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# On the geometry of tangent bundle of a hypersurface in $\mathbb{R}^{n+1}$ 

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#### Abstract

In this paper, tangent bundle $T M$ of the hypersurface $M$ in $\mathbb{R}^{n+1}$ has been studied. For hypersurface $M$ given by immersion $f: M \rightarrow \mathbb{R}^{n+1}$, considering the fact that $F=d f: T M \rightarrow \mathbb{R}^{2 n+2}$ is also immersion, $T M$ is treated as a submanifold of $\mathbb{R}^{2 n+2}$. Firstly, an induced metric which is called rescaled induced metric has been defined on $T M$, and the Levi-Civita connection has been calculated for this metric. Next, curvature tensors of tangent bundle TM have been obtained. Finally, the orthonormal frame at the point $(p, u) \in T M$ has been defined and some curvature properties of such a tangent bundle by means of orthonormal frame for a given point have been investigated.


Key words: Tangent bundle, hypersurface, rescaled induced metric, curvature tensor, orthonormal frame

## 1. Introduction

Theory of tangent bundle has attracted the attention of scientists working in math and physics and has received great importance in these areas. In recent years, there have been many publications examining the differential geometric properties of the tangent bundle using different approaches, methods, and notations. In 1958, Sasaki defined a new metric on the tangent bundle [12] and this metric became the focus of interest for many mathematicians working on the theory of tangent bundle. Moreover, after Dombrowski has established the relationship between the geometry of the tangent bundle with Sasaki metric and the base manifold [6], interest in tangent bundle theory has grown even more. Due to the relationship between almost complex structure $J$ and the tangent bundle $T M$ of a Riemannian manifold $M$, one naturally expects very good features associated with this almost complex structure vis-a-vis the complex geometry. However, the Sasaki metric on $T M$ causes hindrance on the almost complex structure and does not allow it even to be a complex structure unless the base manifold is flat. This problem in the Sasaki metric has led researchers to search for other metrics on the tangent bundle for example Cheeger-Gromoll metric, Oproiu metric (cf. [1, 3, 7-11]). Since the projection $\pi: T M \rightarrow M$ is a Riemannian submersion, all metrics defined on $T M$ are appropriate with this smooth projection. This is why these metrics are called natural metrics. However, in [4] Deshmukh et al. demonstrated that induced metric on $T M$ is not generally a natural metric. In addition, they proved that the smooth map is an immersion and therefore considered tangent bundle $T M$ of a hypersurface $M$ as an immersed submanifold. In [5], Deshmukh and Al-Shaikh defined induced metric on $T M$ to search its geometry using the fact that $T M$ is a submanifold of the Euclidean space $\mathbb{R}^{2 n+2}$. Moreover, the authors found that there is a reduction in the codimension of $T M$, so they examined the differential geometric properties of $T M$ in terms of being hypersurface of $\mathbb{R}^{2 n+1}$.

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In 2018, Al-Shaikh constituted an orthonormal frame on $M^{3}$ which is submanifold of $\mathbb{R}^{4}$ considering a special case of [5] and examined the properties of tangent bundle through this frame [2]. Because tangent bundle of a manifold is not compact, it cannot admit a Riemannian metric of strictly positive sectional curvature, it is important to find a metric on the tangent bundle $T M$ which has nonnegative sectional curvature.

The aim of this study is to introduce an induced metric on tangent bundle, which is called a rescaled induced metric, and to investigate some curvature properties of such a tangent bundle.

For this purpose, firstly, the covariant derivatives of the horizontal and vertical vector fields in the direction of each other are calculated, then the curvature tensors $(0,4)$ and $(1,3)$ types are obtained. Later on, the orthonormal frame at the point $(p, u) \in T M$ is defined and the mean curvature and sectional curvatures of tangent bundle $T M$ were obtained by means of the orthonormal frame for a given point.

## 2. Tangent bundle of a hypersurface

Consider the orientable hypersurface $M$ given by immersion $f: M \rightarrow \mathbb{R}^{n+1}$ and tangent bundle $T M$ of the hypersurface $M$ with immersion $F: T M \rightarrow \mathbb{R}^{2 n+2}$ (See. Theorem 3.2 in [4]). We denote the induced metrics on $M, T M$ by $g, \tilde{g}$ and the Euclidean metric on $\mathbb{R}^{n+1}$ as well as that on $\mathbb{R}^{2 n+2}$ by $\langle$,$\rangle and the Riemannian$ connections on $M, T M, \mathbb{R}^{n+1}, \mathbb{R}^{2 n+2}$ by $\nabla, \widetilde{\nabla}, D, \widetilde{D}$, respectively. Let $N$ and $S$ be the unit normal vector field and the shape operator of the hypersurface $M$. Then we have the following:

Lemma 2.1 If an oriantable hypersurface of $\mathbb{R}^{n+1}$ is $M$ and its tangent bundle as submanifold of $\mathbb{R}^{2 n+2}$ is $T M$, then the metric $\tilde{g}$ on $T M$, which we call rescaled induced metric, for $P=(p, u) \in T M$ satisfies:
(i) $\tilde{g}_{P}\left(X_{P}^{h}, Y_{P}^{h}\right)=a\left\{g_{p}\left(X_{p}, Y_{p}\right)+g_{p}\left(S_{p}\left(X_{p}\right), u\right) g_{p}\left(S_{p}\left(Y_{p}\right), u\right)\right\}$
(ii) $\tilde{g}_{P}\left(X_{P}^{h}, Y_{P}^{v}\right)=0$
(iii) $\tilde{g}_{P}\left(X_{P}^{v}, Y_{P}^{v}\right)=g_{p}\left(X_{p}, Y_{p}\right)$
where $a: M \rightarrow \mathbb{R}$ is a positive function.

Theorem 2.2 Let $M$ be an oriantable hypersurface of the Euclidean space $\mathbb{R}^{n+1}$ and $T M$ be its tangent bundle as submanifold of $\mathbb{R}^{2 n+2}$. Then
(i) $\tilde{\nabla}_{X^{h}} Y^{h}=\left(\nabla_{X} Y\right)^{h}+\left(A_{f}(X, Y)\right)^{h}-\frac{1}{2}(R(X, Y) u)^{v}$
(ii) $\tilde{\nabla}_{X^{h}} Y^{v}=\left(\nabla_{X} Y\right)^{v}+g(S(X), Y) N^{v}$
(iii) $\tilde{\nabla}_{X^{v}} Y^{h}=g(S(Y), X) N^{v}$
(iv) $\tilde{\nabla}_{X^{v}} Y^{v}=0$

