsymbol{u}\left(\mathcal{H}_{T}, \boldsymbol{f}\right) \tag{3.12}
\end{equation*}
$$

Proposition 3.10 There exists a constant $c=c(\Omega)$ independent of $\mathcal{H}_{T}$ and $\boldsymbol{f}$ satisfying the above such that

$$
\left\|\boldsymbol{B}_{0}\left(\mathcal{H}_{T}, \boldsymbol{f}\right)\right\|_{W^{1, p}(\Omega)} \leq c\left(\left\|\mathcal{H}_{T}\right\|_{W^{1-1 / p, p}(\partial \Omega)}+\|\boldsymbol{f}\|_{L^{p^{\prime}}(\Omega)}\right)
$$

Proof Assume that the conclusion is false. Then there exists a sequence $\left\{\mathcal{H}_{j, T}\right\} \subset W^{1-1 / p, p}\left(\partial \Omega, \mathbb{R}^{3}\right)$ and $\boldsymbol{f}_{j} \in L^{p^{\prime}}\left(\Omega, \mathbb{R}^{3}\right)$ satisfying (3.8) such that $\left\|\boldsymbol{B}_{0}\left(\mathcal{H}_{j, T}, \boldsymbol{f}_{j}\right)\right\|_{W^{1, p}(\Omega)}=1$ and

$$
\left\|\mathcal{H}_{j, T}\right\|_{W^{1-1 / p, p}(\partial \Omega)} \rightarrow 0 \text { and }\left\|\boldsymbol{f}_{j}\right\|_{L^{p^{\prime}}(\Omega)} \rightarrow 0 \text { as } j \rightarrow \infty
$$

For brevity of notation, we write $\boldsymbol{B}_{j}=\boldsymbol{B}_{0}\left(\mathcal{H}_{j, T}, \boldsymbol{f}_{j}\right)$. Passing to a subsequence, we may assume that $\boldsymbol{B}_{j} \rightarrow \boldsymbol{B}$ weakly in $W^{1, p}\left(\Omega, \mathbb{R}^{3}\right)$, strongly in $L^{p}\left(\Omega, \mathbb{R}^{3}\right)$, and a.e. in $\Omega$. Thus, curl $\boldsymbol{B} \in L^{p}\left(\Omega, \mathbb{R}^{3}\right), \operatorname{div} \boldsymbol{B}=0$ in $\Omega$, and $\boldsymbol{B}_{T}=\mathbf{0}$ on $\partial \Omega$. Since $\boldsymbol{B}_{j}$ satisfies

$$
\int_{\Omega}\left|\boldsymbol{B}_{j}\right|^{p-2} \boldsymbol{B}_{j} \cdot \boldsymbol{z} d x=0 \text { for all } \boldsymbol{z} \in \mathbb{K}_{T}^{p}(\Omega)
$$

and $\boldsymbol{B}_{j} \rightarrow \boldsymbol{B}$ strongly in $L^{p}\left(\Omega, \mathbb{R}^{3}\right)$ and a.e. in $\Omega$, it follows from Lemma 3.3 that

$$
\begin{equation*}
\int_{\Omega}|\boldsymbol{B}|^{p-2} \boldsymbol{B} \cdot \boldsymbol{z} d x=0 \text { for all } \boldsymbol{z} \in \mathbb{K}_{T}^{p}(\Omega) \tag{3.13}
\end{equation*}
$$

Hence, we have $\boldsymbol{B} \in B(\Omega, \mathbf{0})$. On the other hand, $\boldsymbol{B}_{j}$ is a weak solution of

$$
\begin{cases}\operatorname{curl}\left[S_{t}\left(x,\left|\operatorname{curl} \boldsymbol{B}_{j}\right|^{2}\right) \operatorname{curl} \boldsymbol{B}_{j}\right]=\boldsymbol{f}_{j}, \operatorname{div} \boldsymbol{B}_{j}=0 & \text { in } \Omega  \tag{3.14}\\ \boldsymbol{B}_{j, T}=\mathcal{H}_{j, T} & \text { on } \partial \Omega\end{cases}
$$

