

On Holomorphic poly-Norden Manifolds

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Abstract: In this paper, we investigated a new manifold with a poly-Norden structure, which is inspired by the positive root of the equation $x^2 - mx - 1 = 0$. We call this new manifold as holomorphic poly-Norden manifolds. We examine some properties of the Riemann curvature tensor and give an example of this manifold. Then, we define a different connection on this manifold which is named the semisymmetric metric poly F-connection and study some properties of the curvature and torsion tensor field according to this connection.

Key words: Poly-Norden structure, semisymmetric metric connection, Tachibana operator, bronze ratio

1. Introduction

The theory of differential structures on manifolds is studied with great interest. In [19], the authors have extensively investigated complex, product, contact, and f-structures. Later, a very interesting structure was defined on the manifolds, which is called the golden-structure [1]. In fact, the golden-structure is inspired by the equation $x^2 - x - 1 = 0$, whose positive root $\eta = \frac{1+\sqrt{5}}{2} = 1.61803398874989\dots$ is the golden ratio. If the equation $\varphi^2 - \varphi - I = 0$ is provided on manifold M , then (M, φ) is called golden manifold, where φ is the tensor field of type $(1, 1)$ on the manifold.

In [9], the authors defined metallic structures which are the generalization of the golden structure. For integers p and q , the metallic ratio $\sigma_{p,q} = \frac{p+\sqrt{p^2+4q}}{2}$ is the root of the equation $x^2 - px - q = 0$. Also, a manifold M endowed with the tensor field J of type $(1, 1)$, such that $J^2 - pJ - qI = 0$, is named metallic manifold. Many authors have made interesting studies on golden and metallic manifolds. In one of them [4], they defined a semisymmetric metric F -connection on golden manifolds and made studies on it. A semisymmetric connection $\bar{\nabla}$ is a connection whose torsion tensor checks the equation $S(U, V) = w(V)U - w(U)V$, where U, V are vector fields and w is a covector field. In addition, if this connection holds the requirements $\bar{\nabla}g = 0$ and $\bar{\nabla}F = 0$, then this connection is called semisymmetric metric F -connection. See [2, 3, 5, 11, 13, 17, 18] studies for more information.

The new bronze ratio is defined by

$$B_m = \frac{m + \sqrt{m^2 - 4}}{2},$$

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which is the positive root of the equation $x^2 - mx + 1 = 0$ [10]. In [14], by inspiring from the ratio, the author introduced a new structure on a manifold, which is called a poly-Norden structure. In his work, the author examined some geometric properties of the poly-Norden manifold and investigated certain maps between poly-Norden manifolds and other manifolds endowed with different structures.

A poly-Norden structure on a differentiable manifold M is a $(1, 1)$ -type tensor field (affinor) F , which satisfies the relation $F^2 = mF - I$, where I is the identity operator on the Lie algebra of vector fields on the manifold. Thus, the pair (M, F) is named an almost poly-Norden manifold. We say that a semi-Riemann metric g is pure (or self-adjoint) with respect to a poly-Norden structure F if $g(FU, V) = g(U, FV)$ for any vector fields U, V . Also, if $g(FU, FV) = mg(FU, V) - g(U, V)$, then the semi-Riemann metric g is called a F -compatible metric (see [6, 7]). So, an almost poly-Norden manifold (M, F) endowed with a semi-Riemann metric g is called an almost poly-Norden semi-Riemann manifold and is represented by (M, g, F) [14]. Also, see [12] study for more information on almost poly-Norden manifolds.

In this paper, we derive the integrability condition of the almost poly-Norden structure F on (M, g, F) with the help of a different operator whose name is φ operator (or Tachibana operator) [16]. Then, we named this manifold (M, g, F) as holomorphic poly-Norden manifold because it satisfies the condition $\varphi_F g = 0$ and by examining the curvature property, we gave an example of such manifold. After that, we introduced a connection ${}^p\nabla$ with semisymmetric torsion endowed with poly-Norden structure F on this manifold and proved that this new connection satisfies the equations ${}^p\nabla g = 0$ and ${}^p\nabla F = 0$, that is, ${}^p\nabla$ is a semisymmetric metric F -connection. Finally, by using the operator φ , we investigated the curvature and torsion properties of this connection ${}^p\nabla$.