Proof If Kozul's formula is used

$$
\begin{aligned}
2 \tilde{g}\left(\tilde{\nabla}_{X^{h}} Y^{h}, Z^{h}\right)= & X^{h} \tilde{g}\left(Y^{h}, Z^{h}\right)+Y^{h} \tilde{g}\left(Z^{h}, X^{h}\right) \\
& -Z^{h} \tilde{g}\left(X^{h}, Y^{h}\right)-\tilde{g}\left(X^{h},\left[Y^{h}, Z^{h}\right]\right) \\
& +\tilde{g}\left(Y^{h},\left[Z^{h}, X^{h}\right]\right)+\tilde{g}\left(Z^{h},\left[X^{h}, Y^{h}\right]\right)
\end{aligned}
$$

from Lemma 2.1 and the fact $\left[X^{h}, Y^{h}\right]=[X, Y]^{h}-(R(X, Y) u)^{v}$, we get

$$
\begin{aligned}
2 \tilde{g}\left(\tilde{\nabla}_{X^{h}} Y^{h}, Z^{h}\right)= & \left(X^{h} a\right)[g(Y, Z)+g(S(Y), u) g(S(Z), u)] \\
& +a\left[\begin{array}{c}
X^{h} g(Y, Z)+g(S(Z), u) X^{h} g(S(Y), u) \\
+g(S(Y), u) X^{h} g(S(Z), u)
\end{array}\right] \\
& +\left(Y^{h} a\right)[g(Z, X)+g(S(Z), u) g(S(X), u)] \\
& +a\left[\begin{array}{c}
Y^{h} g(Z, X)+g(S(X), u) Y^{h} g(S(Z), u) \\
+g(S(Z), u) Y^{h} g(S(X), u)
\end{array}\right] \\
& -\left(Z^{h} a\right)\left[\begin{array}{c}
g(X, Y)+g(S(X), u) g(S(Y), u)] \\
\\
\end{array} \quad-a\left[\begin{array}{c}
Z^{h} g(X, Y)+g(S(Y), u) Z^{h} g(S(X), u) \\
+g(S(X), u) Z^{h} g(S(Y), u)
\end{array}\right]\right. \\
& -\tilde{g}\left(X^{h},[Y, Z]^{h}\right)+\tilde{g}\left(Y^{h},[Z, X]^{h}\right)+\tilde{g}\left(Z^{h},[X, Y]^{h}\right) .
\end{aligned}
$$

From the fact that $X^{h} g(Y, u)=g\left(\nabla_{X} Y, u\right), X^{h} g\left(Y, e_{i}\right)=g\left(\nabla_{X} Y, e_{i}\right)$ and the shape operator gives $S_{p}$ : $T_{p} M \rightarrow T_{p} M$ a linear map for each $p \in M$, choosing a basis $\left\{e_{1}, e_{2}, \ldots, e_{n}\right\}$ of $T_{p} M$ that diagonalizes $S_{p}$ with $S_{p}\left(e_{i}\right)=\lambda_{i} e_{i}$, we get

$$
\begin{aligned}
X^{h} g(Y, S(u)) & =X^{h} g\left(Y, S\left(\sum g_{p}\left(u, e_{i}\right) e_{i}\right)\right) \\
& =\sum \lambda_{i} g_{p}\left(u, e_{i}\right) X^{h} g\left(Y, e_{i}\right) \\
& =\sum \lambda_{i} g_{p}\left(u, e_{i}\right) g\left(\nabla_{X} Y, e_{i}\right) \\
& =g\left(\nabla_{X} Y, S(u)\right)
\end{aligned}
$$

Considering these results and

$$
X^{h} \tilde{g}\left(Y^{v}, Z^{v}\right)=\tilde{g}\left(\left(\nabla_{X} Y\right)^{v}, Z^{v}\right)+\tilde{g}\left(Y^{v},\left(\nabla_{X} Z\right)^{v}\right)
$$

we get

$$
\begin{aligned}
& 2 \tilde{g}\left(\tilde{\nabla}_{X^{h}} Y^{h}, Z^{h}\right)=(X a)[g(Y, Z)+g(S(Y), u) g(S(Z), u)] \\
& +(Y a)[g(Z, X)+g(S(Z), u) g(S(X), u)] \\
& -(Z a)[g(X, Y)+g(S(X), u) g(S(Y), u)]
\end{aligned}
$$

and thus we have

$$
\begin{aligned}
2 \tilde{g}\left(\tilde{\nabla}_{X^{h}} Y^{h}, Z^{h}\right)= & \frac{1}{a}\left\{\begin{array}{c}
\tilde{g}\left((X(a) Y)^{h}, Z^{h}\right) \\
+\tilde{g}\left((Y(a) X)^{h}, Z^{h}\right) \\
-\tilde{g}\left(\left(g(X, Y) \circ d f^{*}\right)^{h}, Z^{h}\right)
\end{array}\right\} \\
& +2 \tilde{g}\left(\left(\nabla_{X} Y\right)^{h}, Z^{h}\right)
\end{aligned}
$$

where $\left(g(X, Y) \circ d f^{*}\right)$ is locally expressed as

$$
g(X, Y) \circ d f^{*}=g_{i j} f^{k}=g_{i j} \partial^{k} f
$$

In this way, we obtain

$$
\begin{aligned}
& 2 \tilde{g}\left(\tilde{\nabla}_{X^{h}} Y^{h}, Z^{h}\right) \\
= & 2 \tilde{g}\left(\left(\nabla_{X} Y\right)^{h}+\left(\frac{1}{2 a}\binom{X(a) Y+Y(a) X}{-g(X, Y) \circ d f^{*}}\right)^{h}, Z^{h}\right) \\
= & 2 \tilde{g}\left(\left(\nabla_{X} Y+A_{f}(X, Y)\right)^{h}, Z^{h}\right)
\end{aligned}
$$

and herefrom we get the horizontal part of vector field $\tilde{\nabla}_{X^{h}} Y^{h}$ as $\left(\nabla_{X} Y\right)^{h}+\left(A_{f}(X, Y)\right)^{h}$. Now we will search the vertical part of vector field $\tilde{\nabla}_{X^{h}} Y^{h}$. From the equation

$$
X^{h}\left(\stackrel{\tilde{g}}{g}\left(Y^{v}, Z^{v}\right)\right)=\tilde{g}\left(\left(\nabla_{X} Y\right)^{v}, Z^{v}\right)+\tilde{g}\left(Y^{v},\left(\nabla_{X} Z\right)^{v}\right)
$$

and Kozul's formula, we get

$$
\begin{aligned}
2 \tilde{g}\left(\tilde{\nabla}_{X^{h}} Y^{h}, Z^{v}\right)= & \stackrel{\sim}{g}\left(Z^{v},[X, Y]^{h}-(R(X, Y) u)^{v}\right) \\
& -Z^{v}\{a\{g(X, Y)+g(S(X), u) g(S(Y), u)\}\} \\
& -\tilde{g}\left(X^{h},\left(\nabla_{Y} Z\right)^{v}\right)-\tilde{g}\left(Y^{h},\left(\nabla_{X} Z\right)^{v}\right) \\
= & -\tilde{g}\left((R(X, Y) u)^{v}, Z^{v}\right)
\end{aligned}
$$

Hence, vertical part of vector field $\tilde{\nabla}_{X^{h}} Y^{h}$ is found as $-\frac{1}{2}(R(X, Y) u)^{v}$. Finally, combining expressions $\tilde{g}\left(\tilde{\nabla}_{X^{h}} Y^{h}, Z^{h}\right)$ and $\tilde{g}\left(\tilde{\nabla}_{X^{h}} Y^{h}, Z^{v}\right)$, we obtain (i) as follows

$$
\tilde{\nabla}_{X^{h}} Y^{h}=\left(\nabla_{X} Y\right)^{h}+\left(A_{f}(X, Y)\right)^{h}-\frac{1}{2}(R(X, Y) u)^{v}
$$

To prove (ii), we use the immersion $F: T M \rightarrow \mathbb{R}^{2 n+2}$ to write the Gauss equation $\tilde{D}_{X} Y=\tilde{\nabla}_{X} Y+\tilde{h}(X, Y)$ for $T M$ (eq. 3 in [4]), in the form

$$
\tilde{D}_{d F\left(X^{h}\right)} d F\left(Y^{v}\right)=d F\left(\tilde{\nabla}_{X^{h}} Y^{v}\right)+\tilde{h}\left(X^{h}, Y^{v}\right)
$$

We get from Lemma 3.2 in [4]

$$
\tilde{D}_{[d f(X)]^{h}+V}[d f(Y)]^{v}=d F\left(\tilde{\nabla}_{X^{h}} Y^{v}\right)+\tilde{h}\left(X^{h}, Y^{v}\right)
$$