Since $S_{t}\left(x,\left|\operatorname{curl} \boldsymbol{B}_{j}\right|^{2}\right) \operatorname{curl} \boldsymbol{B}_{j} \in L^{p^{\prime}}\left(\Omega, \mathbb{R}^{3}\right)$ and

$$
\operatorname{curl}\left[S_{t}\left(x,\left|\operatorname{curl} \boldsymbol{B}_{j}\right|^{2}\right) \operatorname{curl} \boldsymbol{B}_{j}\right]=\boldsymbol{f}_{j} \in L^{p^{\prime}}\left(\Omega, \mathbb{R}^{3}\right)
$$

we see that

$$
\boldsymbol{\nu} \times\left. S_{t}\left(x,\left|\operatorname{curl} \boldsymbol{B}_{j}\right|^{2}\right) \operatorname{curl} \boldsymbol{B}_{j}\right|_{\partial \Omega} \in W^{-1 / p^{\prime}, p^{\prime}}\left(\partial \Omega, \mathbb{R}^{3}\right)
$$

(cf. [2]). Since $\mathcal{H}_{j, T} \in W^{1-1 / p, p}\left(\partial \Omega, \mathbb{R}^{3}\right)=W^{1 / p^{\prime}, p}\left(\partial \Omega, \mathbb{R}^{3}\right)$, it follows from (3.13) that

$$
\begin{align*}
\int_{\Omega} \boldsymbol{f}_{j} \cdot \boldsymbol{B}_{j} d x= & \int_{\Omega} \operatorname{curl}\left[S_{t}\left(x,\left|\operatorname{curl} \boldsymbol{B}_{j}\right|^{2}\right) \operatorname{curl} \boldsymbol{B}_{j}\right] \cdot \boldsymbol{B}_{j} d x \\
= & \int_{\Omega} S_{t}\left(x,\left|\operatorname{curl} \boldsymbol{B}_{j}\right|^{2}\right) \operatorname{curl} \boldsymbol{B}_{j} \cdot \operatorname{curl} \boldsymbol{B}_{j} d x \\
& +\int_{\partial \Omega}\left\langle\boldsymbol{B}_{j, T}, \boldsymbol{\nu} \times S_{t}\left(x,\left|\operatorname{curl} \boldsymbol{B}_{j}\right|^{2}\right) \operatorname{curl} \boldsymbol{B}_{j}\right\rangle d S \tag{3.15}
\end{align*}
$$

where $\langle\cdot, \cdot\rangle$ denotes the duality bracket between the spaces $W^{1 / p^{\prime}, p}\left(\partial \Omega, \mathbb{R}^{3}\right)$ and $W^{-1 / p^{\prime}, p^{\prime}}\left(\partial \Omega, \mathbb{R}^{3}\right)$. Here we note that for any $\boldsymbol{B} \in L^{p^{\prime}}\left(\Omega, \mathbb{R}^{3}\right)$ satisfying curl $\boldsymbol{B} \in L^{p^{\prime}}\left(\Omega, \mathbb{R}^{3}\right)$, we have

$$
\|\boldsymbol{\nu} \times \boldsymbol{B}\|_{W^{-1 / p^{\prime}, p^{\prime}}(\partial \Omega)} \leq C\left(\|\boldsymbol{B}\|_{L^{p^{\prime}}(\Omega)}+\|\operatorname{curl} \boldsymbol{B}\|_{L^{p^{\prime}}(\Omega)}\right)
$$