2. Preliminaries

Let M_n be $(n = 2k)$ differentiable manifold of class C^∞ . Throughout this paper, all connections and tensor fields on the manifold will be assumed to be of class C^∞ . In addition, the set of tensor fields of type (p, q) will be represented by $\mathfrak{S}_q^p(M_n)$. For example, the set of vector and covector fields will be indicated by $\mathfrak{S}_0^1(M_n)$ and $\mathfrak{S}_1^0(M_n)$, respectively. Now, let us give some definitions that we will use in this article.

Definition 2.1 ([16]) *Let M_n be differentiable manifold. For any $K \in \mathfrak{S}_q^0(M_n)$, if the following condition holds, then the tensor field K is called a pure tensor field.*

$$\begin{aligned} K(JV_1, V_2, \dots, V_q) &= K(V_1, JV_2, \dots, V_q) \\ &= \dots = K(V_1, V_2, \dots, JV_q), \end{aligned}$$

where $V_1, V_2, \dots, V_q \in \mathfrak{S}_0^1(M_n)$ and $J \in \mathfrak{S}_1^1(M_n)$.

Definition 2.2 ([16]) *Let M_n be differentiable manifold. If K is a pure tensor field, then the operator φ (or Tachibana operator) applied to this tensor is given by*

$$\begin{aligned} &(\varphi_J K)(X, V_1, V_2, \dots, V_q) \tag{2.1} \\ &= (JX)(K(V_1, V_2, \dots, V_q)) - X(K(JV_1, V_2, \dots, V_q)) \\ &\quad + \sum_{i=1}^q K(V_1, \dots, (L_{V_i} J)X, \dots, V_q), \end{aligned}$$

where $X \in \mathfrak{S}_0^1(M_n)$ and L_V represents the Lie differentiation according vector field V .

Let J be a complex structure, that is, $J^2 = -I$. In the equation (2.1), if $\varphi_J K = 0$, then the vector field K is called a holomorphic (or analytic) tensor field. The Riemann metric g on an almost complex manifold (M_n, J) is called a Norden (or anti-Hermitian) manifold if it satisfies the condition

$$g(JU, V) = g(U, JV) \text{ or } g(JU, JV) = -g(U, V),$$

where $U, V \in \mathfrak{S}_0^1(M_n)$. It is easy to see that g is a semi-Riemannian metric [6]. Then, the triplet (M_n, g, J) is named almost Norden manifold. Besides, if $\nabla J = 0$, then the triplet (M_n, g, J) becomes a Norden (anti-Kähler) manifold, where ∇ is the Riemannian connection of g .

On almost Norden manifold (M_n, g, J) , if $\varphi_J g = 0$, then g is holomorphic and this manifold is called almost holomorphic Norden manifold.

3. Holomorphic poly-Norden manifolds

In [14], the author (Propositions 3.4 and 3.5) shows that complex and poly-Norden structures will be written in terms of each other, such that

$$F_{\pm} = \frac{m}{2}I \pm \frac{\sqrt{4-m^2}}{2}J \tag{3.1}$$

and

$$J_{\pm} = \pm \left(\frac{-m}{\sqrt{4-m^2}}I + \frac{2}{\sqrt{4-m^2}}F \right),$$

where $-2 < m < 2$. From the equation (2.1) and (3.1), we obtain

$$\varphi_F K = \frac{\sqrt{4-m^2}}{2}\varphi_J K \tag{3.2}$$

and from here, we can easily say that if $\varphi_F K = 0$, then the tensor K is holomorphic. This means that we can study holomorphicity on the almost poly-Norden semi-Riemann manifold (M_n, g, F) .

Theorem 3.1 *Let (M_n, g, F) be an almost poly-Norden semi-Riemann manifold. If ∇ denotes the Levi-Civita connection of the metric g , then $\nabla F = 0$ if and only if $\varphi_F g = 0$.*

Proof From the covariant derivation of the $g(FU, V) = g(U, FV)$ with respect to Riemann connection ∇ , we obtain

$$g((\nabla_X F)U, V) = g(U, (\nabla_X F)V).$$

Applying φ to the Riemannian tensor g and from $L_U V = [U, V] = \nabla_U V - \nabla_V U$, we get

$$\begin{aligned} (\varphi_{FX}g)(U, V) &= (FX)g(U, V) - Xg(FU, V) \\ &\quad + g((L_U F)X, V) + g(U, (L_V F)X) \\ &= -g((\nabla_X F)U, V) + g((\nabla_U F)X, V) + g(X, (\nabla_V F)U) \end{aligned}$$

and

$$(\varphi_{FV}g)(U, X) = -g((\nabla_V F)U, X) + g((\nabla_U F)V, X) + g(V, (\nabla_X F)U). \tag{3.3}$$