Note that the metric on $\mathbb{R}^{2 n+2}$ being Sasaki metric, using the corresponding equation in [8], we obtain

$$
\left[d f\left(\nabla_{X} Y\right)+g(S(X), Y) N\right]^{v}=d F\left(\tilde{\nabla}_{X^{h}} Y^{v}\right)+\tilde{h}\left(X^{h}, Y^{v}\right)
$$

Since $N^{v}$ is tangent to $T M$, equating the tangential and normal components, we get

$$
\begin{align*}
d F\left(\tilde{\nabla}_{X^{h}} Y^{v}\right) & =d F\left(\left(\nabla_{X} Y\right)^{v}\right)+g(S(X), Y) N^{v}  \tag{2.1}\\
\tilde{h}\left(X^{h}, Y^{v}\right) & =0
\end{align*}
$$

that gives

$$
\tilde{\nabla}_{X^{h}} Y^{v}=\left(\nabla_{X} Y\right)^{v}+g(S(X), Y) N^{v}
$$

which proves (ii).
For (iii), we use the fact that $\left[Y^{h}, X^{v}\right]=\left(\nabla_{Y} X\right)^{v}$ (cf. [8], proposition 5.1) and (ii) to get

$$
\left(\nabla_{Y} X\right)^{v}+g(S(Y), X) N^{v}-\widetilde{\nabla}_{X^{v}} Y^{h}=\left(\nabla_{Y} X\right)^{v}
$$

so we obtain

$$
\tilde{\nabla}_{X^{v}} Y^{h}=g(S(Y), X) N^{v}
$$

which proves (iii).
To proof (iv), we use the Kozul's formula and Proposition 5.1 in [8] together with Lemma 2.1, so we obtain

$$
\begin{aligned}
2 \tilde{g}\left(\tilde{\nabla}_{X^{v}} Y^{v}, Z^{h}\right)= & -Z^{h} \tilde{g}\left(X^{v}, Y^{v}\right) \\
& -\tilde{g}\left(X^{v},\left[Y^{v}, Z^{h}\right]\right)+\tilde{g}\left(Y^{v},\left[Z^{h}, X^{v}\right]\right) \\
= & 0
\end{aligned}
$$

and

$$
\begin{aligned}
2 \tilde{g}\left(\tilde{\nabla}_{X^{v}} Y^{v}, Z^{v}\right) & =X^{v} g(Y, Z)+Y^{v} g(Z, X)-Z^{v} g(X, Y) \\
& =0
\end{aligned}
$$

which proves (iv).

Lemma 2.3 Let $X, Y \in \chi(M)$ be two vector fields on the hypersurface $M$ in $\mathbb{R}^{n+1}$. Then the second fundamental form $\tilde{h}$ of the submanifold $T M$ satisfies
(i) $\tilde{h}\left(X^{v}, Y^{v}\right)=0$,
(ii) $\tilde{h}\left(X^{h}, Y^{v}\right)=0$,
(iii) $\tilde{h}\left(X^{h}, Y^{h}\right)=g(S(X), Y) N^{h}$.

Proof The truth of equation (ii) is clear from Eq. 2.1. For (i), we have from equations $\tilde{D}_{X} Y=\tilde{\nabla}_{X} Y+\tilde{h}(X, Y)$, $\tilde{D}_{X} \tilde{N}=-\tilde{S}_{\tilde{N}}(X)+\nabla{ }_{X}^{\perp} \tilde{N}$ for the submanifold $T M$ that $\tilde{D}_{X^{v}} Y^{v}=\tilde{\nabla}_{X^{v}} Y^{v}+\tilde{h}\left(X^{v}, Y^{v}\right)$ which together with the fact that metric on the tangent bundle $T \mathbb{R}^{n+1}$ is a Sasaki metric, that is, $\tilde{D}_{X^{v}} Y^{v}=0$, we get $\tilde{h}\left(X^{v}, Y^{v}\right)=0$. For (iii), we have local orthonormal unit normal vector fields $\tilde{N}=\frac{1}{\sqrt{a}} N^{h}, N^{*}$ for the submanifold $T M$ as described in Lemmas 3.3 and 3.4 of [4], where $N^{*}$ is vertical on the tangent bundle $T \mathbb{R}^{n+1}$. Therefore, we get

$$
\begin{aligned}
\tilde{h}\left(X^{h}, Y^{h}\right) & =\tilde{g}\left(\tilde{h}\left(X^{h}, Y^{h}\right), \tilde{N}\right)+\tilde{g}\left(\tilde{h}\left(X^{h}, Y^{h}\right), N^{*}\right) \\
& =\tilde{g}\left(\tilde{S}_{\tilde{N}}\left(X^{h}\right), Y^{h}\right) \tilde{N}+\tilde{g}\left(\tilde{S}_{N^{*}}\left(X^{h}\right), Y^{h}\right) N^{*}
\end{aligned}
$$

Considering equations $\tilde{D}_{X} Y=\tilde{\nabla}_{X} Y+\tilde{h}(X, Y), \tilde{D}_{X} \tilde{N}^{\sim}=-\tilde{S}_{\tilde{N}}(X)+\nabla \stackrel{\perp}{X} \tilde{N}^{\text {together with Lemma } 3.2 \text { of [4] }}$
and Proposition 7.2 in [8] for Sasaki metric on $T \mathbb{R}^{n+1}$ we find

$$
\begin{align*}
\tilde{g}\left(\widetilde{S}_{\tilde{N}}\left(X^{h}\right), Y^{h}\right) \tilde{N}= & \frac{1}{\sqrt{a}} \tilde{g}\left(\tilde{D}_{X^{h}} \frac{1}{\sqrt{a}} N^{h}, Y^{h}\right) N^{h} \\
= & \frac{1}{\sqrt{a}} \tilde{g}\left(\left[D_{X}\left(\frac{1}{\sqrt{a}}\right)\right] N^{h}+\frac{1}{\sqrt{a}}\left(D_{X} N\right)^{h}, Y^{h}\right) N^{h} \\
= & \frac{1}{\sqrt{a}} D_{X}\left(\frac{1}{\sqrt{a}}\right) \tilde{g}\left(N^{h}, Y^{h}\right) N^{h} \\
& +\frac{1}{\sqrt{a}} \frac{1}{\sqrt{a}} \tilde{g}\left(\left(D_{X} N\right)^{h}, Y^{h}\right) N^{h} \\
= & \frac{1}{\sqrt{a}} D_{X}\left(\frac{1}{\sqrt{a}}\right) a \cdot g(N, Y) \\
& +\frac{1}{a} \cdot a \cdot g\left(D_{X} N, Y\right) N^{h} \\
= & g(S(X), Y) N^{h} . \tag{2.2}
\end{align*}
$$

Since $N^{v}$ is tangent to $T M$ and the unit normal vector field $N^{*}$ is vertical on the tangent bundle $T \mathbb{R}^{n+1}$ and from Lemma 3.2 of [4] and Proposition 7.2 in [8], it is taken

$$
\begin{aligned}
\tilde{g}\left(\tilde{h}\left(X^{h}, Y^{h}\right), N^{*}\right)= & \tilde{g}\left(\tilde{D}_{d F\left(X^{h}\right)} d F\left(Y^{h}\right), N^{*}\right) \\
= & \tilde{g}\left(\left(D_{d F(X)} d F(Y)\right)^{h}+(X g(S(Y), u)) N^{v}, N^{*}\right) \\
& +\tilde{g}\left(g(S(Y), u)\left(D_{d F(X)} N\right)^{v}, N^{*}\right) \\
= & -g(S(Y), u) \tilde{g}\left((S(X))^{v}, N^{*}\right)=0
\end{aligned}
$$

where we used $(S(X))^{v} \in \chi(T M)$ and that $N^{*}$ is normal vector field to the submanifold $T M$. Combining the above equation with equation 2.2 , we get

$$
\widetilde{h}\left(X^{h}, Y^{h}\right)=g(S(X), Y) N^{h}
$$

Lemma 2.4 [5] The covariant derivatives in the direction of $X^{h}$ and $X^{v}$ for $X \in \chi(M)$ of the vertical and horizontal lifts of the unit normal vector field $N$ for an orientable hypersurface $M$ in $\mathbb{R}^{n+1}$ are given by
(i) $\widetilde{D}_{X^{v}} N^{v}=0$,
(ii) $\widetilde{D}_{X^{v}} N^{h}=0$,
(iii) $\widetilde{D}_{X^{h}} N^{v}=-(S(X))^{v}$,
(iv) $\widetilde{D}_{X^{h}} N^{h}=-(S(X))^{h}$.