See, for example, [2, p. 45]. Therefore, we have

$$
\begin{aligned}
\left|\int_{\partial \Omega}\left\langle\mathcal{H}_{j, T}, \boldsymbol{\nu} \times S_{t}\left(x,\left|\operatorname{curl} \boldsymbol{B}_{j}\right|^{2}\right) \operatorname{curl} \boldsymbol{B}_{j}\right\rangle d S\right| & \leq C\left\|\mathcal{H}_{j, T}\right\|_{W^{1-1 / p, p}(\partial \Omega)}\left(\left\|S_{t}\left(x,\left|\operatorname{curl} \boldsymbol{B}_{j}\right|^{2}\right) \operatorname{curl} \boldsymbol{B}_{j}\right\|_{L^{p^{\prime}}(\Omega)}+\left\|\boldsymbol{f}_{j}\right\|_{L^{p^{\prime}}(\Omega)}\right) \\
& \leq C\left\|\mathcal{H}_{j, T}\right\|_{W^{1-1 / p, p}(\partial \Omega)}\left\{\left(\int_{\Omega}\left(\Lambda\left|\operatorname{curl} \boldsymbol{B}_{j}\right|^{p-1}\right)^{p^{\prime}} d x\right)^{1 / p^{\prime}}+\left\|\boldsymbol{f}_{j}\right\|_{L^{p^{\prime}(\Omega)}}\right\} \\
& \leq C_{1}\left\|\mathcal{H}_{j, T}\right\|_{W^{1-1 / p, p}(\partial \Omega)}\left(\left\|\operatorname{curl} \boldsymbol{B}_{j}\right\|_{L^{p}(\Omega)}^{p / p^{\prime}}+\left\|\boldsymbol{f}_{j}\right\|_{L^{p^{\prime}}(\Omega)}\right)
\end{aligned}
$$

Since curl $\boldsymbol{B}_{j} \rightarrow \operatorname{curl} \boldsymbol{B}$ weakly in $L^{p}\left(\Omega, \mathbb{R}^{3}\right)$, we see that $\left\|\operatorname{curl} \boldsymbol{B}_{j}\right\|_{L^{p}(\Omega)}$ is bounded. Since $\left\|\mathcal{H}_{j, T}\right\|_{W^{1-1 / p, p}(\partial \Omega)} \rightarrow$ 0 , we have

$$
\int_{\partial \Omega}\left\langle\boldsymbol{\nu} \times \mathcal{H}_{j, T}, S_{t}\left(x,\left|\operatorname{curl} \boldsymbol{B}_{j}\right|^{2}\right) \operatorname{curl} \boldsymbol{B}_{j}\right\rangle d S \rightarrow 0
$$

as $j \rightarrow \infty$. By Lemma 3.5 , we have

$$
\left\|\boldsymbol{B}_{j}\right\|_{L^{p}(\Omega)} \leq C(\Omega)\left(\left\|\operatorname{curl} \boldsymbol{B}_{j}\right\|_{L^{p}(\Omega)}+\left\|\mathcal{H}_{j, T}\right\|_{W^{1-1 / p, p}(\partial \Omega)}\right) \leq C
$$

Since $\boldsymbol{f}_{j} \rightarrow 0$ in $L^{p^{\prime}}\left(\Omega, \mathbb{R}^{3}\right)$, we see that

$$
\int_{\Omega} \boldsymbol{f}_{j} \cdot \boldsymbol{B}_{j} d x \rightarrow 0 \text { as } j \rightarrow \infty
$$

Since curl $\boldsymbol{B}_{j} \rightarrow \operatorname{curl} \boldsymbol{B}$ weakly in $L^{p}\left(\Omega, \mathbb{R}^{3}\right)$, using (3.15),

$$
\begin{align*}
\int_{\Omega}|\operatorname{curl} \boldsymbol{B}|^{2} d x & \leq \liminf _{j \rightarrow \infty} \int_{\Omega}\left|\operatorname{curl} \boldsymbol{B}_{j}\right|^{p} d x \\
& \leq \limsup _{j \rightarrow \infty} \int_{\Omega}\left|\operatorname{curl} \boldsymbol{B}_{j}\right|^{p} d x \\
& \leq \frac{1}{\lambda} \limsup _{j \rightarrow \infty} \int_{\Omega} S_{t}\left(x,\left|\operatorname{curl} \boldsymbol{B}_{j}\right|^{2}\right)\left|\operatorname{curl} \boldsymbol{B}_{j}\right|^{2} d x=0 \tag{3.16}
\end{align*}
$$

thus we can see that $\operatorname{curl} \boldsymbol{B}=\mathbf{0}$, so $\boldsymbol{B} \in \mathbb{K}_{T}^{p}(\Omega)$. From (3.13) with $\boldsymbol{z}=\boldsymbol{B}$, we have

$$
0=\int_{\Omega}|\boldsymbol{B}|^{p-2} \boldsymbol{B} \cdot \boldsymbol{B} d x=\int_{\Omega}|\boldsymbol{B}|^{p} d x
$$