From the last two equations, we have

$$(\varphi_{FX}g)(U, V) + (\varphi_{FV}g)(U, X) = 2g((\nabla_U F) V, X). \tag{3.4}$$

It is clear that in the equation (3.3), if $\nabla F = 0$, then $\varphi_F g = 0$ and in the equation (3.4), if $\varphi_F g = 0$, then $\nabla F = 0$. □

Also, from the equation (3.2), we have

$$\varphi_F g = \frac{\sqrt{4 - m^2}}{2} \varphi_J g.$$

Then, if $\varphi_F g = 0$ (or $\nabla F = 0$), then the triplet (M_n, g, F) is called holomorphic poly-Norden manifold.

Twin metric G of the almost poly-Norden semi-Riemann manifold (M_n, g, F) is defined by

$$G(U, V) = g(FU, V), \tag{3.5}$$

for $X, Y \in \mathfrak{S}_0^1(M_n)$. Then,

$$\begin{aligned} G(U, V) &= g(FU, V) \\ &= g(V, FU) \\ &= g(FY, U) = G(V, U) \end{aligned}$$

and

$$\begin{aligned} G(FU, V) &= g(F^2U, V) \\ &= g(FU, FV) = G(U, FV), \end{aligned}$$

that is, twin metric G is both symmetric and pure according to poly-Norden structure F . From the covariant derivation of the equation (3.5) with respect to Riemann connection ∇ , we obtain

$$\begin{aligned} (\nabla_X G)(U, V) &= (\nabla_X g)(FU, V) + g((\nabla_X F)U, V) \\ &= g((\nabla_X F)U, V) \end{aligned}$$

and then,

Proposition 3.2 *Let (M_n, g, F) be a holomorphic poly-Norden manifold. The Riemann connection of the metric g equals to the Riemann connection of the twin metric G , i.e., ${}^G\nabla = \nabla$.*

Let gR and ${}^G R$ be Riemann curvature tensors of the metric g and the twin metric G , respectively. From the proposition 3.2, we can easily see that ${}^gR = {}^G R$. The Ricci identity for poly-Norden structure F on holomorphic poly-Norden manifold (M_n, g, F) is as follows:

$${}^gR(U, V, FZ) - F({}^gR(U, V, Z)) = 0. \tag{3.6}$$

Also, for the $(0, 4)$ -type of the curvature tensor gR , we get ${}^gR(U, V, Z, W) = g(R(U, V, Z), W)$ and

$$\begin{aligned} {}^gR(U, V, FZ, W) &= g({}^gR(U, V, FZ), W) \\ &= g(F{}^gR(U, V, Z), W) \\ &= g({}^gR(U, V, Z), FW) \\ &= {}^gR(U, V, Z, FW), \end{aligned}$$

that is, the curvature tensor gR is pure according to Z and W . Besides, from the ${}^gR(U, V, Z, W) = {}^gR(Z, W, U, V)$ property of the curvature tensor gR , we have

$${}^gR(FU, V, Z, W) = {}^gR(U, FV, Z, W).$$

Finally, for ${}^gR = {}^G R$ and (3.5), the curvature tensor ${}^G R$ of the twin metric G is as follows:

$$\begin{aligned} {}^G R(U, V, Z, W) &= G({}^G R(U, V, Z), W) \\ &= g(F({}^G R(U, V, Z)), W) \\ &= g({}^G R(U, V, Z), FW) \\ &= {}^gR(U, V, Z, FW) \end{aligned}$$

and

$${}^G R(Z, W, U, V) = {}^gR(Z, FW, U, V).$$

From the last two equations, we obtain ${}^gR(U, V, Z, FW) = {}^gR(Z, FW, U, V)$. After all, we say that the curvature tensor gR is pure with regard to poly-Norden structure F , i.e.