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Lemma 2.5 [5] For the tangent bundle $T M$ of an orientable hypersurface $M$ of the Euclidean space $\mathbb{R}^{n+1}$, we have
(i) $\tilde{h}\left(X^{v}, N^{v}\right)=0$,
(ii) $\tilde{\nabla}_{X^{v}} N^{v}=0$,
(iii) $\tilde{h}\left(X^{h}, N^{v}\right)=0$,
(iv) $\tilde{\nabla}_{X^{h}} N^{v}=-(S(X))^{v}, \quad X \in \chi(M)$.

## 3. Curvature tensors of tangent bundle of hypersurfaces in a euclidean Space

In this section, we obtain expressions for the curvature tensors with type $(1,3)$ and $(0,4)$ of the tangent bundle $T M$ of the hypersurface $M$ in a Euclidean space $\mathbb{R}^{n+1}$ as a submanifold with unit normal $N$, as well as study the properties of the vector field $N^{v}$. The tangent bundle $T M$ is now a submanifold of the Euclidean space $\mathbb{R}^{2 n+2}$. Then using the Gauss equation expressing curvature tensor field for submanifold $T M$ in the Euclidean space $\mathbb{R}^{2 n+2}$ together with Lemma 2.1, we have the following theorems:

Theorem 3.1 Let $(M, g)$ be a hypersurface in $\mathbb{R}^{n+1}$ and $(T M, \tilde{g})$ be its tangent bundle. Then $\widetilde{R}$ the Riemannian curvature tensor field with type $(1,3)$ of the tangent bundle equipped with the rescaled induced metric $\tilde{g}$ is as follows:
(i) $\tilde{R}\left(X^{h}, Y^{h}\right) Z^{h}=\left\{\begin{array}{c}R(X, Y) Z+\left(\nabla_{X} A_{f}\right)(Y, Z)-\left(\nabla_{Y} A_{f}\right)(X, Z) \\ +A_{f}\left(X, A_{f}(Y, Z)\right)-A_{f}\left(Y, A_{f}(X, Z)\right)\end{array}\right\}^{h}$

$$
+\left\{\begin{array}{c}
\frac{1}{2}\left(\nabla_{Y} R\right)(X, Z) u-\frac{1}{2}\left(\nabla_{X} R\right)(Y, Z) u \\
-\frac{1}{2} R\left(X, A_{f}(Y, Z)\right)+\frac{1}{2} R\left(Y, A_{f}(X, Z)\right) \\
-\frac{1}{2} g(S(X), R(Y, Z) u) N \\
+\frac{1}{2} g(S(Y), R(X, Z) u) N \\
+g(S(Z), R(X, Y) u) N
\end{array}\right\}^{v}
$$

(ii) $\tilde{R}\left(X^{h}, Y^{h}\right) Z^{v}=\left\{\begin{array}{c}R(X, Y) Z-g\left(\left(\nabla_{Y} S\right) X, Z\right) N \\ +g\left(\left(\nabla_{X} S\right) Y, Z\right) N \\ -g(S(Y), Z) S(X) \\ +g(S(X), Z) S(Y)\end{array}\right\}^{v}$,
(iii) $\tilde{R}\left(X^{h}, Y^{v}\right) Z^{h}=\left\{\begin{array}{c}g\left(\left(\nabla_{X} S\right) Y, Z\right) N \\ -g(S(Y), Z) S(X) \\ -g\left(S(Y), A_{f}(X, Z)\right) N\end{array}\right\}^{v}$,
(iv) $\widetilde{R}\left(X^{h}, Y^{v}\right) Z^{v}=0$,
(v) $\widetilde{R}\left(X^{v}, Y^{v}\right) Z^{h}=0$,
(vi) $\widetilde{R}\left(X^{v}, Y^{v}\right) Z^{v}=0, \quad X, Y, Z \in \chi(M)$.

Proof If we use formula of the curvature tensor together with Theorem 2.2, we get for (i)

$$
\left.\begin{array}{rl}
\widetilde{R}\left(X^{h}, Y^{h}\right) Z^{h}= & \tilde{\nabla}_{X^{h}}\left\{\left(\nabla_{Y} Z\right)^{h}+\left(A_{f}(Y, Z)\right)^{h}-\frac{1}{2}(R(Y, Z) u)^{v}\right\} \\
& -\tilde{\nabla}_{Y^{h}}\left\{\left(\nabla_{X} Z\right)^{h}+\left(A_{f}(X, Z)\right)^{h}-\frac{1}{2}(R(X, Z) u)^{v}\right\} \\
& -\tilde{\nabla}_{[X, Y]^{h}-(R(X, Y) u)^{v} Z^{h}} \\
= & \left\{\begin{array}{c}
R(X, Y) Z+\left(\nabla_{X} A_{f}\right)(Y, Z)-\left(\nabla_{Y} A_{f}\right)(X, Z) \\
+A_{f}\left(X, A_{f}(Y, Z)\right)-A_{f}\left(Y, A_{f}(X, Z)\right)
\end{array}\right\}^{h} \\
& +\left\{\begin{array}{c}
\frac{1}{2}\left(\nabla_{Y} R\right)(X, Z) u-\frac{1}{2}\left(\nabla_{X} R\right)(Y, Z) u \\
-\frac{1}{2} R\left(X, A_{f}(Y, Z)\right)+\frac{1}{2} R\left(Y, A_{f}(X, Z)\right) \\
-\frac{1}{2} g(S(X), R(Y, Z) u) N \\
+\frac{1}{2} g(S(Y), R(X, Z) u) N \\
+g(S(Z), R(X, Y) u) N
\end{array}\right\}
\end{array}\right\}
$$