Therefore, $\boldsymbol{B}=\mathbf{0}$ in $\Omega$, so $\boldsymbol{B}_{j} \rightarrow \mathbf{0}$ weakly in $W^{1, p}\left(\Omega, \mathbb{R}^{3}\right)$ and strongly in $L^{p}\left(\Omega, \mathbb{R}^{3}\right)$. From (3.16), we can see that $\left\|\operatorname{curl} \boldsymbol{B}_{j}\right\|_{L^{p}(\Omega)} \rightarrow 0$. By (2.3),

$$
\left\|\boldsymbol{B}_{j}\right\|_{W^{1, p}(\Omega)} \leq c_{2}(\Omega)\left(\left\|\boldsymbol{B}_{j}\right\|_{L^{p}(\Omega)}+\left\|\operatorname{curl} \boldsymbol{B}_{j}\right\|_{L^{p}(\Omega)}+\left\|\mathcal{H}_{j, T}\right\|_{W^{1-1 / p, p}(\partial \Omega)}\right) \rightarrow 0
$$

as $j \rightarrow \infty$. This contradicts $\left\|\boldsymbol{B}_{j}\right\|_{W^{1, p}(\Omega)}=1$.
Proof of Theorem 1.1 The proof of Theorem 1.1 follows from Lemma 2.1, Proposition 3.6, and Proposition 3.10 .

Remark 3.11 Instead of minimizing

$$
\frac{1}{2} \int_{\Omega} S\left(t,|\operatorname{curl} \boldsymbol{u}|^{2}\right) d x-\int_{\Omega} \boldsymbol{f} \cdot \boldsymbol{u} d x
$$

it is also interesting to minimize

$$
\frac{1}{2} \int_{\Omega} S\left(x,|\operatorname{div} \boldsymbol{u}|^{2}\right) d x-\int_{\Omega} \boldsymbol{f} \cdot \boldsymbol{u} d x
$$

This problem is related to the mathematical theory of liquid crystals. For $p=2$ and $S(x, t)=t$ and $\boldsymbol{f}=\mathbf{0}$, see Aramaki [3].

## 4. Continuous dependence on the data of minimizers

In this section, in addition to (1.1) we assume that there exists a constant $c>0$ such that

$$
\left(S_{t}\left(x,|\boldsymbol{a}|^{2}\right) \boldsymbol{a}-S_{t}\left(x,|\boldsymbol{b}|^{2}\right) \boldsymbol{b}\right) \cdot(\boldsymbol{a}-\boldsymbol{b}) \geq\left\{\begin{array}{c}
c|\boldsymbol{a}-\boldsymbol{b}|^{p}  \tag{4.1}\\
\text { if } p \geq 2 \\
c(|\boldsymbol{a}|+|\boldsymbol{b}|)^{p-2}|\boldsymbol{a}-\boldsymbol{b}|^{2} \\
\text { if } 1<p<2
\end{array}\right.
$$

for all $\boldsymbol{a}, \boldsymbol{b} \in \mathbb{R}^{3}$ and $\Omega$ has no holes. We note that (4.1) implies (1.2).
Then we have the following.
Theorem 4.1 Let $\boldsymbol{B}_{0}\left(\mathcal{H}_{T}, \boldsymbol{f}\right) \in B\left(\Omega, \mathcal{H}_{T}\right)$ and $\boldsymbol{B}_{0}\left(\mathcal{H}_{T}^{\prime}, \boldsymbol{f}^{\prime}\right) \in B\left(\Omega, \mathcal{H}_{T}^{\prime}\right)$ be minimizers of $R_{t}^{p}\left(\mathcal{H}_{T}, \boldsymbol{f}\right)$ and $R_{t}^{p}\left(\mathcal{H}_{T}^{\prime}, \boldsymbol{f}^{\prime}\right)$ in (3.9), respectively. Then there exists a constant