$$\begin{aligned} {}^gR(FU, V, Z, W) &= {}^gR(U, FV, Z, W) \\ &= {}^gR(U, V, FZ, W) = {}^gR(U, V, Z, FW). \end{aligned}$$

Then,

Theorem 3.3 *Let (M_n, g, F) be a holomorphic poly-Norden manifold. Then, $\varphi_F {}^gR = 0$, that is, the curvature tensor gR is a holomorphic tensor.*

Proof From the covariant derivation of the equation (3.6), we have,

$$(\nabla_X {}^gR)(FU_1, U_2, U_3) = F(\nabla_X {}^gR)(U_1, U_2, U_3). \tag{3.7}$$

If the operator φ is applied to the Riemann curvature tensor gR , we obtain

$$\begin{aligned} (\varphi_{FX} {}^gR)(U_1, U_2, U_3, U_4) &= (\nabla_{FX} {}^gR)(U_1, U_2, U_3, U_4) \\ &\quad - (\nabla_X {}^gR)(FU_1, U_2, U_3, U_4). \end{aligned} \tag{3.8}$$

Substituting (3.7) in (3.8) and using the Bianchi's 2nd identity for the tensor field gR , we obtain

$$\begin{aligned}
 (\varphi_{FX} {}^gR)(U_1, U_2, U_3, U_4) &= g((\nabla_{FX} {}^gR)(U_1, U_2, U_3) - (\nabla_X {}^gR)(FU_1, U_2, U_3), U_4) \\
 &= g((\nabla_{FX} {}^gR)(U_1, U_2, U_3) - F(\nabla_X {}^gR)(U_1, U_2, U_3), U_4) \\
 &= -g((\nabla_{U_2} {}^gR)(FX, U_1, U_3) + (\nabla_{U_1} {}^gR)(U_2, FX, U_3) \\
 &\quad + F(\nabla_X {}^gR)(U_1, U_2, U_3), U_4) \\
 &= -g(F((\nabla_{U_2} {}^gR)(X, U_1, U_3) + (\nabla_{U_1} {}^gR)(U_2, X, U_3) \\
 &\quad + (\nabla_X {}^gR)(U_1, U_2, U_3), U_4) \\
 &= -g(\sigma_{(X, U_1, U_2)}(\nabla_X {}^gR)(U_1, U_2, U_3), FU_4) \\
 &= 0
 \end{aligned}$$

where σ represents the cyclic sum over X , U_1 , and U_2 . Finally, from the equation (3.2), we have

$$\varphi_F {}^gR = \frac{\sqrt{4 - m^2}}{2} \varphi_J {}^gR,$$

namely, the curvature tensor gR is a holomorphic tensor. □

Example 3.4 Let \mathbb{R}_{2n} be a semi-Euclidean space endowed with semi-Euclidean metric g , that is,

$$g = \begin{pmatrix} \delta_i^j & 0 \\ 0 & -\delta_{\bar{i}}^{\bar{j}} \end{pmatrix}$$

where $i, j = 1, \dots, n$, $\bar{i}, \bar{j} = n + 1, \dots, 2n$. Also, let \mathbb{C}_n be a complex space with \mathbb{R}_{2n} such that

$$s : z \in \mathbb{C}_n \longrightarrow s(z) = Z \in \mathbb{R}_{2n},$$

where $z = (z_1, z_2, \dots, z_n)$, $s(z) = Z = (x_1, x_2, \dots, x_n; y_1, y_2, \dots, y_n)$ and $z_t = x_t + iy_t$, $t = 1, 2, \dots, n$. Then, the complex structure J on \mathbb{R}_{2n} is given by

$$J = \begin{pmatrix} 0 & \delta_i^j \\ -\delta_{\bar{i}}^{\bar{j}} & 0 \end{pmatrix}.$$

From here, we easily see that $g_{im}F_j^m = g_{mj}F_i^m =$, i.e. the structure J is compatible (purity) with metric g and then (\mathbb{R}_{2n}, J, g) is a holomorphic Norden Euclidean space. Also, poly-Norden structures F_{\pm} on \mathbb{R}_{2n} obtained from complex structure J are as follows:

$$F_{\pm} = \begin{pmatrix} \frac{m}{2} \delta_i^j & \pm \frac{\sqrt{4-m^2}}{2} \delta_{\bar{i}}^{\bar{j}} \\ \mp \frac{\sqrt{4-m^2}}{2} \delta_{\bar{i}}^{\bar{j}} & \frac{m}{2} \delta_i^j \end{pmatrix}$$

and the triple (\mathbb{R}_{2n}, F, g) is called a holomorphic poly-Norden Euclidean space.