For (ii), we get

$$
\begin{aligned}
& \tilde{R}\left(X^{h}, Y^{h}\right) Z^{v}= \tilde{\nabla}_{X^{h}}\left\{\left(\nabla_{Y} Z\right)^{v}+g(S(Y), Z) N^{v}\right\} \\
&-\tilde{\nabla}_{Y^{h}}\left\{\left(\nabla_{X} Z\right)^{v}+g(S(X), Z) N^{v}\right\} \\
&-\tilde{\nabla}_{[X, Y]^{h}-(R(X, Y) u)^{v} Z^{v}}= \\
&\left(\nabla_{X} \nabla_{Y} Z\right)^{v}+g\left(S(X), \nabla_{Y} Z\right) N^{v} \\
&+\left(\nabla_{X} g(S(Y), Z) N^{v}\right)^{v} \\
&+g\left(S(X), g(S(Y), Z) N^{v}\right) N^{v} \\
&-\left(\nabla_{Y} \nabla_{X} Z\right)^{v}-g\left(S(Y), \nabla_{X} Z\right) N^{v} \\
&-\left(\nabla_{Y} g(S(X), Z) N^{v}\right)^{v} \\
&-g\left(S(Y), g(S(X), Z) N^{v}\right) N^{v} \\
&-\left(\nabla_{[X, Y]} Z\right)^{v}-g(S([X, Y]), Z) N^{v}
\end{aligned}
$$

where if we consider that

$$
\begin{aligned}
\left(\nabla_{Y} g\right)(S(X), Z)= & \nabla_{Y} g(S(X), Z)-g\left(\nabla_{Y} S(X), Z\right)-g\left(S(X), \nabla_{Y} Z\right) \\
= & \nabla_{Y} g(S(X), Z)-g\left(\left(\nabla_{Y} S\right) X, Z\right) \\
& -g\left(S\left(\nabla_{Y} X\right), Z\right)-g\left(S(X), \nabla_{Y} Z\right)
\end{aligned}
$$

and from lemma 2.5, we obtain

$$
\tilde{R}\left(X^{h}, Y^{h}\right) Z^{v}=\left\{\begin{array}{c}
R(X, Y) Z-g\left(\left(\nabla_{Y} S\right) X, Z\right) N+g\left(\left(\nabla_{X} S\right) Y, Z\right) N \\
-g(S(Y), Z) S(X)+g(S(X), Z) S(Y)
\end{array}\right\}^{v} .
$$

For (iii), we can write

$$
\begin{aligned}
\tilde{R}\left(X^{h}, Y^{v}\right) Z^{h}= & \tilde{\nabla}_{X^{h}}\left\{g(S(Y), Z) N^{v}\right\}-\tilde{\nabla}_{\left(\nabla_{X} Y\right)^{v}} Z^{h} \\
& -\widetilde{\nabla}_{Y^{v}}\left\{\left(\nabla_{X} Z\right)^{h}+\left(A_{f}(X, Z)\right)^{h}-\frac{1}{2}(R(X, Z) u)^{v}\right\} \\
= & \left(\nabla_{X} g(S(Y), Z)\right) N^{v}+g(S(Y), Z) \tilde{\nabla}_{X^{h}} N^{v} \\
& -g\left(S(Y), \nabla_{X} Z\right) N^{v}-g\left(S(Y), A_{f}(X, Z)\right) N^{v} \\
& -g\left(S\left(\nabla_{X} Y\right), Z\right) N^{v}
\end{aligned}
$$

where since

$$
\nabla_{X} S(Y)=\left(\nabla_{X} S\right) Y+S\left(\nabla_{X} Y\right)
$$

and from Lemma 2.5 we get

$$
\begin{aligned}
\widetilde{R}\left(X^{h}, Y^{v}\right) Z^{h}= & \left(\nabla_{X} g(S(Y), Z)\right) N^{v}-g\left(S(Y), \nabla_{X} Z\right) N^{v} \\
& -g\left(\nabla_{X} S(Y), Z\right) N^{v}+g\left(\left(\nabla_{X} S\right) Y, Z\right) N^{v} \\
& -g(S(Y), Z)(S(X))^{v}-g\left(S(Y), A_{f}(X, Z)\right) N^{v}
\end{aligned}
$$

also because

$$
\nabla_{X} g(S(Y), Z)=\left(\nabla_{X} g\right)(S(Y), Z)+g\left(\nabla_{X} S(Y), Z\right)+g\left(S(Y), \nabla_{X} Z\right)
$$

and $\nabla_{X} g=0$, it is found that

$$
\nabla_{X} g(S(Y), Z)-g\left(\nabla_{X} S(Y), Z\right)-g\left(S(Y), \nabla_{X} Z\right)=0
$$

Thus, we find (iii) as

$$
\widetilde{R}\left(X^{h}, Y^{v}\right) Z^{h}=\left\{\begin{array}{c}
g\left(\left(\nabla_{X} S\right) Y, Z\right) N-g(S(Y), Z) S(X) \\
-g\left(S(Y), A_{f}(X, Z)\right) N
\end{array}\right\}^{v}
$$

For (iv), we can obtain easily that

$$
\begin{aligned}
\widetilde{R}\left(X^{h}, Y^{v}\right) Z^{v} & =-\widetilde{\nabla}_{Y^{v}}\left\{\left(\nabla_{X} Z\right)^{v}+g(S(X), Z) N^{v}\right\} \\
& =0
\end{aligned}
$$

For (v) and (vi), we can similarly see that

$$
\begin{aligned}
\widetilde{R}\left(X^{v}, Y^{v}\right) Z^{h} & =\widetilde{\nabla}_{X^{v}}\left\{g(S(Y), Z) N^{v}\right\}-\widetilde{\nabla}_{Y^{v}}\left\{g(S(X), Z) N^{v}\right\} \\
& =0
\end{aligned}
$$

and

$$
\widetilde{R}\left(X^{v}, Y^{v}\right) Z^{v}=0
$$

Theorem 3.2 Let $(M, g)$ be a hypersurface in $\mathbb{R}^{n+1}$ and $(T M, \tilde{g})$ be its tangent bundle. Then $\widetilde{R}$ the Riemannian curvature tensor field with type $(0,4)$ of the tangent bundle equipped with the rescaled induced metric $\tilde{g}$ is as follows:
(i) $\tilde{R}\left(X^{h}, Y^{h} ; Z^{h}, W^{h}\right)=a . g\left(\left\{\begin{array}{c}R(X, Y) Z+\left(\nabla_{X} A_{f}\right)(Y, Z) \\ -\left(\nabla_{Y} A_{f}\right)(X, Z) \\ +A_{f}\left(X, A_{f}(Y, Z)\right) \\ -A_{f}\left(Y, A_{f}(X, Z)\right)\end{array}\right\}, W\right)$

$$
+a . g(S(W), u) . g\left(\left\{\begin{array}{c}
R(X, Y) Z \\
+\left(\nabla_{X} A_{f}\right)(Y, Z) \\
-\left(\nabla_{Y} A_{f}\right)(X, Z) \\
+A_{f}\left(X, A_{f}(Y, Z)\right) \\
-A_{f}\left(Y, A_{f}(X, Z)\right)
\end{array}\right\}, S(u)\right),
$$

(ii) $\widetilde{R}\left(X^{h}, Y^{h} ; Z^{h}, W^{v}\right)=\frac{1}{2} g\left(\left\{\begin{array}{c}\left(\nabla_{Y} R\right)(X, Z) u \\ -\left(\nabla_{X} R\right)(Y, Z) u \\ -R\left(X, A_{f}(Y, Z)\right) \\ +R\left(Y, A_{f}(X, Z)\right)\end{array}\right\}, W\right)$,
(iii) $\widetilde{R}\left(X^{h}, Y^{h} ; Z^{v}, W^{h}\right)=0$,
(iv) $\tilde{R}\left(X^{h}, Y^{h} ; Z^{v}, W^{v}\right)=g\left(\left\{\begin{array}{c}R(X, Y) Z \\ -g(S(Y), Z) S(X) \\ +g(S(X), Z) S(Y)\end{array}\right\}, W\right)$,
(v) $\widetilde{R}\left(X^{v}, Y^{v} ; Z^{v}, W^{h}\right)=0$,
(vi) $\widetilde{R}\left(X^{v}, Y^{v} ; Z^{v}, W^{v}\right)=0$,
(vii) $\widetilde{R}\left(X^{h}, Y^{h} ; Z^{h}, N^{v}\right)=0$,
(viii) $\widetilde{R}\left(X^{h}, Y^{h} ; Z^{v}, N^{v}\right)=g\left(\left(\nabla_{X} S\right) Y-\left(\nabla_{Y} S\right) X, Z\right), \quad X, Y, Z, W \in \chi(M)$.