$$
C=C\left(p, \Omega,\|\boldsymbol{f}\|_{L^{p^{\prime}}(\Omega)},\left\|\boldsymbol{f}^{\prime}\right\|_{L^{p^{\prime}}(\Omega)},\left\|\mathcal{H}_{T}\right\|_{W^{1-1 / p, p}(\partial \Omega)},\left\|\mathcal{H}_{T}^{\prime}\right\|_{W^{1-1 / p, p}(\partial \Omega)}\right)
$$

such that

$$
\begin{aligned}
& \left\|\boldsymbol{B}_{0}\left(\mathcal{H}_{T}, \boldsymbol{f}\right)-\boldsymbol{B}_{0}\left(\mathcal{H}_{T}^{\prime}, \boldsymbol{f}^{\prime}\right)\right\|_{W^{1, p}(\Omega)}^{p \vee 2} \\
& \leq C\left(\left\|\boldsymbol{f}-\boldsymbol{f}^{\prime}\right\|_{L^{p^{\prime}}(\Omega)}+\max \left\{\left\|\mathcal{H}_{T}-\mathcal{H}_{T}^{\prime}\right\|_{W^{1-1 / p, p}(\partial \Omega)},\left\|\mathcal{H}_{T}-\mathcal{H}_{T}^{\prime}\right\|_{W^{1-1 / p, p}(\partial \Omega)}^{p \vee 2}\right\}\right)
\end{aligned}
$$

where $p \vee 2=\max \{p, 2\}$.

Proof For brevity of notations, we write $\boldsymbol{B}=\boldsymbol{B}_{0}\left(\mathcal{H}_{T}, \boldsymbol{f}\right)$ and $\boldsymbol{B}^{\prime}=\boldsymbol{B}_{0}\left(\mathcal{H}_{T}^{\prime}, \boldsymbol{f}^{\prime}\right)$. Then $\boldsymbol{B}$ and $\boldsymbol{B}^{\prime}$ are weak solutions of the following equations:

$$
\begin{cases}\operatorname{curl}\left[S_{t}\left(x,|\operatorname{curl} \boldsymbol{B}|^{2}\right) \operatorname{curl} \boldsymbol{B}\right]=\boldsymbol{f}, \operatorname{div} \boldsymbol{B}=0 & \text { in } \Omega, \\ \boldsymbol{B}_{T}=\mathcal{H}_{T} & \text { on } \partial \Omega\end{cases}
$$

and

$$
\begin{cases}\operatorname{curl}\left[S_{t}\left(x,\left|\operatorname{curl} \boldsymbol{B}^{\prime}\right|^{2}\right) \operatorname{curl} \boldsymbol{B}^{\prime}\right]=\boldsymbol{f}^{\prime}, \operatorname{div} \boldsymbol{B}^{\prime}=0 & \text { in } \Omega \\ \boldsymbol{B}_{T}^{\prime}=\mathcal{H}_{T}^{\prime} & \text { on } \partial \Omega\end{cases}
$$

Then we have

$$
\begin{aligned}
\int_{\Omega} \boldsymbol{f} \cdot\left(\boldsymbol{B}-\boldsymbol{B}^{\prime}\right) d x= & \int_{\Omega} S_{t}\left(x,|\operatorname{curl} \boldsymbol{B}|^{2}\right) \operatorname{curl} \boldsymbol{B} \cdot \operatorname{curl}\left(\boldsymbol{B}-\boldsymbol{B}^{\prime}\right) d x \\
& +\int_{\partial \Omega}\left\langle\mathcal{H}_{T}-\mathcal{H}_{T}^{\prime}, \boldsymbol{\nu} \times S_{t}\left(x,|\operatorname{curl} \boldsymbol{B}|^{2}\right) \operatorname{curl} \boldsymbol{B}\right\rangle d S
\end{aligned}
$$