4. Semisymmetric metric poly F -connection

In this section, we are going to study the holomorphic poly-Norden manifold endowed with another connection rather than the metric connection.

Theorem 4.1 *Let (M_n, g, F) be a holomorphic poly-Norden manifold and ${}^p\nabla$ be a connection with torsion pT on that manifold such that*

$${}^pT(U, V) = \gamma(V)(U) - \gamma(U)(V) - \gamma(FV)(FU) + \gamma(FU)(FV) \tag{4.1}$$

where $U, V \in \mathfrak{S}_0^1(M_n)$ and $\gamma \in \mathfrak{S}_1^0(M_n)$. If this connection satisfies ${}^p\nabla g = 0$ and ${}^p\nabla F = 0$, then

$$\begin{aligned} {}^p\nabla_U V &= \nabla_U V + \gamma(V)(U) - g(U, V)(W) \\ &\quad - \gamma(FV)(FU) + g(FU, V)(FW), \end{aligned} \tag{4.2}$$

where ∇ stands for the Levi-Civita connection of the metric g and $g(W, Y) = \gamma(Y)$, $W \in \mathfrak{S}_0^1(M_n)$.

Proof It is well known that a new connection ${}^p\nabla$ can be formed with

$${}^p\nabla_U V = \nabla_U V + D(U, V), \tag{4.3}$$

where D is the deformation tensor field of type (1,2). Then, from ${}^pT(U, V) = {}^p\nabla_U V - {}^p\nabla_V U - [U, V]$ and the method of Hayden [8], we obtain

$${}^pT(U, V) = D(U, V) - D(V, U) \tag{4.4}$$

If ${}^p\nabla g = 0$, we have

$$D(U, V, Z) + D(U, Z, V) = 0. \tag{4.5}$$

From the equations (4.4) and (4.5), we have

$${}^pT(U, V, Z) = D(U, V, Z) - D(V, U, Z)$$

$${}^pT(Z, U, V) = D(Z, U, V) - D(U, Z, V)$$

$${}^pT(Z, V, U) = D(Z, V, U) - D(V, Z, U)$$

and then

$${}^pT(U, V, Z) + {}^pT(Z, U, V) + {}^pT(Z, V, U) = 2D(U, V, Z),$$

where ${}^pT(U, V, Z) = g({}^pT(U, V), Z)$.

Substituting (4.1) in the last equation, we get

$$D(U, V) = \gamma(V)(U) - g(U, V)(W) - \gamma(FV)(FU) + g(FU, V)(FW).$$

Also, the connection given by (4.2) satisfies the condition ${}^p\nabla F = 0$. So, this proof is complete. □

From now on, the connection ${}^p\nabla$ will be called semisymmetric metric poly F -connection.

With a simple calculation, we can see that the torsion tensor pT is pure according to poly-Norden structure F , i.e.

$${}^pT(FU, V) = {}^pT(U, FV) = F{}^pT(U, V).$$

Also, in [15], the author has proved that an F -connection is pure if and only if its torsion tensor is pure. Then, we can easily write as following equation:

$${}^p\nabla_{FU}V = {}^p\nabla_U(FV) = F{}^p\nabla_UV.$$

Then,

Theorem 4.2 *Let (M_n, g, F) be a holomorphic poly-Norden manifold. If the covector γ in (4.1) is holomorphic, then the torsion tensor pT is also a holomorphic tensor, i.e. $\varphi_F\gamma = 0$ and $\varphi_F {}^pT = 0$.*

Proof By applying the φ operator to the torsion tensor pT , we get

$$\begin{aligned} (\varphi_{FX} {}^pT)(U, V) &= ({}^p\nabla_{FX} {}^pT)(U, V) - ({}^p\nabla_X {}^pT)(FU, V) \\ &= [({}^p\nabla_{FX}\gamma)(V) - ({}^p\nabla_X\gamma)(FV)](U) \\ &\quad - [({}^p\nabla_{FX}\gamma)(U) - ({}^p\nabla_X\gamma)(FU)](V) \\ &\quad + [({}^p\nabla_{FX}\gamma)(FU) - m({}^p\nabla_X\gamma)(FU) \\ &\quad \quad + ({}^p\nabla_X\gamma)(U)](FV) \\ &\quad - [({}^p\nabla_{FX}\gamma)(FV) - m({}^p\nabla_X\gamma)(FV) \\ &\quad \quad + ({}^p\nabla_X\gamma)(V)](FU). \end{aligned} \tag{4.6}$$