Proof Now, to prove the above equations, we will use the fact $\widetilde{R}\left(X^{h}, Y^{h} ; Z^{h}, W^{h}\right)=\tilde{g}\left(\tilde{R}\left(X^{h}, Y^{h}\right) Z^{h}, W^{h}\right)$
and together with Theorem 3.1. Thus, for (i), we get

$$
\left.\begin{array}{rl}
\tilde{R}\left(X^{h}, Y^{h}, Z^{h}, W^{h}\right)= & \stackrel{\sim}{g}\left(\left\{\begin{array}{c}
R(X, Y) Z+\left(\nabla_{X} A_{f}\right)(Y, Z) \\
-\left(\nabla_{Y} A_{f}\right)(X, Z) \\
+A_{f}\left(X, A_{f}(Y, Z)\right) \\
-A_{f}\left(Y, A_{f}(X, Z)\right)
\end{array}\right\}^{h}\right. \\
= & a \cdot g\left(\left\{\begin{array}{c}
R(X, Y) Z+\left(\nabla_{X} A_{f}\right)(Y, Z) \\
-\left(\nabla_{Y} A_{f}\right)(X, Z) \\
+A_{f}\left(X, A_{f}(Y, Z)\right) \\
-A_{f}\left(Y, A_{f}(X, Z)\right)
\end{array}\right\}, W\right) \\
& +a . g(S(W), u) . g\left(\begin{array}{c}
R(X, Y) Z \\
+\left(\nabla_{X} A_{f}\right)(Y, Z) \\
-\left(\nabla_{Y} A_{f}\right)(X, Z) \\
+A_{f}\left(X, A_{f}(Y, Z)\right) \\
-A_{f}\left(Y, A_{f}(X, Z)\right)
\end{array}\right), S(u)
\end{array}\right) .
$$

Similarly, for (ii), it is obtained that

$$
\begin{aligned}
\tilde{R}\left(X^{h}, Y^{h}, Z^{h}, W^{v}\right) & =\tilde{g}\left(\left\{\begin{array}{c}
\frac{1}{2}\left(\nabla_{Y} R\right)(X, Z) u \\
-\frac{1}{2}\left(\nabla_{X} R\right)(Y, Z) u \\
-\frac{1}{2} R\left(X, A_{f}(Y, Z)\right) \\
+\frac{1}{2} R\left(Y, A_{f}(X, Z)\right) \\
-\frac{1}{2} g(S(X), R(Y, Z) u) N \\
+\frac{1}{2} g(S(Y), R(X, Z) u) N \\
+g(S(Z), R(X, Y) u) N
\end{array}\right)^{v}, W^{v}\right) \\
& =\frac{1}{2} g\left(\left\{\begin{array}{c}
\left(\nabla_{Y} R\right)(X, Z) u-\left(\nabla_{X} R\right)(Y, Z) u \\
-R\left(X, A_{f}(Y, Z)\right)+R\left(Y, A_{f}(X, Z)\right)
\end{array}\right\}, W\right) .
\end{aligned}
$$

For (iii),(iv),(v), and (vi), it is easy to see respectively the following equations

$$
\begin{aligned}
\widetilde{R}\left(X^{h}, Y^{h} ; Z^{v}, W^{h}\right)= & \left.\tilde{g}\left(\left\{\begin{array}{c}
R(X, Y) Z-g\left(\left(\nabla_{Y} S\right) X, Z\right) N \\
+g\left(\left(\nabla_{X} S\right) Y, Z\right) N \\
-g(S(Y), Z) S(X) \\
+g(S(X), Z) S(Y)
\end{array}\right)^{v}{ }^{v}\right), W^{h}\right) \\
= & 0 \\
\widetilde{R}\left(X^{h}, Y^{h} ; Z^{v}, W^{v}\right)= & \tilde{g}\left(\left\{\begin{array}{c}
R(X, Y) Z \\
-g\left(\left(\nabla_{Y} S\right) X, Z\right) N \\
+g\left(\left(\nabla_{X} S\right) Y, Z\right) N \\
-g(S(Y), Z) S(X) \\
+g(S(X), Z) S(Y)
\end{array}\right\}, W^{v}\right. \\
= & g\left(\left\{\begin{array}{r}
R(X, Y) Z-g(S(Y), Z) S(X) \\
+g(S(X), Z) S(Y)
\end{array}\right\}, W\right), \\
& \widetilde{R}\left(X^{v}, Y^{v} ; Z^{v}, W^{h}\right)=0, \\
& \widetilde{R}\left(X^{v}, Y^{v} ; Z^{v}, W^{v}\right)=0 .
\end{aligned}
$$

Finally, for equations (vii) and (viii), we can obtain that

$$
\begin{aligned}
\widetilde{R}\left(X^{h}, Y^{h} ; Z^{h}, N^{v}\right) & =g\left(\left\{\begin{array}{c}
\frac{1}{2}\left(\nabla_{Y} R\right)(X, Z) u \\
-\frac{1}{2}\left(\nabla_{X} R\right)(Y, Z) u \\
-\frac{1}{2} R\left(X, A_{f}(Y, Z)\right) \\
+\frac{1}{2} R\left(Y, A_{f}(X, Z)\right) \\
-\frac{1}{2} g(S(X), R(Y, Z) u) N \\
+\frac{1}{2} g(S(Y), R(X, Z) u) N \\
+g(S(Z), R(X, Y) u) N
\end{array}\right\}, N\right) \\
= & 0
\end{aligned}
$$

and

$$
\begin{aligned}
\tilde{R}\left(X^{h}, Y^{h} ; Z^{v}, N^{v}\right) & =\tilde{g}\left(\left\{\begin{array}{c}
R(X, Y) Z \\
-g\left(\left(\nabla_{Y} S\right) X, Z\right) N \\
+g\left(\left(\nabla_{X} S\right) Y, Z\right) N \\
-g(S(Y), Z) S(X) \\
+g(S(X), Z) S(Y)
\end{array}\right\}^{v}, N^{v}\right) \\
& =g\left(\left(\nabla_{X} S\right) Y-\left(\nabla_{Y} S\right) X, Z\right)
\end{aligned}
$$

## 4. Orthonormal frame on the tangent bundle

In this section, considering the orthonormal basis $\left\{e_{1}, e_{2}, \ldots, e_{n}\right\}$ on the hypersurface $M$ at $p$, orthonormal frame on the tangent bundle $T M$ at $(p, u)$ will be introduced. Here, it is assumed that parameter curves on $M$ are principal curvature lines.

Lemma 4.1 Let $(M, g)$ be a hypersurface in $\mathbb{R}^{n+1}$ and $(T M, \tilde{g})$ be its tangent bundle as submanifold of $\mathbb{R}^{2 n+2}$ and $\left\{e_{1}, e_{2}, \ldots, e_{n}\right\}$ be an orthonormal basis for $M$ at $p$, such that $e_{1}=\frac{u}{|u|}$. Thus, for a given point $(p, u) \in T M$, with $u \neq 0$, the set $\left\{f_{1}, f_{2}, \ldots, f_{2 n}\right\}$ formed from horizontal and vertical lifts of $\left\{e_{1}, e_{2}, \ldots, e_{n}\right\}$ is an orthonormal basis for TM. Here, $f_{1}=\frac{1}{\sqrt{\lambda}} e_{1}^{h}$ with $\lambda=a\left(1+\kappa_{1}^{2} \cdot|u|^{2}\right), f_{i}=\frac{1}{\sqrt{a}} e_{i}^{h}$ for $i=2, \ldots, n$ and $f_{j+n}=e_{j}^{v}$ for $j=1, \ldots, n$.