and

$$
\begin{aligned}
\int_{\Omega} \boldsymbol{f}^{\prime} \cdot\left(\boldsymbol{B}-\boldsymbol{B}^{\prime}\right) d x= & \int_{\Omega} S_{t}\left(x,\left|\operatorname{curl} \boldsymbol{B}^{\prime}\right|^{2}\right) \operatorname{curl} \boldsymbol{B}^{\prime} \cdot \operatorname{curl}\left(\boldsymbol{B}-\boldsymbol{B}^{\prime}\right) d x \\
& +\int_{\partial \Omega}\left\langle\mathcal{H}_{T}-\mathcal{H}_{T}^{\prime}, \boldsymbol{\nu} \times S_{t}\left(x,\left|\operatorname{curl} \boldsymbol{B}^{\prime}\right|^{2}\right) \operatorname{curl} \boldsymbol{B}^{\prime}\right\rangle d S
\end{aligned}
$$

Therefore, we have

$$
\begin{aligned}
& \int_{\Omega}\left(S_{t}\left(x,|\operatorname{curl} \boldsymbol{B}|^{2}\right) \operatorname{curl} \boldsymbol{B}-S_{t}\left(x,\left|\operatorname{curl} \boldsymbol{B}^{\prime}\right|^{2}\right) \operatorname{curl} \boldsymbol{B}^{\prime}\right) \cdot\left(\operatorname{curl} \boldsymbol{B}-\operatorname{curl} \boldsymbol{B}^{\prime}\right) d x \\
&= \int_{\Omega}\left(\boldsymbol{f}-\boldsymbol{f}^{\prime}\right) \cdot\left(\boldsymbol{B}-\boldsymbol{B}^{\prime}\right) d x \\
&-\int_{\partial \Omega}\left\langle\mathcal{H}_{T}-\mathcal{H}_{T}^{\prime}, \boldsymbol{\nu} \times\left(S_{t}\left(x,|\operatorname{curl} \boldsymbol{B}|^{2}\right) \operatorname{curl} \boldsymbol{B}\right.\right. \\
&\left.\left.-S_{t}\left(x,\left|\operatorname{curl} \boldsymbol{B}^{\prime}\right|^{2}\right) \operatorname{curl} \boldsymbol{B}^{\prime}\right)\right\rangle d S \\
& \leq\left\|\boldsymbol{f}-\boldsymbol{f}^{\prime}\right\|_{L^{p^{\prime}}(\Omega)}\left\|\boldsymbol{B}-\boldsymbol{B}^{\prime}\right\|_{L^{p}(\Omega)} \\
&+C\left\|\mathcal{H}_{T}-\mathcal{H}_{T}^{\prime}\right\|_{W^{1-1 / p, p}(\partial \Omega)}\left(\| S_{t}\left(x,|\operatorname{curl} \boldsymbol{B}|^{2}\right) \operatorname{curl} \boldsymbol{B}\right. \\
&\left.-S_{t}\left(x,\left|\operatorname{curl} \boldsymbol{B}^{\prime}\right|^{2}\right) \operatorname{curl} \boldsymbol{B}^{\prime}\left\|_{L^{p^{\prime}}(\Omega)}+\right\| \boldsymbol{f}-\boldsymbol{f}^{\prime} \|_{L^{p^{\prime}}(\Omega)}\right) \\
& \leq\left\|\boldsymbol{f}-\boldsymbol{f}^{\prime}\right\|_{L^{p^{\prime}}(\Omega)}\left(\|\boldsymbol{B}\|_{L^{p}(\Omega)}+\left\|\boldsymbol{B}^{\prime}\right\|_{L^{p}(\Omega)}\right) \\
&+C\left\|\mathcal{H}_{T}-\mathcal{H}_{T}^{\prime}\right\|_{W^{1-1 / p, p}(\partial \Omega)}\left(\|\operatorname{curl} \boldsymbol{B}\|_{L^{p}(\Omega)}^{p / p^{\prime}}\right. \\
&+\left\|\operatorname{curl} \boldsymbol{B}^{\prime}\right\|_{L^{p^{\prime}}(\Omega)}^{p / p^{\prime}} \\
&\left.+\|\boldsymbol{f}\|_{L^{p^{\prime}}(\Omega)}+\left\|\boldsymbol{f}^{\prime}\right\|_{L^{p^{\prime}}(\Omega)}\right) \\
& \leq C_{1}\left(\left\|\boldsymbol{f}-\boldsymbol{f}^{\prime}\right\|_{L^{p^{\prime}}(\Omega)}+\left\|\mathcal{H}_{T}-\mathcal{H}_{T}^{\prime}\right\|_{W^{1-1 / p, p}(\partial \Omega)}\right)
\end{aligned}
$$