Also, for the covector field γ in the equation (4.1), we obtain

$$\begin{aligned} (\varphi_{FX}\gamma)(U) &= ({}^p\nabla_{FX}\gamma)(U) - ({}^p\nabla_X\gamma)(FU) \\ &= 0 \end{aligned} \tag{4.7}$$

Finally, from the equation (4.6) and (4.7), we get

$$\begin{aligned} (\varphi_{FX} {}^pT)(U, V) &= (\varphi_{FX}\gamma)(V)(U) - (\varphi_{FX}\gamma)(U)(V) \\ &\quad + (\varphi_{FX}\gamma)(FV)(FU) - (\varphi_{FX}\gamma)(FU)(FV) \\ &= 0 \end{aligned}$$

□

Then, we write the following corollary:

Remark 4.3 1. *From the equation (3.2), it is obvious that*

$$\varphi_F\gamma = \frac{\sqrt{4-m^2}}{2}\varphi_J\gamma,$$

and

$$\varphi_F {}^pT = \frac{\sqrt{4-m^2}}{2}\varphi_J {}^pT,$$

2. *If $\varphi_F {}^pT = 0$, from $(\varphi_{FX}{}^pT)(U, V) = ({}^p\nabla_{FX}{}^pT)(U, V) - ({}^p\nabla_X{}^pT)(FU, V)$, we can write*

$$\begin{aligned} ({}^p\nabla_{FX}{}^pT)(U, V) &= ({}^p\nabla_X{}^pT)(FU, V) \\ &= ({}^p\nabla_X{}^pT)(U, FV) = F({}^p\nabla_X{}^pT)(U, V), \end{aligned}$$

that is, the covariant derivation of the torsion tensor pT according to ${}^p\nabla$ is pure according to poly-Norden structure F .

3. The last theorem can also be proved for Riemann connection ∇ , that is, we write $(\varphi_{FX}{}^pT)(U, V) = (\nabla_{FX}{}^pT)(U, V) - (\nabla_X{}^pT)(FU, V)$ and

$$\begin{aligned} (\nabla_{FX}{}^pT)(U, V) &= (\nabla_X{}^pT)(FU, V) \\ &= (\nabla_X{}^pT)(U, FV) = F(\nabla_X{}^pT)(U, V). \end{aligned}$$

Throughout this article, we will assume that $\varphi_F\gamma = 0$, that is,

$$({}^p\nabla_{FX}\gamma)(U) - ({}^p\nabla_X\gamma)(FU) = 0.$$

5. The curvature tensor of semisymmetric metric poly F -connection

It is well-known that the curvature tensor of any linear connection $\bar{\nabla}$ for all vector fields is as follows:

$$\bar{R}(U, V, Z) = (\bar{\nabla}_U\bar{\nabla}_V - \bar{\nabla}_V\bar{\nabla}_U - \bar{\nabla}_{[U, V]})Z.$$

Then, (0, 4)-type of the curvature tensor for the connection (4.2) has the following form:

$$\begin{aligned} {}^pR(U, V, Z, W) &= {}^gR(U, V, Z, W) \\ &+ \varsigma(U, Z)g(V, W) - \varsigma(V, Z)g(U, W) \\ &+ \varsigma(V, W)g(U, Z) - \varsigma(U, W)g(V, Z) \\ &+ \varsigma(V, FZ)g(FU, W) - \varsigma(U, FZ)g(FV, W) \\ &+ \varsigma(U, FW)g(FV, Z) - \varsigma(V, FW)g(FU, Z), \end{aligned} \tag{5.1}$$

where

$$\begin{aligned} \varsigma(U, V) &= (\nabla_U\gamma)(V) - \gamma(U)\gamma(V) + \frac{1}{2}\gamma(W)g(U, V) \\ &+ \gamma(FU)\gamma(FV) - \frac{1}{2}\omega(FW)g(FU, V). \end{aligned} \tag{5.2}$$