Proof We have

$$
\begin{aligned}
\tilde{g}\left(f_{1}, f_{1}\right) & =\tilde{g}\left(\frac{1}{\sqrt{\lambda}} e_{1}^{h}, \frac{1}{\sqrt{\lambda}} e_{1}^{h}\right)=\frac{1}{\lambda} \tilde{g}\left(e_{1}^{h}, e_{1}^{h}\right) \\
& =\frac{1}{\lambda} a\left\{g\left(e_{1}, e_{1}\right)+g\left(S\left(e_{1}\right), u\right) g\left(S\left(e_{1}\right), u\right)\right\} \\
& =\frac{a}{\lambda}\left(1+\kappa_{1}^{2} \cdot|u|^{2}\right) \\
& =1
\end{aligned}
$$

$$
\begin{aligned}
\tilde{g}\left(f_{2}, f_{2}\right) & =\tilde{g}\left(\frac{1}{\sqrt{a}} e_{2}^{h}, \frac{1}{\sqrt{a}} e_{2}^{h}\right)=\frac{1}{a} \tilde{g}\left(e_{2}^{h}, e_{2}^{h}\right) \\
& =\frac{1}{a} a\left\{g\left(e_{2}, e_{2}\right)+g\left(S\left(e_{2}\right), u\right) g\left(S\left(e_{2}\right), u\right)\right\} \\
& =1
\end{aligned}
$$

so we get

$$
\begin{aligned}
& \tilde{g}\left(f_{n}, f_{n}\right)= \tilde{g}\left(\frac{1}{\sqrt{a}} e_{n}^{h}, \frac{1}{\sqrt{a}} e_{n}^{h}\right)=\frac{1}{a} \tilde{g}\left(e_{n}^{h}, e_{n}^{h}\right) \\
&= \frac{1}{a} a\left\{g\left(e_{n}, e_{n}\right)+g\left(S\left(e_{n}\right), u\right) g\left(S\left(e_{n}\right), u\right)\right\} \\
&= 1 \\
& \tilde{g}\left(f_{n+1}, f_{n+1}\right)= \tilde{g}\left(e_{1}^{v}, e_{1}^{v}\right)=1 \\
& \vdots \\
& \tilde{g}\left(f_{2 n}, f_{2 n}\right)=\tilde{g}\left(e_{n}^{v}, e_{n}^{v}\right)=1
\end{aligned}
$$

Moreover, we can easily show that the inner product of any pair of the set $\left\{f_{1}, f_{2}, \ldots, f_{2 n}\right\}$ is zero.

Theorem 4.2 Let $(M, g)$ be a hypersurface in $\mathbb{R}^{n+1}$ and $(T M, \tilde{g})$ be its tangent bundle as submanifold of $\mathbb{R}^{2 n+2}$. Then, the mean curvature denoted by $\tilde{H}$ of $T M$ is

$$
\widetilde{H}=\frac{1}{2 n}\left\{\frac{1}{\lambda} h\left(e_{1}, e_{1}\right)+\frac{1}{a}\left[h\left(e_{2}, e_{2}\right)+\cdots+h\left(e_{n}, e_{n}\right)\right]\right\} N^{h}
$$

Proof For the orthonormal basis $\left\{e_{1}, e_{2}, \ldots, e_{n}\right\}$ of the hypersurface $M$, we have the orthonormal basis of $T M$ at the point $(p, u)$ as

$$
\left\{f_{1}, f_{2}, \ldots, f_{2 n}\right\}=\left\{\frac{1}{\sqrt{\lambda}} e_{1}^{h}, \frac{1}{\sqrt{a}} e_{2}^{h}, \ldots, \frac{1}{\sqrt{a}} e_{n}^{h}, e_{1}^{v}, e_{2}^{v}, \ldots, e_{n}^{v}\right\}
$$

Hence, the mean curvature of $T M$ is calculated as

$$
\begin{aligned}
\tilde{H} & =\frac{1}{2 n}\left\{\sum_{i=1}^{2 n} \tilde{h}\left(f_{i}, f_{i}\right)\right\} \\
& =\frac{1}{2 n}\left\{\begin{array}{c}
\frac{1}{\lambda} \tilde{h}\left(e_{1}^{h}, e_{1}^{h}\right) \\
+\frac{1}{a} h\left(e_{2}^{h}, e_{2}^{h}\right)+\cdots+\frac{1}{a} h\left(e_{n}^{h}, e_{n}^{h}\right) \\
+h \\
\left.+e_{1}^{v}, e_{1}^{v}\right)+\cdots+h\left(e_{n}^{v}, e_{n}^{v}\right)
\end{array}\right\} \\
& =\frac{1}{2 n}\left\{\begin{array}{c}
\frac{1}{\lambda} g\left(S\left(e_{1}\right), e_{1}\right) \\
+\frac{1}{a} g\left(S\left(e_{2}\right), e_{2}\right)+\cdots+\frac{1}{a} g\left(S\left(e_{n}\right), e_{n}\right)
\end{array}\right\} N^{h} \\
& =\frac{1}{2 n}\left\{\begin{array}{c}
\frac{1}{\lambda} h\left(e_{1}, e_{1}\right) \\
+\frac{1}{a}\left[h\left(e_{2}, e_{2}\right)+\cdots+h\left(e_{n}, e_{n}\right)\right]
\end{array}\right\} N^{h} .
\end{aligned}
$$

Theorem 4.3 Let $(M, g)$ be a hypersurface in $\mathbb{R}^{n+1}$ and $(T M, \tilde{g})$ be its tangent bundle as submanifold of $\mathbb{R}^{2 n+2}$. Then, sectional curvatures denoted by $\tilde{K}$ of $T M$ are

$$
\begin{aligned}
\tilde{K}_{1 i} & =\frac{1}{a}\left\{\begin{array}{c}
R_{1 i i 1}+g\left(\nabla_{1}\left(A_{f}\right)_{i i}-\nabla_{i}\left(A_{f}\right)_{1 i}, e_{1}\right) \\
+g\left(A_{f}\left(e_{1},\left(A_{f}\right)_{i i}\right)-A_{f}\left(e_{i},\left(A_{f}\right)_{1 i}\right), e_{1}\right)
\end{array}\right\} \\
(i & =2, \cdots, n) \\
\tilde{K}_{i j} & =\frac{1}{a}\left\{\begin{array}{c}
R_{i j j i}+g\left(\nabla_{i}\left(A_{f}\right)_{j j}-\nabla_{j}\left(A_{f}\right)_{i j}, e_{i}\right) \\
+g\left(A_{f}\left(e_{i},\left(A_{f}\right)_{j j}\right)-A_{f}\left(e_{j},\left(A_{f}\right)_{i j}\right), e_{i}\right)
\end{array}\right\} \\
(i, j & =2, \cdots, n, \quad i \neq j, \quad i<j) \\
\tilde{K}_{1 k} & =0, \quad(k=n+1, \cdots, 2 n) \\
\tilde{K}_{j k} & =0, \quad(j=2, \cdots, n, \quad k=n+1, \cdots, 2 n) \\
\tilde{K}_{k l} & =0, \quad(k, l=n+1, \cdots, 2 n, \quad k \neq l, \quad k<l)
\end{aligned}
$$