When $p \geq 2$, by the monotonicity (4.1), we have

$$
\left\|\operatorname{curl}\left(\boldsymbol{B}-\boldsymbol{B}^{\prime}\right)\right\|_{L^{p}(\Omega)}^{p} \leq C\left(\left\|\boldsymbol{f}-\boldsymbol{f}^{\prime}\right\|_{L^{p^{\prime}}(\Omega)}+\left\|\mathcal{H}_{T}-\mathcal{H}_{T}^{\prime}\right\|_{W^{1-1 / p, p}(\partial \Omega)}\right)
$$

Since $\Omega$ has no holes, it follows from Lemma 2.2 (ii) and the remark that

$$
\begin{aligned}
\left\|\boldsymbol{B}-\boldsymbol{B}^{\prime}\right\|_{W^{1, p}(\Omega)}^{p} & \leq C(\Omega)\left(\left\|\operatorname{curl}\left(\boldsymbol{B}-\boldsymbol{B}^{\prime}\right)\right\|_{L^{p}(\Omega)}^{p}+\left\|\boldsymbol{B}_{T}-\boldsymbol{B}_{T}^{\prime}\right\|_{W^{1-1 / p, p}(\partial \Omega)}\right) \\
& \leq C\left(\left\|\boldsymbol{f}-\boldsymbol{f}^{\prime}\right\|_{L^{p^{\prime}}(\Omega)}+\max \left\{\left\|\mathcal{H}_{T}-\mathcal{H}_{T}^{\prime}\right\|_{W^{1-1 / p, p}(\partial \Omega)},\left\|\mathcal{H}_{T}-\mathcal{H}_{T}^{\prime}\right\|_{W^{1-1 / p, p}(\partial \Omega)}^{p}\right\}\right)
\end{aligned}
$$

When $1<p<2$, by the monotonicity (4.1), we have

$$
\int_{\Omega}\left(|\operatorname{curl} \boldsymbol{B}|+\left|\operatorname{curl} \boldsymbol{B}^{\prime}\right|\right)^{p-2}\left|\operatorname{curl}\left(\boldsymbol{B}-\boldsymbol{B}^{\prime}\right)\right|^{2} d x \leq C\left(\left\|\boldsymbol{f}-\boldsymbol{f}^{\prime}\right\|_{L^{p^{\prime}}(\Omega)}+\left\|\mathcal{H}_{T}-\mathcal{H}_{T}^{\prime}\right\|_{W^{1-1 / p, p}(\partial \Omega)}\right)
$$

If we use the reverse Hölder inequality (cf. Sobolev [14, p. 8]) with $s=p / 2, s^{\prime}=p /(p-2)$, we have

$$
\int_{\Omega}\left(|\operatorname{curl} \boldsymbol{B}|+\left|\operatorname{curl} \boldsymbol{B}^{\prime}\right|\right)^{p-2}\left|\operatorname{curl}\left(\boldsymbol{B}-\boldsymbol{B}^{\prime}\right)\right|^{2} d x \geq\left(\int_{\Omega}\left(|\operatorname{curl} \boldsymbol{B}|+\left|\operatorname{curl} \boldsymbol{B}^{\prime}\right|\right)^{p} d x\right)^{(p-2) / p}\left\|\operatorname{curl} \boldsymbol{B}-\operatorname{curl} \boldsymbol{B}^{\prime}\right\|_{L^{p}(\Omega)}^{2}
$$