It is said that the curvature tensor pR is hold:

$${}^pR(U, V, W, Z) = -{}^pR(U, V, Z, W) = -{}^pR(V, U, Z, W),$$

that is, pR is antisymmetric according to the first and last two components. Also,

$$\varsigma(U, V) - \varsigma(V, U) = (\nabla_U\gamma)(V) - (\nabla_V\gamma)(U) \tag{5.3}$$

and for the exterior differential operator d applied to the covector field ω , we get

$$\begin{aligned} 2(d\gamma)(U, V) &= U\gamma(V) - V\gamma(U) - \gamma([U, V]) \\ &= (\nabla_U\gamma)V + \gamma(\nabla_UV) - (\nabla_V\gamma)U - \gamma(\nabla_VU) - \gamma([U, V]) \\ &= (\nabla_U\gamma)V - (\nabla_V\gamma)U + \gamma(\nabla_UV - \nabla_VU) - \gamma([U, V]) \\ &= (\nabla_U\gamma)(V) - (\nabla_V\gamma)(U). \end{aligned} \tag{5.4}$$

From the equations (5.3) and (5.4), we obtain

$$\begin{aligned} \varsigma(U, V) - \varsigma(V, U) &= (\nabla_U \gamma)(V) - (\nabla_V \gamma)(U) \\ &= 2(d\gamma)(U, V). \end{aligned} \tag{5.5}$$

Then, we write the following corollary.

Corollary 5.1 1. *The covector field γ is closed if and only if the tensor field ς is symmetric.*

2. *If the covector field γ is a gradient, that is $\gamma = \partial f$, then the tensor ς is symmetric.*

For the tensor ς given by (5.2) is pure with regard to poly-Norden structure F , that is,

$$\begin{aligned} \varsigma(U, FV) - \varsigma(FU, V) &= [(\nabla_U \gamma)(FV) - (\nabla_{FU} \gamma)(V)] \\ &= (\varphi_{FU} \gamma)(V) \\ &= 0 \end{aligned}$$

and from the equation (5.5), we get

$$\begin{aligned} &{}^p R(U, V, Z, W) - {}^p R(Z, W, U, V) \\ &= 2(d\gamma)(U, Z)g(V, W) - 2(d\gamma)(V, Z)g(U, W) \\ &\quad + 2(d\gamma)(V, W)g(U, Z) - 2(d\gamma)(U, W)g(V, Z) \\ &\quad + 2(d\gamma)(FV, Z)g(FU, W) - 2(d\gamma)(FU, Z)g(FV, W) \\ &\quad + 2(d\gamma)(FU, W)g(FV, Z) - 2(d\gamma)(FV, W)g(FU, Z), \end{aligned}$$

then,

Proposition 5.2 *For the curvature tensor ${}^p R$, if the covector field γ is closed ($d\gamma = 0$), then ${}^p R(U, V, Z, W) - {}^p R(Z, W, U, V) = 0$.*

By applying the φ operator to the tensor ς , we get

$$\begin{aligned} (\varphi_{FX} \varsigma)(U, V) &= ({}^p \nabla_{FX} \varsigma)(U, V) - ({}^p \nabla_X \varsigma)(FU, V) \\ &= (\nabla_{FX} \varsigma)(U, V) - (\nabla_X \varsigma)(FU, V) \end{aligned} \tag{5.6}$$

From the equation (5.2), we have

$$(\varphi_{FX} \varsigma)(U, V) = (\nabla_{FX} \nabla_U \gamma)(V) - (\nabla_X \nabla_{FU} \gamma)(V). \tag{5.7}$$

In the last equation, if we apply the Ricci identity to the 1-form γ , we obtain

$$(\nabla_{FX} \nabla_U \gamma)(V) = (\nabla_U \nabla_{FX} \gamma)(V) - \frac{1}{2} \gamma(gR(FX, U, V))$$

and

$$\begin{aligned} (\nabla_X \nabla_{FU} \gamma)(V) &= (\nabla_X \nabla_U \gamma)(FV) \\ &= (\nabla_U \nabla_X \gamma)(FV) - \frac{1}{2} \gamma({}^gR(X, U, FV)) \\ &= (\nabla_U \nabla_{FX} \gamma)(V) - \frac{1}{2} \gamma({}^gR(X, FU, V)) \end{aligned}$$