Proof Using orthonormal frame $\left\{f_{1}, f_{2}, \ldots, f_{2 n}\right\}$ of $T M$ at the point $(p, u)$, the sectional curvature $\widetilde{K}$ can be given by the following formulas

$$
\begin{aligned}
\tilde{K}_{1 i}= & \tilde{K}\left(f_{1}, f_{i}\right)=\widetilde{R}\left(f_{1}, f_{i}, f_{i}, f_{1}\right) \\
& (i=2, \cdots, n) \\
\tilde{K}_{i j}= & \widetilde{K}\left(f_{i}, f_{j}\right)=\widetilde{R}\left(f_{i}, f_{j}, f_{j}, f_{i}\right) \\
& (i, j=2, \cdots, n, \quad i \neq j, \quad i<j) \\
\tilde{K}_{1 k}= & \tilde{K}\left(f_{1}, f_{k}\right)=\widetilde{R}\left(f_{1}, f_{k}, f_{k}, f_{1}\right) \\
& (k=n+1, \cdots, 2 n) \\
\tilde{K}_{j k}= & \tilde{K}\left(f_{j}, f_{k}\right)=\widetilde{R}\left(f_{j}, f_{k}, f_{k}, f_{j}\right) \\
& (j=2, \cdots, n, \quad k=n+1, \cdots, 2 n) \\
& \tilde{K}\left(f_{k}, f_{l}\right)=\widetilde{R}\left(f_{k}, f_{l}, f_{l}, f_{k}\right), \\
\tilde{K}_{k l}= & (k, l=n+1, \cdots, 2 n, \quad k \neq l, \quad k<l) .
\end{aligned}
$$

Firstly, from $\left\{f_{1}, f_{2}, \ldots, f_{2 n}\right\}=\left\{\frac{1}{\sqrt{\lambda}} e_{1}^{h}, \frac{1}{\sqrt{a}} e_{2}^{h}, \ldots, \frac{1}{\sqrt{a}} e_{n}^{h}, e_{1}^{v}, e_{2}^{v}, \ldots, e_{n}^{v}\right\}$ the orthonormal basis of $T M$ at the point
( $p, u$ ) and Theorem 3.2, we get

$$
\left.\begin{array}{rl}
\tilde{K}_{1 i}= & \tilde{K}\left(f_{1}, f_{i}\right)=\widetilde{R}\left(f_{1}, f_{i}, f_{i}, f_{1}\right) \\
= & \widetilde{R}\left(\frac{1}{\sqrt{\lambda}} e_{1}^{h}, \frac{1}{\sqrt{a}} e_{i}^{h}, \frac{1}{\sqrt{a}} e_{i}^{h}, \frac{1}{\sqrt{\lambda}} e_{1}^{h}\right) \\
= & \frac{1}{a \lambda} \widetilde{R}\left(e_{1}^{h}, e_{i}^{h}, e_{i}^{h} e_{1}^{h}\right) \\
= & \frac{1}{\lambda} g\left(\left\{\begin{array}{c}
R\left(e_{1}, e_{i}\right) e_{i}+\left(\nabla_{e_{1}} A_{f}\right)\left(e_{i}, e_{i}\right) \\
-\left(\nabla_{e_{i}} A_{f}\right)\left(e_{1}, e_{i}\right) \\
+A_{f}\left(e_{1}, A_{f}\left(e_{i}, e_{i}\right)\right) \\
-A_{f}\left(e_{i}, A_{f}\left(e_{1}, e_{i}\right)\right)
\end{array}\right\}, e_{1}\right) \\
& +\frac{1}{\lambda} g\left(S\left(e_{1}\right), u\right) \cdot g\left(\begin{array}{c}
R\left(e_{1}, e_{i}\right) e_{i} \\
+\left(\nabla_{e_{1}} A_{f}\right)\left(e_{i}, e_{i}\right) \\
-\left(\nabla_{e_{i}} A_{f}\right)\left(e_{1}, e_{i}\right) \\
+A_{f}\left(e_{1}, A_{f}\left(e_{i}, e_{i}\right)\right) \\
-A_{f}\left(e_{i}, A_{f}\left(e_{1}, e_{i}\right)\right)
\end{array}\right\}, S(u)
\end{array}\right)
$$

Herefrom, if we take expression with coordinates for brevity, we have

$$
\begin{aligned}
\tilde{K}_{1 i}= & \frac{1}{\lambda}\left\{\begin{array}{c}
R_{1 i i 1}+g\left(\nabla_{1}\left(A_{f}\right)_{i i}-\nabla_{i}\left(A_{f}\right)_{1 i}, e_{1}\right) \\
+g\left(A_{f}\left(e_{1},\left(A_{f}\right)_{i i}\right)-A_{f}\left(e_{i},\left(A_{f}\right)_{1 i}\right), e_{1}\right)
\end{array}\right\} \\
& +\frac{\kappa_{1} \cdot|u|}{\lambda} \cdot g\left(\left\{\begin{array}{c}
R\left(e_{1}, e_{i}\right) e_{i} \\
+\nabla_{1}\left(A_{f}\right)_{i i} \\
-\nabla_{i}\left(A_{f}\right)_{1 i} \\
+A_{f}\left(e_{1},\left(A_{f}\right)_{i i}\right) \\
-A_{f}\left(e_{i},\left(A_{f}\right)_{1 i}\right)
\end{array}\right\}, S(u)\right)
\end{aligned}
$$

If we consider $S(u)=S\left(e_{1} \cdot|u|\right)=|u| S\left(e_{1}\right)=|u| \kappa_{1} e_{1}$ and $\lambda=a\left(1+\kappa_{1}^{2} \cdot|u|^{2}\right)$, we get

$$
\tilde{K}_{1 i}=\frac{1}{a}\left\{\begin{array}{c}
R_{1 i i 1}+g\left(\nabla_{1}\left(A_{f}\right)_{i i}-\nabla_{i}\left(A_{f}\right)_{1 i}, e_{1}\right) \\
+g\left(A_{f}\left(e_{1},\left(A_{f}\right)_{i i}\right)-A_{f}\left(e_{i},\left(A_{f}\right)_{1 i}\right), e_{1}\right)
\end{array}\right\} .
$$

Similarly, it is calculated as

$$
\begin{aligned}
\tilde{K}_{i j} & =\tilde{K}\left(f_{i}, f_{j}\right)=\widetilde{R}\left(f_{i}, f_{j}, f_{j}, f_{i}\right) \\
& =\widetilde{R}\left(\frac{1}{\sqrt{a}} e_{i}^{h}, \frac{1}{\sqrt{a}} e_{j}^{h}, \frac{1}{\sqrt{a}} e_{j}^{h}, \frac{1}{\sqrt{a}} e_{i}^{h}\right) \\
& =\frac{1}{a^{2}} \widetilde{R}\left(e_{i}^{h}, e_{j}^{h}, e_{j}^{h}, e_{i}^{h}\right) \\
& =\frac{1}{a}\left\{\begin{array}{c}
R_{i j j i}+g\left(\nabla_{i}\left(A_{f}\right)_{j j}-\nabla_{j}\left(A_{f}\right)_{i j}, e_{i}\right) \\
+g\binom{A_{f}\left(e_{i},\left(A_{f}\right)_{j j}\right)}{-A_{f}\left(e_{j},\left(A_{f}\right)_{i j}\right), e_{i}}
\end{array}\right\} .
\end{aligned}
$$

And other sectional curvatures are obtained as zero.

Conclusion 4.4 In this article, rescaled induced metric has been defined on $T M$ which is considered a submanifold of $\mathbb{R}^{2 n+2}$ and by means of this metric, orthonormal frame on $T M$ at the point $P=(p, u)$ has been established. In this way, many differential geometric results in the theory of submanifolds can be obtained other than the results given in this paper.

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