Here we have

$$
\left(\int_{\Omega}\left(|\operatorname{curl} \boldsymbol{B}|+\left|\operatorname{curl} \boldsymbol{B}^{\prime}\right|\right)^{p} d x\right)^{(2-p) / p} \leq D_{1}\left(\|\operatorname{curl} \boldsymbol{B}\|_{L^{p}(\Omega)}^{p}+\left\|\operatorname{curl} \boldsymbol{B}^{\prime}\right\|_{L^{p}(\Omega)}^{p}\right)^{(2-p) / p} \leq D_{2}
$$

Hence,

$$
\begin{aligned}
\left\|\operatorname{curl}\left(\boldsymbol{B}-\boldsymbol{B}^{\prime}\right)\right\|_{L^{2}(\Omega)}^{2} & \leq D_{3} \int_{\Omega}\left(|\operatorname{curl} \boldsymbol{B}|+\left|\operatorname{curl} \boldsymbol{B}^{\prime}\right|\right)^{p-2}\left|\operatorname{curl}\left(\boldsymbol{B}-\boldsymbol{B}^{\prime}\right)\right|^{2} d x \\
& \leq C\left(\left\|\boldsymbol{f}-\boldsymbol{f}^{\prime}\right\|_{L^{p^{\prime}}(\Omega)}+\left\|\mathcal{H}_{T}-\mathcal{H}_{T}^{\prime}\right\|_{W^{1-1 / p, p}(\partial \Omega)}\right)
\end{aligned}
$$

Since $\Omega$ has no holes, it follows from Lemma 2.2 (ii) and the remark that

$$
\begin{aligned}
\left\|\boldsymbol{B}-\boldsymbol{B}^{\prime}\right\|_{W^{1, p}(\Omega)}^{2} & \leq C(\Omega)\left(\left\|\operatorname{curl}\left(\boldsymbol{B}-\boldsymbol{B}^{\prime}\right)\right\|_{L^{p}(\Omega)}^{2}+\left\|\boldsymbol{B}_{T}-\boldsymbol{B}_{T}^{\prime}\right\|_{W^{1-1 / p, p}(\partial \Omega)}^{2}\right) \\
& \leq C\left(\left\|\boldsymbol{f}-\boldsymbol{f}^{\prime}\right\|_{L^{p^{\prime}}(\Omega)}+\max \left\{\left\|\mathcal{H}_{T}-\mathcal{H}_{T}^{\prime}\right\|_{W^{1-1 / p, p}(\partial \Omega)},\left\|\mathcal{H}_{T}-\mathcal{H}_{T}^{\prime}\right\|_{W^{1-1 / p, p}(\partial \Omega)}^{2}\right\}\right)
\end{aligned}
$$

This completes the proof.

Corollary 4.2 The minimizer $\boldsymbol{B}_{0}$ of (3.9) is continuous in $W^{1, p}\left(\Omega, \mathbb{R}^{3}\right)$ with respect to the date $\boldsymbol{f} \in L^{p^{\prime}}\left(\Omega, \mathbb{R}^{3}\right)$ and $\mathcal{H}_{T} \in W^{1-1 / p, p}(\partial \Omega)$; that is to say, if $\boldsymbol{f}_{j} \rightarrow \boldsymbol{f}$ in $L^{p^{\prime}}\left(\Omega, \mathbb{R}^{3}\right)$ and $\mathcal{H}_{j, T} \rightarrow \mathcal{H}_{T}$ in $W^{1-1 / p, p}(\partial \Omega)$, then

$$
\boldsymbol{B}_{0}\left(\mathcal{H}_{j, T}, \boldsymbol{f}_{j}\right) \rightarrow \boldsymbol{B}_{0}\left(\mathcal{H}_{T}, \boldsymbol{f}\right) \text { in } W^{1, p}\left(\Omega, \mathbb{R}^{3}\right)
$$

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## ARAMAKI/Turk J Math

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