Substituting (5.2) in the equation (5.6), we get

$$\begin{aligned} (\varphi_{FX\varsigma})(U, V) &= -\frac{1}{2} \gamma[{}^gR(FX, U, V) - {}^gR(X, U, FV)] \\ &= 0. \end{aligned}$$

Then,

Proposition 5.3 *Let (M_n, g, F) be a holomorphic poly-Norden manifold. The tensor ς given by the equation (5.2) is a holomorphic tensor, that is, $\varphi_F \varsigma = \frac{\sqrt{4-m^2}}{2} \varphi_J \varsigma$ and*

$$({}^p\nabla_{FX}\varsigma)(U, V) = ({}^p\nabla_X\varsigma)(FU, V) = ({}^p\nabla_X\varsigma)(U, FV). \tag{5.8}$$

Because of the purity of the tensor ς , we say that the curvature tensor of the semisymmetric metric poly F -connection is a pure tensor, namely,

$$\begin{aligned} {}^pR(FU, V, Z, W) &= {}^pR(U, FV, Z, W) \\ &= {}^pR(U, V, FZ, W) = {}^pR(U, V, Z, FW) \end{aligned}$$

and from (2.1) and (5.1), we obtain

$$\begin{aligned} (\varphi_{FX} {}^pR)(U_1, U_2, U_3, U_4) &= ({}^p\nabla_{FX} {}^pR)(U_1, U_2, U_3, U_4) \\ &\quad - ({}^p\nabla_X {}^pR)(FU_1, U_2, U_3, U_4). \end{aligned} \tag{5.9}$$

Substituting (5.1) in the last equation, we have

$$\begin{aligned} &(\varphi_{FX} {}^pR)(U_1, U_2, U_3, U_4) \\ = &({}^p\nabla_{FX} {}^gR)(U_1, U_2, U_3, U_4) - ({}^p\nabla_X {}^gR)(FU_1, U_2, U_3, U_4) \\ &+ (\varphi_{FX\varsigma})(U_1, U_3)g(U_2, U_4) - (\varphi_{FX\varsigma})(U_2, U_3)g(U_1, U_4) \\ &+ (\varphi_{FX\varsigma})(U_2, U_4)g(Y_1, U_3) - (\varphi_{FX\varsigma})(Y_1, Y_4)g(U_2, U_3) \\ &+ (\varphi_{FX\varsigma})(FU_2, U_3)g(FU_1, U_4) - (\varphi_{FX\varsigma})(FU_1, U_3)g(FU_2, U_4) \\ &+ (\varphi_{FX\varsigma})(FU_1, U_4)g(FU_2, U_3) - (\varphi_{FX\varsigma})(FU_2, U_4)g(FU_1, U_3) \end{aligned}$$

From the proposition 5.3 and theorem 3.3, we obtain

$$\begin{aligned} (\varphi_{FX} {}^pR)(U_1, U_2, U_3, U_4) &= ({}^p\nabla_{FX} {}^gR)(U_1, U_2, U_3, U_4) \\ &\quad - ({}^p\nabla_X {}^gR)(FU_1, U_2, U_3, U_4) \\ &= (\varphi_{FX} {}^gR)(U_1, U_2, U_3, U_4) \\ &= 0. \end{aligned}$$

Finally,

Theorem 5.4 *Let (M_n, g, F) be a holomorphic poly-Norden manifold. The curvature tensor pR of the semi-symmetric metric poly F -connection is a holomorphic tensor, i.e. $\varphi_F {}^pR = \frac{\sqrt{4-m^2}}{2} \varphi_J {}^pR$ and*

$$\begin{aligned} ({}^p\nabla_{FX} {}^pR)(U_1, U_2, U_3, U_4) &= ({}^p\nabla_X {}^pR)(FU_1, U_2, U_3, U_4) \\ &= ({}^p\nabla_X {}^pR)(U_1, FU_2, U_3, U_4) \\ &= ({}^p\nabla_X {}^pR)(U_1, U_2, FU_3, U_4) \\ &= ({}^p\nabla_X {}^pR)(U_1, U_2, U_3, FU_4) \\ &= F({}^p\nabla_X {}^pR)(U_1, U_2, U_3, U_4). \end{aligned}$$

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